

## easY<mark>gen-300</mark> Genset Control



**Operation Manual** Software Version starting from 2.0008



Manual 37218D

### WARNING

Read this entire manual and all other publications pertaining to the work to be performed before installing, operating, or servicing this equipment. Practice all plant and safety instructions and precautions. Failure to follow instructions can cause personal injury and/or property damage.

The engine, turbine, or other type of prime mover should be equipped with an overspeed (overtemperature, or overpressure, where applicable) shutdown device(s), that operates totally independently of the prime mover control device(s) to protect against runaway or damage to the engine, turbine, or other type of prime mover with possible personal injury or loss of life should the mechanical-hydraulic governor(s) or electric control(s), the actuator(s), fuel control(s), the driving mechanism(s), the linkage(s), or the controlled device(s) fail.

Any unauthorized modifications to or use of this equipment outside its specified mechanical, electrical, or other operating limits may cause personal injury and/or property damage, including damage to the equipment. Any such unauthorized modifications: (i) constitute "misuse" and/or "negligence" within the meaning of the product warranty thereby excluding warranty coverage for any resulting damage, and (ii) invalidate product certifications or listings.

## CAUTION

To prevent damage to a control system that uses an alternator or battery-charging device, make sure the charging device is turned off before disconnecting the battery from the system.

Electronic controls contain static-sensitive parts. Observe the following precautions to prevent damage to these parts.

- Discharge body static before handling the control (with power to the control turned off, contact a
  grounded surface and maintain contact while handling the control).
- Avoid all plastic, vinyl, and Styrofoam (except antistatic versions) around printed circuit boards.
- Do not touch the components or conductors on a printed circuit board with your hands or with conductive devices.



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#### Important definitions



#### WARNING

Indicates a potentially hazardous situation that, if not avoided, could result in death or serious injury.

#### CAUTION

Indicates a potentially hazardous situation that, if not avoided, could result in damage to equipment.



#### NOTE

Provides other helpful information that does not fall under the warning or caution categories.

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## **Revision History**

Rev.	Date	Editor	Change	
NEW	04-10-15	TP	ease	
А	05-12-14	TP	nor corrections; MCB closing limit description added; update to reflect version V2.0006	
В	06-03-23	TP	finor corrections; wire size conversion chart added; update to reflect version V2.0007 (refer to Update In-	
			formation on page 9 for more info)	
С	07-09-19	TP	Minor corrections; update to reflect version V2.0008 (refer to Update Information on page 9 for more info)	
D	08-12-01	TE	Minor corrections; time of motor stop added	

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## Chapter 1. General Information

## **Related Documents**

#### 

Туре		English	German
easYgen-300 Series			
easYgen-300 – Manual	this manual ⇔	37218	-
Additional Manuals			
LeoPC1 – User Manual		37146	GR37146
PC program for configuration, parameter visualization, ren	note control, data logging, langu	age upload, alarm a	and user management,
and event recorder management. This manual describes th	e use of LeoPC1 software.	•	-
LeoPC1 – Engineering Manual		37164	GR37164
PC program for configuration, parameter visualization, ren	note control, data logging, langu	age upload, alarm a	and user management,
and event recorder management. This manual describes th	e programming of LeoPC1 softw	/are.	

Table 1-1: Manual - overview

## **Update Information**

#### 

The software version may be checked using the PC configuration tool LeoPC1 (refer to the LeoPC1 manual for more information). The software version is indicated in the Versions section of the Parameterize screen under the last parameter "Program version".

Revision C of this manual 37218 reflects the update from Software Version 2.0007 to 2.0008. This includes the following new functionality:

• Self-acknowledgement of mains phase rotation monitoring may now be enabled (refer to Monitoring: Mains on page 80)

Revision B of this manual 37218 reflects the update from Software Version 2.0006 to 2.0007. This includes the following new functionality:

- Password protected front panel configuration
- Front panel configurable maintenance counter

The parameters HMI Password (refer to Password on page 75) and Commissioning code level (refer to Codes on page 96) are new and not contained in Software Version 2.0006.



Figure 1-2: Functional overview

The easYgen-300 Series generator set controller provides the following functions:

- Genset control
- Engine and generator protection
- Engine data measurement -
  - including oil pressure and temperature, coolant temperature, battery voltage, speed, service hours, etc.
- Generator voltage measurement
- Engine crank sequencing
- Alarm display with circuit breaker trip and engine shutdown
- AMF (automatic mains failure) standby genset control with automatic engine start on a mains failure detection and open transition breaker control
- CAN bus communications to engine controllers
- Password protected configuration

Type designation is as follows:

easYgen	sYgen -xxx		
		Option	
		[] no option	
		[X] = option X (MPU and CAN capable)	
		Model	
		[300] = Series	
		[320] = Model '320' (1 circuit breaker [GCB])	
		[350] = Model '350' (2 circuit breakers [GCB&MCB])	
		Туре	

#### Examples:

EASYGEN-320 (standard easYgen-320 with generator circuit breaker) EASYGEN-350X (standard easYgen-350 with generator and mains circuit breaker, MPU input & CAN interface)

**Intended Use** The control unit must only be operated as described in this manual. The prerequisite for a proper and safe operation of the product is correct transportation, storage, and installation as well as careful operation and maintenance.



#### NOTE

This manual has been developed for a unit fitted with all available options. Inputs/outputs, functions, configuration screens and other details described, which do not exist on your unit may be ignored.

The present manual has been prepared to enable the installation and commissioning of the unit. Because of the large variety of parameter settings, it is not possible to cover every possible combination. The manual is therefore only a guide. In case of incorrect entries or a total loss of functions, the default settings can be taken from the enclosed list of parameters.

## Chapter 2. easYgen Series 300 Overview

The easYgen Series 300 consists of four models which are intended for different applications and requirements. This manual covers all available versions of the easYgen Series 300. Please take information about the differences between the units from this section.

Functionality \ easYgen	[320]	[320X]	[350]	[350X]
Generator voltage measurement	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$
Mains voltage measurement			$\checkmark$	$\checkmark$
GCB	✓	$\checkmark$	$\checkmark$	$\checkmark$
MCB			$\checkmark$	✓
MPU (pickup) input		$\checkmark$		✓
CAN bus (J 1939 protocol)		$\checkmark$		$\checkmark$
Password protection	✓	$\checkmark$	$\checkmark$	$\checkmark$

Table 2-1: easYgen series 300 product features



## NOTE

Some parameters of the easYgen-300 series can only be configured using the Direct Configuration Cable DPC (P/N 5417-557) and a notebook/PC with the software LeoPC1. These parameters are indicated with an L in the parameter description under Parameters starting from page 70 and can not be configured at the unit directly.

The configuration with LeoPC1 via the DPC is described under Configuration Using the PC on page 67. The DPC is not part of the easYgen-300 shipment and sold separately (P/N 5417-557).

### **IMPORTANT NOTE ABOUT COUNTERS**

The counters for

- Operation hours
- Maintenance Interval
- Number of starts

can be recalibrated with LeoPC1 and the configuration files belonging to the unit. If 3<sup>rd</sup> party users are not allowed to change these values, you can easily remove the parameters which enable changing the counters by editing the LeoPC1 configuration files as described under Editing the Configuration File on page 68.

The counter for

Maintenance Interval

can also be recalibrated using the front panel. You may prevent the user from recalibrating this parameter by setting a HMI password as described under Codes on page 96.

## Chapter 3. Electrostatic Discharge Awareness

All electronic equipment is static-sensitive, some components more than others. To protect these components from static damage, you must take special precautions to minimize or eliminate electrostatic discharges.

Follow these precautions when working with or near the control.

- 1. Before performing maintenance on the electronic control, discharge the static electricity on your body to ground by touching and holding a grounded metal object (pipes, cabinets, equipment, etc.).
- 2. Avoid the build-up of static electricity on your body by not wearing clothing made of synthetic materials. Wear cotton or cotton-blend materials as much as possible because these do not store static electric charges as much as synthetics.
- 3. Keep plastic, vinyl, and Styrofoam materials (such as plastic or Styrofoam cups, cup holders, cigarette packages, cellophane wrappers, vinyl books or folders, plastic bottles, and plastic ash trays) away from the control, the modules, and the work area as much as possible.
- 4. **Opening the control cover may void the unit warranty.**

Do not remove the Printed Circuit Board (PCB) from the control cabinet unless absolutely necessary. If you must remove the PCB from the control cabinet, follow these precautions:

- Ensure that the device is completely de-energized (all connectors must be disconnected).
- Do not touch any part of the PCB except the edges.
- Do not touch the electrical conductors, connectors, or components with conductive devices with your hands.
- When replacing a PCB, keep the new PCB in the protective antistatic bag it comes in until you are ready to install it. Immediately after removing the old PCB from the control cabinet, place it in the protective antistatic bag.



### CAUTION

To prevent damage to electronic components caused by improper handling, read and observe the precautions in Woodward manual 82715, *Guide for Handling and Protection of Electronic Controls, Printed Circuit Boards, and Modules.* 



#### NOTE

The unit is capable to withstand an electrostatic powder coating process with a voltage of up to 85 kV and a current of up to 40  $\mu$ A.

## Chapter 4. Housing

## **Dimensions / Panel Cut-Out**



Figure 4-1: Housing - panel cut-out

Description		Dimension	Tolerance
Height	Total	158 mm	
	Panel cut-out	138 mm	+ 1.0 mm
	Housing dimension	136 mm	
Width	Total	158 mm	
	Panel cut-out	138 mm	+ 1.0 mm
	Housing dimension	136 mm	
Depth	Total	40 mm	

Table 4-1: Housing - panel cut-out

## Installation

#### 

For installation into a door panel, proceed as follows:

#### 1. Panel cut-out

Cut out the panel according to the dimensions in Figure 4-1.

#### 2. **Remove terminals**

Loosen the wire connection terminal screws on the back of the unit and remove the wire connection terminal strips if required (1).

#### 3. Loosen clamping screws

Loosen the four clamping screws (1) until they are almost flush with the clamp inserts and tilt the clamp inserts down by  $45^{\circ}$  (2) to remove them from the housing. Do not completely remove the screws from the clamp inserts.

#### 4. **Insert unit into cut-out**

Insert the unit into the panel cut-out. Verify that the unit fits correctly in the cut-out. If the panel cut-out is not big enough, enlarge it accordingly. Ensure that the gasket is placed properly if used. Ensure that the paper strip is not pinched between gasket and panel to maintain isolation.

#### 5. Attach clamp inserts

Re-install the clamp inserts by tilting the insert to a  $45^{\circ}$  angle (1). Insert the nose of the insert into the slot on the side of the housing. Raise the clamp insert so that it is parallel to the control panel (2).

#### 6. **Tighten clamping screws**

Tighten the clamping screws (1) until the control unit is secured to the control panel (2). Over tightening of these screws may result in the clamp inserts or the housing breaking. Do not exceed the recommended tightening torque of 0.1 Nm.

#### 7. **Reattach terminals**

Reattach the wire connection terminal strips (1) and secure them with the side screws.













Note: If the gasket is damaged, it needs to be replaced. Use only the original gasket kit (P/N 3050-1057) for replacement.

Chapter 5. Wiring Diagrams



Figure 5-1: Wiring diagram - easYgen-320



Figure 5-2: Wiring diagram - easYgen320X



Figure 5-3: Wiring diagram - easYgen350



Figure 5-4: Wiring diagram - easYgen350X

## Chapter 6. Connections



### NOTE

The wire sizes in the following chapter are indicated in square millimeters. Please refer to Conversion Chart: Wire Size on page 105 to convert the sizes to AWG.

## **Terminal Arrangement**

20 19	2 1
upper terminal strip	
lower terminal strip	only [320X], [350X]
2122	3536 3940

Figure 6-1: easYgen-300 back view - terminal arrangement

## **Power supply**

#### 

• 6.5 to 32.0 Vdc				
	∽ → <b>••</b> ↓	6.5 to 32.0 Vdc 0 Vdc	Power supply	
			Figure 6-2: Power sup	ply

Terminal	Description	A <sub>max</sub>
1	0 Vdc reference potential	2.5 mm <sup>2</sup>
2	6.5 to 32.0 Vdc	2.5 mm <sup>2</sup>

Table 6-1: Power supply - terminal assignment

For a proper operation of the device, a minimum initial voltage of 10.5 Vdc is necessary when switching on the easYgen. After this, a continuous operating voltage between 6.5 and 32 Vdc is possible to operate the easYgen safely. The control unit is capable of handling voltage drops to 0 V for a maximum of 10 ms.



## CAUTION

Ensure that the engine will be shut down by an external device in case the power supply of the easYgen-300 control unit fails. Failure to do so may result in damages to the equipment.

## **Charging Alternator**

#### 



Figure 6-3: Charging alternator input/output

Terminal	Description	A <sub>max</sub>
2	Battery B+	2.5 mm <sup>2</sup>
3	Charging alternator input D+ 24 Vdc	2.5 mm <sup>2</sup>
4	Charging alternator input D+ 12 Vdc	2.5 mm <sup>2</sup>

Table 6-2: Charging alternator input/output - terminal assignment



## CAUTION

Terminal 3 must be used for charging voltages exceeding 16 Volts. Connecting the terminals 3 and 4 incorrectly, may result in damage to the unit.



### NOTE

The charging alternator D+ acts as an output for pre-exciting the charging alternator during engine start-up only. During regular operation, it acts as an input for monitoring the charging voltage. Refer to Firing Speed Detection on page 62 for more information.

## **Voltage Measuring**

#### 

The easYgen-300 series allows the use of different voltage measuring methods for generator and mains voltage depending on the model. These are described in the following text.

Measuring method	Description
3Ph 4W	Measurement is performed phase-neutral (WYE connected system). Phase voltages and neutral conductor must be connected for proper calculation. The measurement, display and protection are adjusted according to the rules for WYE or delta connected systems. Monitoring refers to the following voltages: • V <sub>L12</sub> , V <sub>L23</sub> , and V <sub>L31</sub> , or • V <sub>L1N</sub> , V <sub>L2N</sub> , and V <sub>L3N</sub> .
3Ph 3W	Measurement is performed phase-phase (delta connected system). Phase voltages must be connected for proper calculation. The measurement, display and protection are ad- justed according to the rules for delta connected systems. Monitoring refers to the fol- lowing voltages: • V <sub>L12</sub> , V <sub>L23</sub> , V <sub>L31</sub> .
1Ph 2W	Measurement is performed for single-phase systems. The measurement, display and protection are adjusted according to the rules for single-phase systems. Monitoring refers to the following voltages: • $V_{LIN}$ .
1Ph 3W	Measurement is performed for single-phase systems. The measurement, display and pro- tection are adjusted according to the rules for single-phase systems. Monitoring refers to the following voltages: • V <sub>L1N</sub> , V <sub>L3N</sub> .

Table 6-3: Voltage measuring principles

The above described voltage measuring methods are shown with appropriate wiring examples for the different models for generator and mains voltage measuring in Figure 6-4 to Figure 6-12.

## NOTE

Please note that not all measuring methods can be performed with all models of the easYgen-300 series. The methods of measurement are indicated in the wiring diagrams for the respective models.



1

#### NOTE

LeoPC1 and a DPC cable (Revision B, P/N 5417-557) are required to configure the voltage measuring methods for all versions of the easYgen-300 series.

#### **Voltage Measuring: Generator**

#### Voltage Measuring: Generator 3Ph 4W, [320X], [350X]



Figure 6-4: Voltage measuring - generator 3Ph 4W

#### Voltage Measuring: Generator 3Ph 3W, [320X], [350X]



Figure 6-5: Voltage measuring - generator 3Ph 3W

#### Voltage Measuring: Generator 1Ph 3W, [320X], [350X]



Figure 6-6: Voltage measuring - generator 1Ph 3W

#### Voltage Measuring: Generator 1Ph 2W, [320], [320X], [350], [350X]

#### Phase-Neutral Voltage Measuring



Figure 6-7: Voltage measuring - generator 1Ph 2W, phase-neutral

#### Phase-Phase Voltage Measuring

It is also possible to perform a phase-phase voltage measuring. The units is intended for a phase-neutral measuring as described above, but may also be used for phase-phase voltage measuring. In this case, phase L2 must be connected to the N terminal of the easYgen and the Generator rated voltage (Parameter 11) must be configured to the phase-phase voltage.



Figure 6-8: Voltage measuring - generator 1Ph 2W, phase-phase

Terminal	Description	A <sub>max</sub>
29	Generator voltage - phase L3 480 Vac	2.5 mm <sup>2</sup>
31	Generator voltage - phase L2 480 Vac	2.5 mm <sup>2</sup>
33	Generator voltage - phase L1 480 Vac	2.5 mm <sup>2</sup>
35	Generator voltage - phase N 480 Vac	2.5 mm <sup>2</sup>

Table 6-4: Voltage measuring - terminal assignment - generator voltage

## NOTE

If you select to perform a phase-phase voltage measuring, the display is still indicating a phase-neutral voltage since the voltage is measured between terminal 33 (L1) and 35 (N).

However, if the Generator rated voltage (Parameter 11) is configured correctly, the displayed value is the correct phase-phase voltage value.

### Voltage Measuring: Mains, [350], [350X]

Voltage Measuring: Mains 3Ph 4W



Figure 6-9: Voltage measuring - mains 3Ph 4W

#### Voltage Measuring: Mains 3Ph 3W, [350X]



Figure 6-10: Voltage measuring - mains 3Ph 3W

#### Voltage Measuring: Mains 1Ph 3W, [350X]



Figure 6-11: Voltage measuring - mains 1Ph 3W

#### Voltage Measuring: Mains 1Ph 2W, [350X]



Figure 6-12: Voltage measuring - mains 1Ph 2W

Terminal	Description	A <sub>max</sub>
21	Mains voltage - phase L3 480 Vac	2.5 mm <sup>2</sup>
23	Mains voltage - phase L2 480 Vac	2.5 mm <sup>2</sup>
25	Mains voltage - phase L1 480 Vac	2.5 mm <sup>2</sup>
27	Mains voltage - phase N 480 Vac	2.5 mm <sup>2</sup>

Table 6-5: Voltage measuring - terminal assignment - mains voltage

## MPU (pickup) [320X], [350X]



Figure 6-13: MPU - principle overview



Figure 6-14: MPU input

Terminal	Description		A <sub>max</sub>
37	MDU	inductive/switching	2.5 mm <sup>2</sup>
38	MPO input	GND	2.5 mm <sup>2</sup>

Table 6-6: MPU - terminal assignment



## NOTE

The shield of the MPU connection cable must be connected on one side to a ground terminal of the cabinet near the easYgen. The shield must not be connected at the MPU side of the cable.



### NOTE

The input frequency of the MPU must be limited to 14 kHz.



Figure 6-15: Minimum required input voltage depending on frequency

## **Discrete Inputs**

#### 

#### **Discrete Inputs: Bipolar Signals**

The discrete inputs are galvanically isolated allowing for a bipolar connection. The discrete inputs are able to handle positive or negative signals.

## i

NOTE

All discrete inputs must use the same polarity, either positive or negative signals, due to the common ground.

#### **Discrete Inputs: Positive Signal**



Figure 6-16: Discrete inputs - alarm/control input - positive signal

Tern	ninal	Description			A <sub>max</sub>
Term.	Com.			Туре ↓	
16		Discrete input [D1]	Low oil pressure	fixed	2.5 mm <sup>2</sup>
17		Discrete input [D2]	High coolant temperature	fixed	2.5 mm <sup>2</sup>
18	15	Discrete input [D3]	Remote start	fixed	2.5 mm <sup>2</sup>
19		Discrete input [D4]	Reply MCB or alarm input	SW	2.5 mm <sup>2</sup>
20		Discrete input [D5]	Reply GCB or alarm input	SW	2.5 mm <sup>2</sup>

SW..alarm input switchable via software, if parameter "Ignore CB reply" is set to "YES"

Table 6-7: Discrete input - terminal assignment - alarm/control input - positive signal

## NOTE The parameter "Ignore CB reply" (described on page 72) may only be configured via LeoPC1.

#### **Discrete Inputs: Negative Signal**



Figure 6-17: Discrete inputs - alarm/control input - negative signal

Terr	ninal	Description			A <sub>max</sub>
Com.	Term.			Type ₽	
	16	Discrete input [D1]	Low oil pressure	fixed	2.5 mm <sup>2</sup>
	17	Discrete input [D2]	High coolant temperature	fixed	2.5 mm <sup>2</sup>
15	18	Discrete input [D3]	Remote start	fixed	2.5 mm <sup>2</sup>
	19	Discrete input [D4]	Reply MCB or alarm input	SW	2.5 mm <sup>2</sup>
	20	Discrete input [D5]	- Reply GCB or alarm input	SW	2.5 mm <sup>2</sup>

SW..alarm input switchable via software, if parameter "Ignore CB reply" is set to "YES"

Table 6-8: Discrete input - terminal assignment - alarm/control inputs - negative signal

#### **Discrete Inputs: Operation Logic**

Discrete inputs may be configured to be used for normally open (N.O) and normally closed (N.C.) contacts. The default condition for N.O. is that the voltage signal is low. If the N.O. contact closes, the signal becomes high and the easYgen will detect an appropriate alarm or status.

The default condition for N.C. is that the voltage signal is high. If the N.C. contact opens, the signal becomes low and the easYgen will detect an appropriate alarm or status.

The N.O. or N.C. contacts may be connected to the signal terminal or to the ground terminal of the discrete input. See previous chapter Discrete Inputs: Bipolar Signals on page 28 for details.



Figure 6-18: Discrete inputs - alarm/control inputs - operation logic

For the easYgen-300 series, the discrete inputs 1-3 are configured to a factory default and cannot be changed. The discrete inputs 4 and 5 are freely configurable depending on the parameter "Ignore CB reply". If this parameter is set to "YES", the discrete inputs are freely configurable, and the operation logic may be configured either to N.O. or N.C.

## **i**

#### NOTE

The parameter "Ignore CB reply" (described on page 72) may only be configured via LeoPC1.

## **Relay Outputs**

#### 

The easYgen series 300 provides up to six (6) galvanically isolated relay outputs. Some relay outputs have fixed assignments and cannot be configured.

• max	. 250 Vac	/dc			
∟ N/⊥ <del>&lt;</del>		external device		Relay	output
			Figu	re 6-19: R	elay outputs
Tern Term.	ninal Com.	Description			$A_{max}$
A	В			Туре ₽	
5/6	7	Relay output [R1] [350], [350X]	Command: open MCB	fixed	2.5 mm <sup>2</sup>
8	9	Relay output [R2]	Command: close GCB	fixed	2.5 mm <sup>2</sup>
10	11	Relay output [R3] [350], [350X]	one from the configurable pa- rameter list		2.5 mm <sup>2</sup>
12	11	Relay output [R4]	one from the configurable pa- rameter list		2.5 mm <sup>2</sup>
13	11	Relay output [R5]	Fuel relay	fixed	2.5 mm <sup>2</sup>
14	11	Relay output [R6]	Crank	fixed	2.5 mm <sup>2</sup>

Table 6-9: Relay outputs - terminal assignment, part 1

The conditions, which may be assigned to the relay outputs R3 [350], [350X] and R4 are listed in Table 10-1: Relay outputs - list of configurable parameters on page 93 (refer to Relay Outputs on page 92). If a signal is selected for an easYgen version without this feature, the relay will not be triggered.

## Interfaces

#### 

#### Overview



Table 6-10: Interfaces - connection overview



## NOTE

The DPC cable (P/N 5417-557) is intended for service operation only. Do not operate the easYgen-300 with the DPC plugged into the unit during regular operation.

# **i**

NOTE

The CAN interface is only used for the visualization of J1939 data from the ECU.

## CAN Bus [320X], [350X]

Wiring



Terminal	Description		A <sub>max</sub>
39	CAN bus -	CAN-L	2.5 mm <sup>2</sup>
40		CAN-H	2.5 mm <sup>2</sup>

Shielding



Figure 6-22: Interfaces - CAN bus - wiring of shielding

Please note that the CAN bus must be terminated at each end of the bus! Figure 6-23 is a topology of the CAN bus with the termination resistors installed.



Figure 6-23: Interfaces - CAN bus topology

#### **Possible CAN Bus Problems**

If no data is transmitted on the CAN bus, check the following for common CAN bus communication problems:

- T structure bus is utilized (stub-end feeders or branch lines are not recommended)
- CAN-L and CAN-H are interchanged
- Not all devices on the bus are using identical Baud rates
- Terminating resistor(s) is/are missing
- Incorrect baud rate (too high) for length of CAN bus
- The CAN bus cable is co-routed with power cables

Woodward recommends the use of twisted-pair cables for the CAN bus (i.e.: Lappkabel Unitronic LIYCY (TP)  $2 \times 2 \times 0.25$ , UNITRONIC-Bus LD  $2 \times 2 \times 0.22$ ).

#### Maximum CAN bus Length

The maximum length of the communication bus wiring is dependent on the configured Baud rate. Refer to Table 6-11 for the maximum bus length (Source: CANopen; Holger Zeltwanger (Hrsg.); 2001 VDE VERLAG GMBH, Berlin und Offenbach; ISBN 3-8007-2448-0).

Baud rate	Max. length
1000 kbit/s	25 m
800 kbit/s	50 m
500 kbit/s	100 m
125 kbit/s	250 m
50 kbits/s	1000 m
20 kbit/s	2500 m

Table 6-11: Maximum CAN bus length

The maximum specified length for the communication bus wiring might not be achieved if poor quality wire is utilized, there is high contact resistance, or other conditions exist. Reducing the baud rate may overcome these issues.

#### **DPC - Direct Configuration Cable**



#### NOTE

Please note that the configuration via the direct configuration cable DPC (P/N 5417-557) is possible starting with Revision B (first delivered July 2003). If you have an older model please contact technical sales.



#### NOTE

The connection cables delivered with the DPC must be used to connect between the control unit and the computer to ensure a proper function of the easYgen. Utilization of an extension or different cable types for the connection between easYgen and DPC can result in a malfunction of the easYgen. This may possibly result in damage to components of the system. If an extension of the data connection line is required, only the serial cable between DPC and notebook/PC may be extended.

Unplug the DPC after configuration to ensure a safe operation!





Figure 7-1: Front panel and display

Figure 7-1 illustrates the front panel/display which includes push-buttons, LEDs and the alphanumerical 7 segment LED display. A short description of the front panel is given below.



## **Operation and Display**

#### Purpose of the Status LEDs

The easYgen has several status LEDs to indicate the operating state. The LEDs indicate the following conditions: LED (9) (on): Mains voltage present (only easYgen-350 and 350X)

- LED (9) (flashing): Mains voltage and/or frequency are not within the Breaker Closure Limits (see page 60)
- LED <sup>(10)</sup>: Mains circuit breaker (MCB) closed (only easYgen-350 and 350X)
- LED <sup>(1)</sup>: Generator circuit breaker (GCB) closed
- LED<sup>(12)</sup> (on): Generator in operation
- LED <sup>(12)</sup> (flashing):Generator voltage and/or frequency are not within the Breaker Closure Limits (see page 60)

LED (0): Engine in operation

- LED (13) (flashing):Engine in operation, but engine monitoring delay time (see page 74) not yet expired
- LED <sup>14</sup>: Alarm message present
- LED <sup>(5)</sup>: Genset in automatic operation
- LED <sup>(6)</sup>: Genset in manual operation
- LED <sup>17</sup>: Genset stopped

A function test of all LEDs and the seven-segment display may be conducted by pressing the  $1^{\circ}$  and  $1^{\circ}$  (8) buttons simultaneously.

### Operating the easYgen

- When the easYgen control unit is powered up and the genset is not operating, LED (17) is illuminated and the MCB is closed (only easYgen-350 and 350X).
- The control unit may be started in automatic mode or have the operation mode changed from automatic to manual by pressing the Auto Manual button 3. LED 5 (automatic) or LED 6 (manual) will indicate the current mode of operation by the corresponding LED being illuminated.
- The Breaker Control button (1) (4) enables the operator to open or close the circuit breaker(s) depending on the current state of the breaker and the control unit being in manual operation mode. This button is disabled in automatic operation mode.
- The Start/Stop Engine button 4 (5) will start and stop the engine when the control unit is in manual operation mode. This button is disabled when the control unit is in automatic operation mode.
- The Stop button 6 is always enabled and when pressed while in the automatic mode will shut the engine down after the configured cool down period has expired. Pressing this button twice will shutdown the genset immediately.
- Active alarm messages may be acknowledged with the Alarm button 🙆 2. Alarm conditions are indicated when LED <sup>14</sup> is illuminated.
- When the easYgen is in normal operation, the operator may view the monitored parameters by using the Scroll button 1. The monitored values will be displayed on the 7-segment display 1. (a detailed description of the displayed operating values may be found later in this manual).

### Acknowledging Alarm Messages

LED <sup>(4)</sup> will flash when an alarm is active. The alarm message will be displayed in the 7-segment display <sup>(1)</sup>. Pressing the alarm button <sup>(2)</sup> <sup>(2)</sup> will acknowledge the alarm, reset the alarm relay (if relay is configured for alarm input), and the LED will change from flashing to continuously illuminated. If more than one fault condition is present, the operator may display these messages by pressing the Scroll button <sup>(2)</sup> <sup>(4)</sup>. The alarm may be deleted by pressing and holding the Alarm button <sup>(2)</sup> <sup>(2)</sup> a second time until the LED <sup>(14)</sup> is no longer illuminated. If the fault condition is still present, the LED <sup>(14)</sup> will remain illuminated and the unit stays in a locked mode according to the appropriate alarm condition.

### Configuring the easYgen

To enter the configuration mode, press the Scroll 1 and Alarm 2 buttons simultaneously. Only the parameters 00 - HMI Password, 01 - Time until horn reset and 72 - Display level are visible without entering a password. In order to display the other parameters, the correct password must be entered in the Parameter 00 - HMI Password. Pressing the Scroll button 1 will display the various parameters that may be changed. The displayed values for the parameters may be changed by pressing the 1 and 1 2 buttons (a detailed description of the parameters begins on page 70 of this manual). If the operator presses and holds these buttons, the rate of change for the value will increase. After the parameter has been adjusted to the desired value, enter it into the control unit by pressing the Scroll button 1 once. After a parameter has been changed and entered into the control unit, the operator may advance to the next parameters by pressing the Scroll button 1 a second time. To exit the configuration mode, press the Scroll 1 and Alarm 2 buttons simultaneously again.

## **Display of the Operating Values**

The easYgen-300 control units are able to display various measured values during operation depending on the respective easYgen model. You may advance through the single value displays using the Scroll button  $\square$  1.

The values are displayed numerically, while the engineering unit, source, and phase are coded in the seven-segment display <sup>(B)</sup> if applicable. See the example below:



- The first digit (counted from left) indicates what is being measured, (mains, engine, or generator). The top horizontal segment indicates mains, the middle horizontal segment indicates engine, and the bottom horizontal segment indicates generator.
- The second digit indicates the measured phase. The top segment indicates L1, the middle horizontal segment indicates L2, and the bottom horizontal segment indicates L3. If only one line is displayed for phase measurement, a phase to neutral measurement is displayed. If two lines are displayed, a phase to phase measure ment is shown.
- Digits 3-6 indicate what the measured value of the displayed parameter is.
- The indicators located at the top left of the first four digits of the display indicate the engineering unit of measure to be utilized. The indicators are assigned the following engineering units of measure.
  - Digit 1: Operating hours [h]
  - Digit 2: Revolutions [rpm]
  - Digit 3: Frequency [Hz]
  - o Digit 4: Voltage [V]

With this information, the example in the figure above reads as follows:

Voltage at generator between phase L2 and N is at 235.0 volts

Digit 1: Generator

Digit 2: Measurement between phase L2 and N

Digits 3 to 6: Numerical value 235.0

Indicator at digit 4: Voltage [V]

Digits 5 and 6 of the display are used to display eight different alarm states. The upper and lower vertical segments are used to indicate the various alarm states. Refer to Alarm Messages on page 41 for the description of the alarm messages.

For customization of your easYgen-300 front using the paper strips, refer to Front Customization on page 108.
## **Default Operating Value Display**

The easYgen detects and selects the default operating value display by evaluating the measured voltage and the circuit breaker position. This default operating value is always displayed first. The operator may advance through the following operating parameters using the Scroll button **1**.

Voltage and CB position	Voltage measuring	Default operating value	[320]	[320X]	[350]	[350X]
Generator voltage present	1Ph 2W or 1Ph 3W	Generator voltage V <sub>1N</sub>	~	✓	~	✓
GCB is closed	3Ph 3W or 3Ph 4W	Generator voltage V <sub>12</sub>		✓		✓
Mains voltage present	1Ph 2W or 1Ph 3W	Mains voltage V <sub>1N</sub>				✓
MCB is closed	3Ph 3W or 3Ph 4W	Mains voltage V <sub>12</sub>			$\checkmark$	✓

Table 7-1: Display - default operating value

If none of the conditions in Table 7-1 is fulfilled, the generator voltage  $V_{12}$  is displayed according to the order in Table 7-2.

## NOTE

The operating value display depends on the set display level (refer to Parameter 72 on page 96).

## Cycling Through the Displayed Operating Values

If the easYgen is in normal operation, the default operating value is displayed. The operator may advance through the different operating parameters using the Scroll button 🗐 1. Following the default operating value, the parameters are displayed in the order shown below (some parameters will not display if the related function is disabled or not available on the control unit):

Parameter / display level	Display	Applies to	
Generator voltage		easYgen-350X	$\checkmark$
V <sub>12</sub> (phase-phase)		easYgen-350	-
		easYgen-320X	✓
DL 1		easYgen-320	-
Generator voltage		easYgen-350X	$\checkmark$
V <sub>23</sub> (phase-phase)		easYgen-350	-
		easYgen-320X	$\checkmark$
DL 2		easYgen-320	-
Generator voltage		easYgen-350X	$\checkmark$
V <sub>31</sub> (phase-phase)		easYgen-350	-
		easYgen-320X	✓
DL 2		easYgen-320	-
Generator voltage		easYgen-350X	$\checkmark$
Average of the phase-phase		easYgen-350	-
voltages (two of the three		easYgen-320X	$\checkmark$
phase-phase indicators are		easYgen-320	-
displayed alternately)			
DL 2			
Generator voltage		easYgen-350X	<b>✓</b>
$V_{1N}$ (phase-neutral)		easYgen-350	<ul> <li>✓</li> </ul>
		easYgen-320X	<b>√</b>
DL I		easYgen-320	✓
Generator voltage		easYgen-350X	$\checkmark$
$V_{2N}$ (phase-neutral)		easYgen-350	-
		easYgen-320X	<ul> <li>✓</li> </ul>
DL 2		easYgen-320	-

Deremeter / display layel	Diaplay				Applies to	
Camaratar valtage	Display	-			Applies to	
Generator voltage	$\bigcirc$				eas r gen-350X	•
$v_{3N}$ (phase-neutral)					eas r gen-350	-
	$\odot$	-	<u> </u>		eas y gen-320X	•
					eas Y gen-320	-
Generator voltage	$\bigcirc$	977			eas Y gen-350X	•
Average of the phase voltages					eas Y gen-350	-
tors is displayed alternately)	$\odot$	_	<u> </u>		eas y gen-320X	-
DL 1					eas r gen-320	-
Mains voltage					easYgen-350X	<ul><li>✓</li></ul>
$V_{12}$ (phase-phase)	ထ				easYgen-350	<b>√</b>
riz (r ···· r ···)				ΠL.	easYgen-320X	_
DL 1					easYgen-320	_
Mains voltage					easYgen-350X	<ul><li>✓</li></ul>
$V_{23}$ (phase-phase)	ထို				easYgen-350	<b>√</b>
25 (r ····· r ····)					easYgen-320X	-
DL 2					easYgen-320	-
Mains voltage					easYgen-350X	<ul> <li>✓</li> </ul>
$V_{31}$ (phase-phase)	ထို				easYgen-350	<b>√</b>
					easYgen-320X	-
DL 2	G				easYgen-320	-
Mains voltage					easYgen-350X	<b>√</b>
Average of the phase-phase	မြ				easYgen-350	<ul> <li>✓</li> </ul>
voltages (two of the three					easYgen-320X	_
phase indicators are displayed					easYgen-320	_
alternately)					8	
Mains voltage	ത		-		easYgen-350X	✓
$V_{1N}$ (phase-neutral)					easYgen-350	$\checkmark$
	$\odot$				easYgen-320X	-
DL I					easYgen-320	-
Mains voltage	ത				easYgen-350X	✓
$V_{2N}$ (phase-neutral)					easYgen-350	✓
DL A	$\odot$				easYgen-320X	-
DL 2					easYgen-320	-
Mains voltage	୦				easYgen-350X	<ul> <li>✓</li> </ul>
$V_{3N}$ (phase-neutral)					easYgen-350	✓
DL A	$\odot$				easYgen-320X	-
DL 2				<u> </u>	easYgen-320	-
Mains voltage	0		-		easYgen-350X	<ul> <li>✓</li> </ul>
Average of the phase voltages					easYgen-350	✓
(one of the three phase indica-	$\odot$				easYgen-320X	-
tors is displayed alternately)		-			easYgen-320	-
DL 2 Pated generator frequency					onsVgon 350V	✓
Rated generator inequency	$\square$	97			easYgen_350	· •
				<b>i</b>	easYgen_320Y	- -
DL 1	$\overline{\mathbf{O}}$				$e_{as}Y_{gen}_{-320}$	, ,
Rated mains frequency					$e_{as}Y_{gen_3}$	<ul><li>✓</li></ul>
Race mans requercy	Q				easYgen_350	· •
				<b>i</b>	easYgen_320Y	-
DL 1					easYgen-320	_
	1					1

Parameter / display level	Display	Applies to	
Engine speed (display is not shown if the MPU is disabled) DL 1		easYgen-350X easYgen-350 easYgen-320X easYgen-320	✓ - ✓ -
Operating hours counter (display is six-digit with one decimal) DL 1		easYgen-350X easYgen-350 easYgen-320X easYgen-320	✓ ✓ ✓
Hours to next maintenance (a negative value indicates excess hours, maintenance overdue) DL 2		easYgen-350X easYgen-350 easYgen-320X easYgen-320	✓ ✓ ✓
Battery voltage DL 2		easYgen-350X easYgen-350 easYgen-320X easYgen-320	✓ ✓ ✓
Charging voltage (display is suppressed if the charging voltage monitoring is disabled) DL 2		easYgen-350X easYgen-350 easYgen-320X easYgen-320	$ \checkmark \\ \checkmark \\ \checkmark \\ \checkmark \\ \checkmark $

Table 7-2: Display of operating values

If the Scroll button 🗐 1 is pressed again, the display returns to the default operating value (refer to Default Operating Value Display on page 37). The display automatically returns after 180 seconds to the default operating value being displayed if a button isn't pressed.

# J1939 Visualization [320X], [350X]

### J1939 Operating Value Display

The easYgen-300 with the X package is able to display standard J1939 messages, which are sent by the engine control to the easYgen via the CAN bus. The values are displayed on the unit and in LeoPC1. In order to visualize J1939 messages with LeoPC1, the PC/laptop running LeoPC1 must be connected via the DPC interface (refer to page 32). It is also possible to display Scania S6 and Deutz EMR2 messages in LeoPC1. The J1939 visualization can be configured with parameter 90, J1939 device type. If this parameter is not configured to Off, the standard J1939 messages are displayed on the unit immediately following the operating values as described in the chapter Display of the Operating Values on page 37.

You find detailed information about the J1939 visualization with LeoPC1 under J1939 Protocol Descriptions starting on page 106.

# NOTE

# Only signals, which are present, will be displayed. If a signal is not sent to the control unit, the display of this value is not shown. If the sent values exceed the specified range, the displayed value is not defined.

The following J1939 messages can be displayed by the easYgen. The J1939 messages follow the operating val-

ues and can be viewed in the following order using the Scroll button 1 **1**. The values are updated by pressing the scroll button.

J19	39 message / display level	Display	Range	
1	Throttle position		0 to 100	%
			Display	000.0
			SPN	91
	DL 1		PGN	61443
2	Percent load at current		0 to 250	%
	RMP		Display	000
			SPN	92
	DL 1		PGN	61443
3	Actual engine % torque		-125 to 1	25 %
	0		Display	0000
			SPN	513
	DL 1		PGN	61444
4	Engine speed		0 to 803	2 rpm
			Display	0000
			SPN	190
	DL 1		PGN	61444
5	Total engine hours		0 to 999	9 h
	e		Display	0000
			SPN	247
	DL 1		PGN	65253
6	Engine coolant temp		-40 to 21	0 °C
	6 1		Display	000
			SPN	110
	DL 1		PGN	65262
7	Fuel temperature		-40 to 21	0 °C
_	I I I I I I I I I I I I I I I I I I I		Display	000
			SPN	174
	DL 1		PGN	65262
8	Engine oil temperature		-273 to 1	735 °C
	U		Display	0000
			SPN	175
	DL 1		PGN	65262

J19	39 message / display level	Display	Range	
9	Engine oil level		0 to 100	%
	-		Display	000
			SPN	98
	DL 1		PGN	65263
10	Engine oil pressure		0 to 100	0 kPa
			Display	0000
			SPN	100
	DL 1		PGN	65263
11	Coolant level		0 to 100	%
			Display	000
			SPN	111
	DL 1		PGN	65263
12	Fuel rate		0 to 321	3 L/h
			Display	0000
			SPN	183
	DL 1		PGN	65266
13	Barometric pressure		0 to 125	kPa
			Display	000
			SPN	108
	DL 1		PGN	65269
14	Air inlet temperature		-40 to 2	10 °C
	_		Display	000
			SPN	172
	DL 1		PGN	65269
15	Boost pressure		0 to 500	kPa
			Display	000
			SPN	102
	DL 1		PGN	65270
16	Intake manifold temp.		-40 to 2	10 °C
	_		Display	000
			SPN	105
	DL 1		PGN	65270
17	Exhaust gas temperature		-273 to	1735 °C
1			Display	0000
			SPN	173
	DL 1		PGN	65270

Table 7-3: J 1939 messages

In case of a defective sensor or a broken wire the easYgen-300 displays four dashes instead of the J1939 value following the respective J1939 identifier.



Figure 7-3: J1939 fault display

The above display shows that the engine oil pressure (identifier 9r) sensor is defective or the cable from the sensor to the ECU is unplugged or broken. A defective sensor or a broken wire is also displayed in LeoPC1. The display appearing in this case is described under J1939 Protocol Descriptions starting on page 106.

### J1939 DM1/DM2 Error Message Display

The easYgen-300 with the X package is able to display J1939 DM1 and DM2 error messages, which are sent by the engine control to the easYgen via the CAN bus. The J1939 visualization can be configured with parameter 90, J1939 device type. If this parameter is not configured to Off, the J1939 DM1 and DM2 error messages are displayed on the unit if the unit is in STOP operating mode.

If the easYgen receives an error message, this will be evaluated in the unit and the scrolling display starts if no

alarm is present. The scrolling display may be cleared by pressing the Alarm button 0 2. If DM1 and DM2 error messages are present at the same time, the scrolling display of the DM1 error messages is displayed as long as no alarm is present. If the scrolling display of the DM1 error messages is cleared by pressing the Alarm button

(2), the scrolling display of the DM2 error messages is displayed. If all scrolling displays are cleared, the operating value display is active again. A scrolling display can only be cleared at least 10 seconds after the first occurrence. If DM1 error messages are not received anymore for at least 10 seconds they will be reset in LeoPC1.

The following content is visualized for DM1 and DM2 error messages:

- DM identifier DM1 (Data Memory 1) or DM2
- SPN number Suspect Parameter Number
- FMI number Failure Mode Identifier
- OC Occurrence Counter

The error messages are indicated by a scrolling display. The scrolling display starts with a header, displays the single messages, and ends with an end marker. There are two separate scrolling displays for DM1 error messages and DM2 error messages. A scrolling display is composed as follows:

	Content	Display	Description
Display header	Header	J1939	The header indicates the start of a scrolling message
	DMLdentifier	dnx	The data memory identifier indicates whether it is a DM1 message (dn1) or a
First error mes- sage	DW Identifier		DM2 message (dn2)
	Suspect Parameter Number	XXXX	The four-digit SPN describes the error message
	Failure Mode Identifier XX		The two-digit FMI describes the error message in detail
	Occurrence Counter	xx	The two-digit OC indicates the number of occurrences of this error message
			Possible further error messages may be between the first and last error message
	DM Identifien	dnx	The data memory identifier indicates whether it is a DM1 message (dn1) or a
Lost amon mass	DW Identifier		DM2 message (dn2)
Last error mes-	Suspect Parameter Number	XXXX	The four-digit SPN describes the error message
sage	Failure Mode Identifier	xx	The two-digit FMI describes the error message in detail
	Occurrence Counter	xx	The two-digit OC indicates the number of occurrences of this error message
Display end	End Marker	End	The end marker indicates the end of the scrolling message

Table 7-4: DM1/DM2 error message composition

The header is displayed left-justified in the 7-segement display for one second and then it starts to scroll. The header and the first error message are separated by a blank. The four content elements of an error message are separated by two blanks. The last error message and the end marker are separated by two blanks. The end marker is displayed for one second. Then the scrolling display starts again.

Example for a scrolling display with only one error message: J1939 dn1-0120-20-03 End

Example for	or a scrolling display wi	th four error messages:			
J1939	dn1-0120-20-03	dn1-0190-05-09	dn1-1312-31-10	dn1-0091-06-04	End



### NOTE

The J1939 DM1 or DM2 error messages are only displayed in STOP operating mode.

You find detailed information about the J1939 protocol under J1939 Protocol Descriptions starting on page 106.

### **Alarm Messages**

If the easYgen detects a fault condition, LED <sup>(1)</sup> starts to flash. The alarm message is displayed in the sevensegment display <sup>(1)</sup> with a blinking "A" for alarm, an alarm number, and the respective alarm segment, if applicable. The alarm may be acknowledged by pressing the Alarm button <sup>(2)</sup> 2. The flashing LED and "A" will change to a continuously illuminated state and the relay will be reset. If more alarm conditions are present, the operator may advance through the different alarm messages using the Scroll button <sup>(1)</sup> 1. By pressing the

Alarm button 2 again, the alarm may be cleared unless the fault condition is still present. Figure 7-4 shows the additional alarm states using the vertical segments of the last two digits of the sevensegment display 3. The four top segments are pre-assigned with the alarms shown in Figure 7-4, but are freely configurable via LeoPC1 for common alarms from a list of alarms located in Table 7-6. The customer-defined paper strip label allows for a customized front display panel. The lower four segments are permanently assigned to engine alarms (battery undervoltage (alarm no. 50A), engine over/underspeed (no. 20A/21A), oil pressure (no. 60A), and coolant temperature (no. 61A)).

Symbol	Alarm	Maintenance hours exceeded	7
Bymeer		Generator over-/underfrequency	
Ē	Battery undervoltage	Generator over-/undervoltage Start failure	
$\sim$	Engine over-/underspeed		
٩ <u>۲</u>	Oil pressure		
<u>بالج</u>	Coolant overtemperature		_ <b>t</b>
			$\overline{\mathbf{h}}$

Figure 7-4: Additional alarm display

The alarm messages are assigned to different alarm classes depending on their importance and required reaction. You find more information about this under Alarm Classes on page 104. The following alarm classes exist:

Class	Description	Reaction of the system
В	Alarm	The operation is not interrupted but a centralized alarm is issued.
F	Shutdown	The GCB will be opened immediately and the engine will be stopped without cool down.

Table 7-5: Alarm classes

The following table displays the possible alarm messages:

	Alarm	Alarm class	Display	Applies	s to
10	Generator overfre- quency	F: Shutdown		350X 350 320X 320	<ul> <li></li> &lt;</ul>
11	Generator under- frequency	F: Shutdown		350X 350 320X 320	<ul> <li></li> <li></li></ul>
12	Generator overvol- tage	F: Shutdown		350X 350 320X 320	<ul> <li></li> &lt;</ul>
13	Generator under- voltage	F: Shutdown		350X 350 320X 320	<ul> <li>✓</li> <li>✓</li> <li>✓</li> <li>✓</li> </ul>

-					
	Alarm	Alarm class	Display	Applies	to
14	Mains rotation	B: Alarm		350X	<ul> <li>✓</li> </ul>
	field mismatch			350	✓
				320X	-
20	The second second			320 250V	-
20	Engine overspeed	F: Shutdown		350X	×
				350	-
				320X	×
21	Excise underground	E. Classicary		320 250V	-
21	Engine underspeed	F: Shutdown		330A	×
				330 220V	-
				320A	-
30	Stort fail	E. Shutdown		320 350X	-
30	Start rain	F. Shuuowh		350A 350	
				330 320X	· •
				3207	· •
31	Unintended stop	F. Shutdown		350X	· · ✓
51	Ommended Stop	I. Dhutuo wh		350	✓
				320X	<b>√</b>
				320	<ul> <li>✓</li> </ul>
40	Maintenance hours	B∙ Alarm		350X	<b>√</b>
10	Munice notice	D. / hum		350	<ul><li>✓</li></ul>
				320X	<ul><li>✓</li></ul>
				3201	<b>√</b>
50	battery undervol-	B∙ Alarm		350X	<b>√</b>
20	tage	D. / Hurth		350	<b>√</b>
	<u>8</u> -			320X	<ul><li>✓</li></ul>
				320	<b>√</b>
51	Charge failure	B: Alarm		350X	<b>√</b>
-				350	<ul> <li>✓</li> </ul>
				320X	<b>√</b>
				320	<b>√</b>
60	DI1: Oil pressure	F: Shutdown		350X	<b>√</b>
	*			350	✓
				320X	$\checkmark$
				320	<ul> <li></li> </ul>
61	DI2: Coolant tem-	F: Shutdown		350X	$\checkmark$
	perature			350	<ul><li>✓</li></ul>
				320X	$\checkmark$
				320	✓
62	DI4: MCB reply or	Control input/		350X	✓
	free configurable	Selectable		350	✓
		B or F		320X	✓
		ļ		320	<ul> <li>✓</li> </ul>
63	DI5: GCB reply or	Control input/		350X	<ul> <li>✓</li> </ul>
	free configurable	Selectable		350	✓
		B or F		320X	<ul> <li>✓</li> </ul>
				320	✓
64	J1939 CAN Error	Selectable		350X	<b>√</b>
		B or F		350	-
				320X	✓
	1			320	-

	Alarm	Alarm class	Display	Applies	to
65	J1939 DM1 amber	Selectable		350X	✓
	warning lamp	B or F		350	-
				320X	$\checkmark$
				320	-
66	J1939 DM1 red	Selectable		350X	$\checkmark$
	stop lamp	B or F		350	-
				320X	$\checkmark$
				320	-

Table 7-6: Alarm messages



# NOTE

Discrete Inputs 4 & 5: If the parameter "Ignore Breaker Replies" (only changeable via LeoPC1) is set to "YES", the discrete inputs for 4 and 5 are no longer control inputs. These discrete inputs may now be used as freely configurable alarm inputs. All alarm classes may be configured for these discrete inputs.

# **Configuration Displays**

The following parameters can be configured as described under Configuring the easYgen on page 36:

	Parameter	Range	Display	Applies	s to
<b>00</b> DL	HMI Password	0000 to 9999		350X 350 320X	✓ ✓ ✓
1				32011	<b>~</b>
01	Time until horn	0 to 1000 s		350X	<b>√</b>
	reset	[1 s interval]		350	✓
DL				320X	~
1				320	$\checkmark$
10	Rated frequen-	50 Hz, 60 Hz		350X	✓
DI	cy			350	<ul> <li>✓</li> </ul>
3				320X	$\checkmark$
11		50 / 400 M		320	<ul><li>✓</li></ul>
11	Generator rated	50 to 480 V		350X	×
DL	voltage			320X	▼ ✓
3				320A	· ✓
12	Mains rated	50 to 480 V		350X	<b>√</b>
	voltage	[1 V interval]		350	<b>√</b>
DL	_			320X	-
3				320	-
20	Fuel relay	0 = open to stop		350X	✓
ы	(open/close)	1 = close to stop		350	~
DL 3				320X	<ul> <li>✓</li> </ul>
				320	<ul> <li>✓</li> </ul>
21	Preglow time	0 to 999 s		350X	<ul> <li>✓</li> </ul>
DL		[1 s interval]		350 220V	×
3				320X	×
30	MPU (nickup)	0 = off  1 = op		350X	· ·
50	on/off	0 = 011, 1 = 011		350	-  -
DL				320X	<b>√</b>
3				320	-

	Parameter	Pange	Display	Applies	to
31	Nominal speed	500 to 4000 rpm		350X	
51	Nominar speed	[1 rpm interval]		350	
DL		(* - <u>F</u> , ,		320X	<ul> <li>✓</li> </ul>
3				320	-
32	Number of	2 to 260 teeth		350X	$\checkmark$
-	teeth	[1 tooth interval]		350	-
DL				320X	$\checkmark$
3		ĺ		320	-
40	Cooldown time	0 to 999 s		350X	$\checkmark$
		[1 s interval]		350	$\checkmark$
DL 3		ľ		320X	$\checkmark$
5		<u> </u>		320	$\checkmark$
50	Generator over-	50.0 to 130.0 %		350X	<ul> <li>✓</li> </ul>
זת	frequency thre-	[0.1 % interval]		350	<ul> <li>✓</li> </ul>
DL 3	shold			320X	<ul> <li>✓</li> </ul>
- 1		- 1 00 0		320	<ul><li>✓</li></ul>
51	Generator over-	0.1 to 99.9 s		350X	×
DL,	frequency ae-	[0.1 s interval]		350 220V	<b>*</b>
3	lay unic			320X	× ./
50	Comparison up	50.0 to 120.0 %		320 250 <b>V</b>	× ./
52	Generator un-	50.0 to 150.0 %		350A	×
DL	threshold	[0.1 70 mice var]		220X	× ✓
3	unconora			3207	· ·
53	Generator un-	0.1 to 99.9 s		320 350X	· •
55	derfrequency	[0.1 s interval]		350	· •
DL	delay time	[011 0 11101 111]		320X	~
3	-			320	<ul> <li>✓</li> </ul>
54	Generator	50.0 to 125.0 %		350X	~
	overvoltage	[0.1 % interval]		350	$\checkmark$
DL 3	threshold	ľ		320X	$\checkmark$
3				320	$\checkmark$
55	Generator	0.1 to 99.9 s		350X	✓
זת	overvoltage de-	[0.1 s interval]		350	✓
DL 3	lay time	ľ		320X	<ul> <li>✓</li> </ul>
				320	<ul> <li>✓</li> </ul>
56	Generator un-	50.0 to 125.0 %		350X	×
DL.	dervoltage	[0.1 % interval]		350 220V	V
3	unesnou			320X	<b>v</b>
57	Concretor un	$0.1 \pm 0.00$ 0 s		320 350Y	V
51	dervoltage de-	0.1 to 99.9 s [0.1 c interval]		330A 250	•
DL	lav time	[0.1 5 morvar]		330 320X	· •
3	10.j			3207	· •
58	Engine over-	0 = off. 1 = on		350X	<b>√</b>
•••	speed monitor-	0 - 011, 1 011		350	+
DL	ing on/off			320X	<b>√</b>
3		ĺ		320	-
59	Engine over-	0 to 9999 rpm		350X	✓
	speed threshold	[1 rpm interval]		350	-
DL 2				320X	$\checkmark$
3				320	-

	Parameter	Range	Display	Applies to
60	Battery under-	8.0 to 42.0 V		350X ✓
	voltage thre-	[0.1 V interval]		350 🗸
DL 2	shold			320X ✓
3				320 🗸
61	Battery charge	0 = off, 1 = on		350X ✓
	failure monitor-			350 🗸
DL 3	ing on/off			320X ✓
				320 🗸
62	Battery charge	0.0 to 32.0 V		350X ✓
DI	failure monitor-	[0.1 V interval]		350 🗸
3	ing threshold			320X ✓
- 0		0.00001		320 ✓
70	Maintenance	0 to 9999 h		350X ✓
DL	nours	[1 II IIIterval]		350 V
1				320X V
71	Poset mainten	0 - no 1 - voc		320 V 350V √
/1	ance hours	0 = 110, 1 = yes	ו הי הי הי הי <u>ה</u> י	350A ·
DL	unee nours			320X ✓
1				32011 ✓
72	Display level	1. 2. 3		350X ✓
. –		-, -, -		350 ✓
DL				320X ✓
1				320 🗸
80	Mains settling	0 to 9999 s		350X ✓
	time	[1 s interval]		350 🗸
DL 3				320X -
5				320 -
81	Mains overvol-	50.0 to 130.0 %		350X ✓
DI	tage threshold	[0.1 % interval]		350 ✓
3				320X -
00		50.0 / 120.0 0/		320 -
82	Mains under-	50.0 to $130.0$ %		350X ▼
DL	shold			330 V
3	Shora			320A -
83	Mains voltage	0 0 to 50 0 %		350X ✓
00	hysteresis	[0.1 % interval]		350 ✓
DL	-			320X -
3				320 -
84	Mains overfre-	70.0 to 160.0 %		350X ✓
	quency thre-	[0.1 % interval]		350 🗸
DL 3	shold			320X -
				320 -
85	Mains under-	70.0 to 160.0 %		350X ✓
DI	shold	[0.1 % interval]		350 ✓
3	511010			320X -
94	Mains fraction	0.0 to 50.0.0/		320 - 350V √
00	cy hysteresis	0.0 10 30.0 % [0 1 % interval]		350A ♥
DL	<i>cy mysteresis</i>			320X
3				320 -

	Parameter	Range	Display	Applies	s to
87 DL 3	Mains phase rotation moni- toring - self acknowledge	0 = Off 1 = On		350X 350 320X 320	✓ ✓ - -
<b>90</b> DL 3	J1939 Device Type	0 = Off 1 = Standard 2 = Scania S6 3 = Deutz EMR		350X 350 320X 320	✓ - ✓ -
<b>91</b> DL 3	Requested Send Address	0 to 255 [1 step interval]		350X 350 320X 320	✓ - ✓ -
<b>92</b> DL 3	Receive Device Number	0 to 255 [1 step interval]		350X 350 320X 320	✓ - ✓ -
<b>93</b> DL 3	J1939 Monito- ring	0 = Off 1 = On		350X 350 320X 320	✓ - ✓ -
<b>94</b> DL 3	J1939 Amber alarm	0 = Off 1 = On		350X 350 320X 320	<ul> <li>✓</li> <li>-</li> <li>✓</li> <li>-</li> </ul>
<b>95</b> DL 3	J1939 Red alarm	0 = Off 1 = On		350X 350 320X 320	✓ - ✓ -

DL..Display Level (parameter 72)

Table 7-7: Configuration displays

# NOTE

# The display automatically returns to the default operating value (refer to Default Operating Value Display on page 37) if a button isn't pressed within 180 seconds.

# **Display Hierarchy**

The display system refreshes if a button isn't pressed within 180 seconds. The initial display depends on the presence of alarm or error messages and the operating mode. The following display hierarchy applies:

Hierarchy level	Display	Comments
1	Alarm messages	Alarm messages are displayed first if they are present (refer to Alarm Messages on page 43)
2	J1939 DM1 error	J1939 DM1 error messages are displayed if they are present and the unit is in STOP operating mode
2	messages	and no alarm messages are present (refer to J1939 DM1/DM2 Error Message Display on page 42)
	11030 DM2 error	J1939 DM2 error messages are displayed if they are present and the unit is in STOP operating mode
3	messages	and no alarm messages or DM1 error messages are present (refer to J1939 DM1/DM2 Error Message
		Display on page 42)
		The operating values are displayed if no alarm or J1939 DM1/DM2 error messages are present in STOP
4	Operating values	operating mode or no alarm messages are present in MANUAL or AUTOMATIC operating mode (refer
	1 0	to Display of the Operating Values on page 36)

Table 7-8: Display hierarchy

# Chapter 8. Functional Description

# **Overview**

### 

Ĩ	Application mode			
	{1 breaker	r open/close}	{2 breaker	s open/close }
easYgen Version	[320], [320X], [350], [350X]		[350]	,[350X]
<b>Operation Mode</b>	MAN	AUTO	MAN	AUTO

Operate the engine					
• Start er	ngine by:				
	the engine START - STOP push button	YES		YES	
	the discrete input DI3 (remote start)		YES		YES
	emergency power (AMF)				YES
• Stop er	ngine by:				
	the STOP push button	YES	YES	YES	YES
	the engine START - STOP push button	YES		YES	
	the discrete input DI3 (remote start)		YES		YES
	emergency power (AMF)				YES
	an alarm (i.e. overspeed)	YES	YES	YES	YES

Operate GCB					
• close (	GCB				
	the BREAKER CONTROL push button	VES		VES	
	(only if engine is running)	1125		1125	
	emergency power (AMF)				YES
• open G	CB				
	the STOP push button	YES	YES	YES	YES
	the BREAKER CONTROL push button	YES		YES	
	emergency power (AMF)				YES
	an alarm (i.e. overvoltage)	YES	YES	YES	YES

Operate	Operate MCB				
• open N	• open MCB				
	the BREAKER CONTROL push button			YES	
	emergency power (AMF)				YES
• close N	• close MCB				
	the STOP push button			YES	YES
	the BREAKER CONTROL push button			VEC	
	(only if mains are present)			160	
	emergency power (AMF)				YES

Table 8-1: Functional description - Overview

• Application Mode (page 50): depends on the application; defines the number/function of the breakers.

• easYgen Version (page 12): indicates, which easYgen versions permit this application mode.

• Operating Mode (page 51): depends on the application; differs between STOP, MANUAL and AUTOMATIC modes.

# **Application Modes**

### 

The most important features of the application modes are illustrated in the following. Please note that the 2 breaker application mode is only possible with the easYgen versions [350], and [350X].

# Application Mode {1 breaker open/close} – [320], [320X], [350], [350X]

GCB

- This application mode provides the following functions:
  - operation of the engine (start/stop)
- monitoring and display of generator and engine parameters
- monitoring of selected parameters and protection of the generator and the engine
- opening and closing the GCB
- dead bus monitoring and logic

## Application Mode {2 breakers open/close} – [350], [350X]

This application mode provides the following functions:

- operation of the engine (start/stop)
- monitoring and display of generator and engine parameters
- monitoring of selected parameters and protection of the generator and the engine
- opening and closing the GCB
- dead bus monitoring and logic
- operating the MCB (open/close)
- emergency power (AMF automatic mains failure) operation



# **Operating Modes**

### 

## **Operating Mode STOP**



# NOTE

Selecting the operating mode STOP is not the same as an EMERGENCY STOP. In some cases the easYgen will perform additional logic functions, such as an engine cool down period, before the engine is stopped. It is recommended that an EMERGENCY STOP discrete input is utilized and programmed as a class F alarm (only configurable via LeoPC1).



In the STOP operating mode neither the engine or the power circuit breakers can be operated. The following occurs if operating mode STOP has been selected while...

### ... the engine is not running

- 1. The GCB will not close
- 2. The fuel solenoid relay cannot be enabled
- 3. The discrete inputs "Oil pressure" and "Coolant Temperature" are ignored
- 4. The push buttons START STOP and BREAKER CONTROL are disabled
- 5. The engine/generator monitoring remains de-activated (exception: all monitoring that is not delayed by the delayed engine speed monitoring)
- 6. The MCB will be closed if it is open [350], [350X]

### ... the engine is running

- 1. The GCB will open if it is closed
- 2. The MCB will close if the GCB is open and mains are present
- 3. An engine cool down will be performed
- 4. The fuel solenoid relay will be disabled
- 5. Selected engine/generator monitoring functions (this includes under-voltage, -frequency, -speed, oil pressure) will be de-activated (exception: all monitoring that is not delayed by the delayed engine speed monitoring)

### **Operating Mode MANUAL**

# i

You find an overview about the buttons, LEDs and the seven-segment display under Operation and Navigation on page 34.



NOTE

In the MANUAL operating mode (AUTO - MANUAL button <sup>3</sup>) the engine and the power circuit breakers are operated via the BREAKER CONTROL button <sup>4</sup>. The LED <sup>16</sup> in the upper right corner of the AUTO - MANUAL button <sup>3</sup> indicates the manual operating mode.

You can perform the following actions in the MANUAL operating mode depending on the application mode:

### Application Mode {2 breakers open/close} - [350], [350X]



### The START - STOP button 5

Start the engine (if the engine is stopped, LED (3) is not illuminated) Stop the engine (if the engine is running, LED (3) is illuminated)



### The BREAKER CONTROL button 4

Open the GCB and close the MCB (if the control unit is in generator operation (LEDs <sup>(1)</sup> and <sup>(2)</sup> are illuminated) and mains are present, LED <sup>(9)</sup> is illuminated) Open the MCB and close the GCB (if the control unit is in mains operation (LEDs <sup>(9)</sup> and <sup>(10)</sup> are illuminated) and engine is running, LED <sup>(13)</sup> is illuminated)

### Detailed operation with 2 CBs in manual mode (mains are present)

	Preconditions:	<ul> <li>Generator is stopped – LED <sup>12</sup> is not illuminated</li> <li>MCB is closed – LED <sup>10</sup> is illuminated</li> <li>Mains are present – LED <sup>9</sup> is illuminated</li> <li>Unit is in manual mode – LED <sup>16</sup> is illuminated</li> </ul>
Engine	e start sequence:	
Action	START	Press the START - STOP button 5
Delay	Preglow time	The relay will energize the glow plugs for the time configured in the engine parameters (page 73)
Operation	Fuel relay	The fuel relay (relay 5) is energized to enable the fuel solenoid
Operation	Crank relay	The crank relay (relay 6) is energized to engage the starter – LED <sup>(12)</sup> il- luminates and LED <sup>(13)</sup> starts flashing when generator speed has been detected
Delay	Engine delay time	The engine monitoring is delayed until time configured in the engine parameters (page 74) expires $- \text{LED}^{(3)}$ changes to steady illumination after the time expires
GCB	close sequence:	1
Action	Breaker control	Pressing the BREAKER CONTROL button
Operation	Open MCB	The MCB open relay (relay 1) energizes to open the MCB – LED $\frac{10}{10}$ goes out
Delay	Breaker delay	The control unit waits for the breaker transfer time configured in the breaker parameters (page 75) to expire
Operation	Close GCB	The GCB close relay (relay 2) energizes to close the GCB – LED $\textcircled{11}$ il- luminates

MCB	close sequence:	
Action	Breaker control	Press the BREAKER CONTROL button 4
Operation	Open GCB	The GCB close relay (relay 2) de-energizes to open the GCB – LED $(1)$ goes out
Delay	Breaker delay	The control unit waits for the breaker transfer time configured in the breaker parameters (page 75) to expire
Operation	Close MCB	The MCB open relay (relay 2) de-energizes to close the MCB – LED <sup>(10)</sup> illuminates
Stop sequ	ence via START -	
	STOP:	
Action	STOP	Press the START - STOP button <sup>5</sup>
Operation	Open GCB	The GCB close relay (relay 2) de-energizes to open the GCB – LED $(1)$ goes out
Operation	Engine stop	The engine stops – LEDs $\frac{12}{12}$ and $\frac{13}{13}$ go out
Action	Breaker control	Pressing the BREAKER CONTROL button 4
Operation	Close MCB	The MCB open relay (relay 1) de-energizes to close the MCB –
		LED <sup>10</sup> illuminates
Stop sequ	ence via STOP one	
	time:	
Action	STOP	Press the STOP button <sup>6</sup> once
Operation	Open GCB	The GCB close relay (relay 2) de-energizes to open the GCB – LED $(1)$ goes out
Delay	Breaker delay	The control unit waits for the breaker transfer time configured in the breaker parameters (page 75) to expire
Operation	Close MCB	The MCB open relay (relay 1) de-energizes to close the MCB – LED <sup>(1)</sup> illuminates
Delay	Cool down time	The control unit waits for the cool down time configured in the engine parameters (page 74) to expire
Operation	Engine stop	The engine stops – LEDs $\frac{12}{12}$ and $\frac{13}{13}$ go out
Stop sequ	ence via STOP two	
	times:	
Action	STOP	Press the STOP button <sup>6</sup> twice
Operation	Open GCB	The GCB close relay (relay 2) de-energizes to open the GCB – LED $(1)$ goes out
Delay	Breaker delay	The control unit waits for the breaker transfer time configured in the breaker parameters (page 75) to expire
Operation	Close MCB	The MCB open relay (relay 1) de-energizes to close the MCB $-$ LED <sup>(10)</sup> illuminates
Operation	Engine stop	The engine stops immediately without a cool down period – LEDs $(2)$ and $(3)$ go out

### Detailed operation with 2 CBs in manual mode (mains are not present) - [350], [350X]

Preconditions: Generator is stopped – LED <sup>12</sup> is not illuminated
MCB is closed – LED <sup>10</sup> is illuminated

- Mains are not present LED 9 is not illuminated
- Unit is in manual mode LED (16) is illuminated

Eng	ine start sequence:	
Action	START	Press the START - STOP button <sup>5</sup>
Delay	Preglow time	If diesel start logic is selected the relay will energize the glow plues for the time configured in the engine parameters (page 73)
Operation	Fuel relay	The fuel relay (relay 5) is energized to enable the fuel solenoid
Operation	Crank relay	The crank relay (relay 6) is energized to engage the starter –
operation		LED $(2)$ illuminates and LED $(3)$ starts flashing when generator
		speed has been detected
Delay	Engine delay time	The control unit waits for the engine monitoring delay time con-
		figured in the engine parameters (page 74) to expire – LED <sup>(13)</sup> changes to steady illumination after the time expires
GC	CB close sequence:	
Action	Breaker control	Press the BREAKER CONTROL button 4
Operation	Open MCB	The MCB open relay (relay 1) energizes to open the MCB –
		LED <sup>(10)</sup> goes out
Delay	Breaker delay	The control unit waits for the breaker transfer time configured in
		the breaker parameters (page 75) to expire
Operation	Close GCB	The GCB close relay (relay 2) energizes to close the GCB –
0.0		LED U illuminates
GC Action	B open sequence:	
Action	Dreaker control	The CCP close relay (relay 2) do exercises to energy the CCP
Operation	Open GCB	The GCB close relay (relay 2) de-energizes to open the GCB $-$
	Note	LED U goes out
	Inote	The MCB close command will not be issued unless the mains re-
Ston seau	ence via START - STOP	tum
Action	STOP	Press the START - STOP button $(5)$
Operation	Open GCB	The GCB close relay (relay 2) de-energizes to open the GCB –
-1		LED <sup>(1)</sup> goes out
Operation	Engine stop	The engine stops – LEDs $\frac{12}{12}$ and $\frac{13}{13}$ go out
Action	Breaker control	Pressing the BREAKER CONTROL button 4
Operation	Close MCB	The MCB open relay (relay 1) de-energizes to close the MCB –
1		LED <sup>10</sup> illuminates
Stop sequ	ence via STOP one time:	
Action	STOP	Press the STOP button 6 once
Operation	Open GCB	The GCB close relay (relay 2) de-energizes to open the GCB –
		LED <sup>(1)</sup> goes out
Delay	Breaker delay	The control unit waits for the breaker transfer time configured in
		the breaker parameters (page 75) to expire
Operation	Close MCB	The MCB open relay (relay 1) de-energizes to close the MCB –
		LED <sup>(10)</sup> illuminates
Delay	Cool down time	The control unit waits for the cool down time configured in the
	<b>T</b> • •	engine parameters (page 74) to expire
Operation	Engine stop	The engine stops – LEDs $\frac{12}{12}$ and $\frac{13}{13}$ go out
Stop seque	ence via STOP two times:	
Action	SIUP	Press the STOP button vice
Operation	Open GCB	I ne GUB close relay (relay 2) de-energizes to open the GCB –
Dalar	Dunghan dalari	LED $\forall goes out$
Delay	breaker delay	the breaker parameters (page 75) to evpire
Operation	Close MCB	The MCB open relay (relay 1) de-energizes to close the MCB –
operation		I = I = I = I = I = I = I = I = I = I =
Operation	Engine stop	The angine stops $I E D = \frac{12}{12}$ and $\frac{13}{13}$ as cut
Perunon	- Sinc stop	rne engine stops – LED's 🤝 and 😎 go out

### Application Mode {1 breaker open/close} - [320], [320X], [350], [350X]



The START - STOP button <sup>5</sup> Starts the engine (if the engine is stopped, LED <sup>(3)</sup> is not illuminated) Stops the engine (if the engine is running, LED <sup>(3)</sup> is illuminated)



## The BREAKER CONTROL button 4

Opens the GCB (if the GCB is closed LED <sup>(1)</sup> is illuminated) Closes the GCB (if the GCB is open (LED <sup>(1)</sup> not illuminated) and the engine is running(LED <sup>(13)</sup> is illuminated))

### Detailed operation with 1 CB in manual mode

	Preconditions:	<ul> <li>Generator is stopped – LED <sup>(12)</sup> is not illuminated</li> <li>Unit is in manual mode – LED <sup>(16)</sup> is illuminated</li> </ul>
Engi	ne start sequence:	
Action	START	Press the START - STOP button $5$
Delay	Preglow time	If diesel start logic is selected the relay will energize the glow
Delay	region unic	plugs for the time configured in the engine parameters (page 73)
Operation	Fuel relay	The fuel relay (relay 5) is energized to enable the fuel solenoid
Operation	Crank relay	The crank relay (relay 6) is energized to engage the starter –
		LED $^{12}$ illuminates and LED $^{13}$ starts flashing when generator
		speed has been detected
Delay	Engine delay time	The control unit waits for the engine monitoring delay time confi-
		gured in the engine parameters (page 74) to expire – LED $(13)$
		changes to steady illumination after the time expires
GC	B close sequence:	
Action	Breaker control	Press the BREAKER CONTROL button 4
Operation	Close GCB	The GCB close relay (relay 2) energizes to close the GCB –
		LED <sup>(11)</sup> illuminates
GC	B open sequence:	
Action	Breaker control	Press the BREAKER CONTROL button 4
Operation	Open GCB	The GCB close relay (relay 2) de-energizes to open the GCB –
		LED <sup>(11)</sup> goes out
Stop se	quence via START - STOP:	
Action	STOP	Press the START - STOP button <sup>5</sup>
Operation	Open GCB	The GCB close relay (relay 2) de-energizes to open the GCB –
		LED <sup>(1)</sup> goes out
Operation	Engine stop	The engine stops – LEDs $^{(2)}$ and $^{(3)}$ go out
Stop seque	ence via STOP one time:	
Action	STOP	Press the STOP button <sup>6</sup> once
Operation	Open GCB	The GCB close relay (relay 2) de-energizes to open the GCB –
		LED <sup>(1)</sup> goes out
Delay	Cool down time	The control unit waits for the cool down time configured in the
		engine parameters (page 74) to expire
Operation	Engine stop	The engine stops – LEDs $(12)$ and $(13)$ go out
Stop sec	quence via STOP two	
	times:	
Action	STOP	Press the STOP button <sup>6</sup> twice
Operation	Open GCB	The GCB close relay (relay 2) de-energizes to open the GCB –
Operation	Engine ston	The angine stops $I EDs \frac{12}{13}$ and $\frac{13}{13}$ go out
Speration	2. one stop	rne engine stops – LEDs 🥌 and 🐸 go out

## **Operating Mode AUTOMATIC**



In the AUTOMATIC operating mode, all engine, GCB, and/or MCB functions are operated via the discrete inputs or automatically by the control unit (i.e. a mains failure). The function of the easY-gen depends on the configuration of the unit and how the external signals are used. LED <sup>(15)</sup>, in the upper left corner of the AUTO - MANUAL button <sup>(3)</sup>, indicates the automatic operating mode.

### Detailed operation with 2 CBs in automatic mode (mains are present) - [350], [350X]

Preconditions:	•	Generator is stopped – LED	12	is not illuminated
----------------	---	----------------------------	----	--------------------

- MCB is closed LED (10) is illuminated
- Mains are present LED  $\bigcirc$  is illuminated
- Unit is in automatic mode LED (15) is illuminated

Start	sequence:
-------	-----------

Action	Remote start	Discrete input DI3 (remote start) is activated (active HIGH signal) at terminal 18
Delay	Preglow time	If diesel start logic is selected the relay will energize the glow plugs for the time configured in the engine parameters (page 73)
Operation	Fuel relay	The fuel relay (relay 5) is energized to enable the fuel solenoid
Operation	Crank relay	The crank relay (relay 6) is energized to engage the starter – LED $(12)$ il-
		luminates and LED <sup>13</sup> starts flashing when generator speed has been detected
Delay	Engine delay time	The control unit waits for the engine monitoring delay time configured
		in the engine parameters (page 74) to expire – LED <sup>(13)</sup> changes to steady illumination after the time expires
Operation	Open MCB	The MCB open relay (relay 1) energizes to open the MCB – LED $(10)$ goes out
Delay	Breaker delay	The control unit waits for the breaker transfer time configured in the breaker parameters (page 75) to expire
Operation	Close GCB	The GCB close relay (relay 2) energizes to close the GCB – LED <sup>(1)</sup> il- luminates
Sto	p sequence:	
Action	Remote stop	Discrete input DI3 (remote start) is deactivated (active LOW signal) at terminal 18
Operation	Open GCB	The GCB close relay (relay 2) de-energizes to open the GCB – LED $(1)$ goes out
Delay	Breaker delay	The control unit waits for the breaker transfer time configured in the
•	·	breaker parameters (page 75) to expire
Operation	Close MCB	The MCB open relay (relay 1) de-energizes to close the MCB –
		LED <sup>10</sup> illuminates
Delay	Cool down time	The control unit waits for the cool down time configured in the engine parameters (page 74) to expire
Operation	Engine stop	The engine stops – LEDs $^{(12)}$ and $^{(13)}$ go out

### Detailed operation with 2 CBs in automatic mode (mains are not present) - [350], [350X]

	<b>Preconditions:</b>	• Generator is stopped – LED $\frac{12}{12}$ is not illuminated
		• MCB is closed – LED $(10)$ is illuminated
		• Mains are not present – LED $\bigcirc$ is not illuminated
		• Unit is in automatic mode – LED $\frac{15}{15}$ is illuminated
Sta	rt sequence:	
Action	Remote start	Discrete input DI3 (remote start) is activated (active HIGH signal) at terminal 18
Delay	Preglow time	If diesel start logic is selected the relay will energize the glow plugs for the time configured in the engine parameters (page 73)
Operation	Fuel relay	The fuel relay (relay 5) is energized to enable the fuel solenoid
Operation	Crank relay	The crank relay (relay 6) is energized to engage the starter – LED $(12)$ illuminates and LED $(13)$ starts flashing when generator speed has been
		detected
Delay	Engine delay time	The control unit waits for the engine monitoring delay time configured
		in the engine parameters (page 74) to expire – LED <sup>(13)</sup> changes to steady illumination after the time expires
Operation	Open MCB	The MCB open relay (relay 1) energizes to open the MCB – LED $\frac{10}{10}$ goes out
Delay	Breaker delay	The control unit waits for the breaker transfer time configured in the breaker parameters (page 75) to expire
Operation	Close GCB	The GCB close relay (relay 2) energizes to close the GCB – LED $(1)$ illuminates
Sto	p sequence:	
Action	Remote stop	Discrete input DI3 (remote start) is deactivated (active LOW signal) at terminal 18
Operation	Open GCB	The GCB close relay (relay 2) de-energizes to open the GCB – LED $(1)$ goes out
Delay	Cool down time	The control unit waits for the cool down time configured in the engine parameters (page 74) to expire
Operation	Engine stop	The engine stops – LEDs $(2)$ and $(3)$ go out



# NOTE

The MCB described in the above text will only close if the mains return.

### AMF / Auto Mains Failure Operation - [350], [350X]

The operation sequence for an AMF operation is similar to the above sequence with the difference that a remote start signal is not required for the engine start and the engine monitoring delay time is not considered, i.e. the CBs are operated immediately. For an AMF operation in automatic mode the parameter Emergency power monitoring (page 75) must be configured to ON, no class F alarms may be present, the engine must be ready for operation, and the configured mains fail delay time (page 75) must expire to start the engine.

### Example for an AMF Operation:

### Initial situation:

- Mains are present
- Mains circuit breaker is closed
- The generator controller is in the automatic operation mode and emergency stand-by

### A mains failure occurs:

• Mains are not present

### Reaction of the unit:

- The mains failure is detected by the unit
- The period configured in the parameter "Mains fail delay time" expires
- The period configured in the parameter "Preglow time" expires
- The generator will be started
- The mains circuit breaker will be opened
- The time configured in the parameter "Transfer time GCBMCB" expires
- The generator circuit breaker will be closed
- The unit is in auto emergency power operation now

### The mains return:

- The return of the mains is detected by the unit
- The period configured in the parameter "Mains settling time" expires
- The generator circuit breaker will be opened
- The "Transfer time GCBMCB" and "Cool down time" timers start to run
- If the time configured in the parameter "Transfer time GCBMCB" expires, the MCB will be closed
- If the time configured in the parameter "Cool down time" expires, the generator/engine will be shut down
- The unit is back in emergency stand-by



# Detailed operation with 1 CB in Automatic mode

	Preconditions:	• Generator is stopped – LED $(12)$ is not illuminated
		• Unit is in Automatic mode – LED 15 is illuminated
Sta	rt sequence:	
Action	Remote start	Discrete input DI3 (remote start) is activated (active HIGH signal) at terminal 18
Delay	Preglow time	If diesel start logic is selected the relay will energize the glow plugs for the time configured in the engine parameters (page 73)
Operation	Fuel relay	The fuel relay (relay 5) is energized to enable the fuel solenoid
Operation	Crank relay	The crank relay (relay 6) is energized to engage the starter $-$ LED $(2)$ il-
		luminates and LED <sup>(13)</sup> starts flashing when generator speed has been detected
Delay	Engine delay time	The control unit waits for the engine monitoring delay time configured in the engine parameters (page 74) to expire – LED $(13)$ changes to steady illumination after the time expires
Operation	Close GCB	The GCB close relay (relay 2) energizes to close the GCB – LED $(1)$ illuminates
Sto	p sequence:	
Action	Remote stop	Discrete input DI3 (remote start) is deactivated (active LOW signal) at terminal 18
Operation	Open GCB	The GCB close relay (relay 2) de-energizes to open the GCB – LED $(1)$ goes out
Delay	Cool down time	The control unit waits for the cool down time configured in the engine parameters (page 74) to expire
Operation	Engine stop	The engine stops – LEDs $(2)$ and $(3)$ go out

# **Breaker Closure Limits**

### 

### **Generator Circuit Breaker**

The easYgen-300 series has fixed breaker closure limits which prevent the GCB closure if the generator voltage and/or frequency is/are not within these limits. These limits depend on the parameters rated system frequency and rated generator voltage (refer to Measuring on page 71) and cannot be changed. The limits are set as follows:

f<sub>generator</sub> must be within f<sub>rated system</sub> +/- 10 % Examples: If the rated system frequency is set to 50 Hz, the upper limit is at 55 Hz and the lower limit is at 45 Hz. If the rated system frequency is set to 60 Hz, the upper limit is at 66 Hz and the lower limit is at 54 Hz.

V<sub>generator</sub> must be within V<sub>rated generator</sub> +/- 10 % Examples:

If the rated generator voltage is set to 400 V, the upper limit is at 440 V and the lower limit is at 360 V. If the rated generator voltage is set to 120 V, the upper limit is at 108 V and the lower limit is at 132 V.

If the generator voltage and/or frequency is/are not within these limits, the generator LED (12) is flashing and the GCB cannot be closed.

If the generator voltage and frequency are within these limits, the generator LED (2) is permanently on and the GCB may be closed.

### Mains Circuit Breaker

The easYgen-350 and 350X have flexible breaker closure limits which prevent the MCB closure if the mains voltage and/or frequency is/are not within the mains failure limits.

These limits depend on the parameters rated system frequency and rated mains voltage and can be freely configured (refer to Monitoring: Mains Failure Limits on page 80 for details).

The conditions for closing the MCB are specified as follows and all conditions must be fulfilled:

- The mains voltage is present.
- The mains settling time (refer to Emergency Power (AMF) on page 75) has expired.
- NONE of the following alarms is present:
  - Mains over/underfrequency
  - Mains over/undervoltage
  - Mains rotation field alarm

If the mains voltage is present, but the voltage and/or frequency is/are not within these limits, the mains LED (9) is flashing, and the MCB cannot be closed.

If the mains voltage and frequency are within these limits, and the mains settling time has expired, the mains LED (9) is illuminated permanently, and the MCB may be closed.

The mains LED 9 is off, if the phase-neutral measuring voltage is below 10V.

# **Functional Description of the Oil Pressure Input DI1**

#### 

The easYgen-300 series is provided with an input for oil pressure. The function of this discrete input is described in the following.



Figure 8-2: Discrete input DI1 - oil pressure

Terminal	Description	A <sub>max</sub>
15	DI1 oil pressure common	2.5 mm <sup>2</sup>
16	DI1 oil pressure signal	2.5 mm <sup>2</sup>

Table 8-1: Discrete input DI1 - oil pressure

The oil pressure switch is connected to the terminals 15 (common) and 16 (DI1 signal) on the easYgen-300. The oil pressure switch (OPS) must be a N.C. contact. If the oil pressure is below the minimum required pressure, the contacts need to close. If the oil pressure is above the minimum required pressure, the contacts need to be open. The oil pressure is only monitored if the easYgen detects speed/frequency from the genset. If the genset is in a stand-by or stop mode, the oil pressure switch is disabled.

### Parameter "Crank termination by DI1"

If the parameter "Crank termination by DI1" is enabled, the oil pressure can be used to terminate the starting system for the engine. 2 seconds after oil pressure is detected, the crank relay will be disabled. The delay ensures that the crank relay is not disabled prior to the engine reaching firing speed.

### Parameter "Starter time"

In all other applications, the starter is active only for the time configured in the parameter "Starter time".

The following diagram shows the starting procedure as a function of time.



Figure 8-3: Starting procedure

# Firing Speed Detection and Crank Termination

### 

The firing speed is used for crank termination if the parameter "Crank termination by DI1" is not enabled (refer to Parameter "Crank termination by DI1" on page 61 if this parameter is enabled). When "Crank termination by DI1" is disabled, the firing speed is determined by the generator frequency or is calculated from the nominal speed and the rated system frequency. The control unit shows the following behavior:

### Case 1:

Firing speed is reached if a minimum generator frequency of 15 Hz is detected. The easYgen versions [320] and [350] operate in this manner. It is possible for the easYgen versions [320X] and [350X] to also operate in this manner if the parameter "Speed pickup" is disabled.

### Case 2:

Firing speed is reached if the calculated firing speed is detected via an MPU. The easYgen versions [320X] and [350X] must have the parameter "Speed pickup" enabled to operate in this manner.

The firing speed is calculated according to the following formula: Firing Speed = -

Rated System Frequency \* 15 Hz

Example: If the nominal speed is 1,500 rpm and the rated system frequency is 50 Hz, the firing speed will be (1,500 rpm / 50 Hz) \* 15 Hz = 450 rpm. The crank will be terminated if the calculated speed exceeds 450 rpm.

# Functional Description of the Charging Alternator Input/Output

The easYgen-300 series monitors the charging alternator operation with the following functionality.

In some cases the alternator itself needs auxiliary excitation from an auxiliary DC source to build up its terminal voltage during start-up. For this, the battery will be connected into the alternator excitation windings during the engine start-up. This ensures that the alternator will be self-excitated and provides voltage for charging the battery after the start-up sequence.

The easYgen provides two features:

1. Auxiliary excitation for the alternator

2. Continuous monitoring of the alternator terminal voltage

If the engine is started, the easYgen's internal electronic switch is closed simultaneously with the crank relay output, and the battery voltage is applied to the exciter winding D+ through the internal switch contacts by terminal 3 (for 24V systems) or terminal 4 (for 12V systems). This pre-excites the charging alternator so that voltage is generated. The internal switch will disconnect the alternator excitation winding from the battery after the engine has started properly and the crank relay output has been de-energized to terminate the crank cycle. Now, the engine is driving the charging alternator, which is charging the battery through the alternator terminal 3 (for 24V systems or terminal 4 for 12V systems) now acts as the charging alternator input for monitoring the charging voltage.

If the voltage on terminal 3 or 4 falls below a defined limit, the easYgen will initiate an "alternator charge failure" alarm.

The terminals 3 and 4 for alternator excitation act as individual resistors for 12 or 24Vdc alternators for current limiting against short circuit conditions due to the low impedance of the excitation winding.



Figure 8-4: Charging alternator input/output



### NOTE

The charging alternator D+ acts as an output for pre-exciting the charging alternator during engine start-up only. During regular operation, it acts as an input for monitoring the charging voltage.

# Functional Description of the 2<sup>nd</sup> CB Close Delay Time

### 

The easYgen-300 series provides Delayed close GCB and Delayed close MCB (only [350], [350X]) signals in the list of configurable parameters (find more details about this under Relay Outputs on page 92) in order to meet the requirements of some special circuit breaker types which require an Enable CB Close signal before the actual CB close signal. The function of these signals is described in the following text.

If those CBs are utilized, they require two Close CB signals with a time delay in between from two different relays. This can be achieved by selecting Delayed close GCB (MCB) from the list of configurable parameters for a freely configurable relay (relay 3 or 4). The delay time can be configured with the parameter 2nd GCB (MCB) Close Delay Time. If the user initiates the command Close GCB (MCB), the signal is immediately issued from the fixed relay (relay2 for GCB or relay 1 for MCB) assigned to give the close command. After the configured delay time has expired, the second Close GCB (MCB) signal is issued. The user configures the delay time for the second close command at the relay output.

### **Example for the functionality:**

Assumption: The close GCB signal is to be issued parallel on a second relay with a delay. Relay 4 shall be used in this example for this. The parameter "Relay 4" has to be configured to "Delayed close GCB" from the list of configurable parameters (refer to Relay Outputs on page 92). The delay time may be configured with the parameter "2nd GCB close delay time" (refer to Application on page 72). A period of 2 seconds shall be configured for this example.

If the user triggers the command "Close GCB" now, the following sequence will be performed:

The signal "Close GCB" energizes the relay firmly assigned to it (relay 2) immediately. After the configured delay has expired, the signal "Close GCB" energizes the relay assigned by the user (relay 4 in this example) with the configured delay.



The delay "t" corresponds with the values of the parameters "2nd GCB close delay time" and "2nd MCB close delay time".

If the respective circuit breaker is opened, both relays return to their initial state.

# 

This functionality can only be configured using LeoPC1.

# Functional Description of the Engine Released Signal

The easYgen-300 series provides the engine released signal in the list of configurable parameters (find more details about this under Relay Outputs on page 92). It is possible to use this signal for some special applications. Its functionality is described in the following for an emergency power supply.

Emergency power supply systems often require that all external system components (i.e. governors, etc.) except the genset control be disconnected from the battery power supply and that the battery is not loaded unnecessarily during engine downtime. This means that the external components shall only be connected with battery power, if the engine is operating.

To achieve this, a genset control signal is required, which connects the external components to the battery, as soon as the engine is started. This can be accomplished using the engine released signal when configuring a relay (relay 3 [350], [350X] or 4) to initiate this signal. The functionality is described in the following text with relay 4.



Figure 8-5: AMF application with engine released signal

The following functionality depends on the setting of the fuel relay (page 73):

### Fuel relay configured as operating solenoid:

The easYgen detects the mains loss and initiates the engine start. Relay 4 (configured to engine released) and relay 5 (fuel relay) are energized. The fuel relay provides the fuel supply to the engine. Relay 4 closes the contact K1 and connects the battery power to the external components that they are ready for operation. This ensures that these external components are not energized until they are needed.

### Fuel relay configured as stop solenoid:

The easYgen detects the mains loss and initiates the engine start. Relay 4 (configured to engine released) is energized. Relay 4 closes the contact K1 and connects the battery power to the external components that are needed for operation. This ensures that these external components are not energized if they are not used. If the engine is stopped, relay 5 (fuel relay) will be energized, cutting off the fuel supply.



### NOTE

It is not recommended to use the fuel relay signal for connecting the external equipment with the battery since this signal drops in amplitude with every possible start pause in contrast to the engine released signal.

# Chapter 9. Configuration

# **Restoring Default Values**

The easYgen can be reset to factory settings easily. This may be comfortable for configuring the easYgen from a known state.

# i

NOTE

The unit has to be in Operating Mode STOP (page 51) to load the default values.

# **Resetting Via the Front Panel**

Preconditions for loading the default values:

- Unit must be in operation mode STOP LED <sup>(17)</sup> is illuminated
- The engine must be stopped LED (13) is not illuminated
- No generator voltage may be present LED <sup>(12)</sup> is not illuminated

Press and hold the UP 1, ALARM 2, and STOP 2 buttons simultaneously for at least 10 seconds to reset the values. The factory default values have been restored when all the LEDs flash briefly,.

# **Resetting Via LeoPC1**

Precondition for loading the default values:

• Unit has to be in operation mode STOP – LED  $\frac{17}{17}$  is illuminated

Connect the easYgen with your PC and start LeoPC1 as described in Configuration Using the PC on page 67. Set the parameter Factory settings to YES. Set the parameter Set default values to YES. Now, the default values are loaded.

# **Configuration Via the Front Panel**

Operating the control unit via the front panel is explained in Configuring the easYgen on page 36. Familiarize yourself with the unit, the buttons' meaning/function, and the display monitoring using this section. The display of the parameters via the front panel and the display of the parameters via the computer program LeoPC1 will differ.



### NOTE

Not all parameters may be accessed or changed when configuring the control unit via the front panel. To properly commission a control unit, LeoPC1 v3.1xxx or higher and a DPC cable (P/N 5417-557) are required.

# **Configuration Using the PC**

### 



### CAUTION

For the configuration of the unit via the PC please use the LeoPC1 software with the following software version:

### LeoPC1 3.1 or higher



# NOTE

Please note that configuration using the direct configuration cable DPC (product number 5417-557) is possible starting with <u>revision B of the DPC</u> (first delivered July 2003). If you have an older model please contact our sales department.

For configuration of the unit via PC program please proceed as follows:

- Install the LeoPC1 program on your notebook/PC according to the provided user manual 37146. Consider the options that are given during the installation.
- Prior to the completion of the installation you will be prompted to select the language with which you want to start the PC program. The language of LeoPC1 may be changed at any time. The selection of the language refers only to language with which the menus and subprograms that LeoPC1 program works with. This setting will not change the configured language of the control unit.
- After the installation of LeoPC1 has been completed it is necessary to reboot your notebook/PC.
- Establish a connection between your notebook/PC and the control unit via the DPC cable. Insert the RJ45 plug into the RJ45 port on the control unit (see DPC Direct Configuration Cable on page 32 for details) and the serial cable to the COM1 port of your notebook/PC.
- You can now start the PC program as follows:
  by "Start/Program/Woodward/LeoPC1" (version 3.1 or higher) and opening the respective cfg file, or
  by a double click on the respective file ending ".cfg" in the subdirectory "/LeoPC1".
  The cfg files differ in their language used. Use the file on the enclosed floppy disk with the language you want, i.e. US for US English or DE for German.
- After the LeoPC1 program has started, establish communication by pressing the F2 button or selecting Communication -> Connect from the menu. This will establish a data link between the control unit and the note-book/PC.
- Start the configuration routine pressing the F3 button or selecting Devices -> Parameterize from the menu and adjust the parameter of the unit to your application using this manual.



# NOTE

You find detailed information about LeoPC1 and the utilization of the software in the user manual 37146 belonging to it.



# NOTE

The connection cables delivered with the DPC must be used to connect it to ensure a proper function of the easYgen. An extension or utilization of different cable types for the connection between easYgen and DPC may result in a malfunction of the easYgen. This may further result in damage to components of the system. If an extension of the data connection line is required, only the serial cable between DPC and notebook/PC may be extended.



### NOTE

Unplug the DPC after configuration to ensure a safe operation! If the DPC remains plugged into the easYgen-300 unit, a safe operation of the unit can not be guaranteed.

# **Editing the Configuration File**

### 

If you want to edit the configuration file in order to inhibit resetting the counters, you have to proceed as follows:

### Open the configuration file in a text editor

In order to edit the configuration file, open the respective \*.asm file in the "Tools" subdirectory of your LeoPC1 installation path with a text editor like Microsoft Notepad. An example of a name (depending on unit and software version) for a configuration file is:

8440-1701\_NEW\_EASYGEN350X\_x20002\_pDirUS.asm

### Delete the lines which are used to display the counter entries in the LeoPC1 configuration

The lines to be deleted in the \*.asm file are:

;!K <b> <color=EE0000> --CONFIG.COUNTERS---</b> %TAB 0,0,0,H'03;!z2550,"> Maintenance hours","0000h",1.0,0,9999 %TAB 0,0,0,H'03;!M2562,"> reset maintenance period h",H'FFFF,2,"No","Yes" %TAB 0,0,0,H'03;!I2515,"> Counter value preset","000000000",1.0 %TAB 0,0,0,H'03;!M2554,"> Set operation hours",H'FFFF,2,"No","Yes" %TAB 0,0,0,H'03;!Z254,"> Number of starts","00000",1.0,0,65535

### Store the modified file

Store the modified configuration file back to the "Tools" subdirectory of your LeoPC1 installation path under the same file name.

If you load the modified file in LeoPC1 now, the deleted lines will not be displayed in the configuration menu anymore.

# **Configuring the Flags**

The easYgen-300 series provides four configurable LED flags in the alphanumerical display to indicate alarms. One or more alarm messages can be assigned to each one of these flags (i.e. the respective flag will be illuminated if the configured alarm state(s) occur(s) in addition to the regular alarm indication). A detailed description of these flags can be found in the chapter Alarm Messages on page 41. The configuration parameter is described in detail under Flags on page 97. The flags may only be configured using LeoPC1.



Figure 9-1: Configurable display flags

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The flag parameters are displayed in LeoPC1 (refer to Configuration Using the PC on page 67 and the LeoPC1 user manual 37146 for more information) under System – Codes like shown in Figure 9-2 in default state (alarm "Start fail" is assigned to flag 1). The parameter with the name "Flag 1 Start fail" has the value "Yes", i.e. the alarm "Start fail" is assigned to flag 1.

Please select device:				Close
Generator 1 - 8440_1701_NEW_1			•	Help
Name	Value	Rights		Input
Level of display	00	RW		
Flag1 Gen.overfreq. 1	No	RW		
Flag1 Gen.underfreg. 1	No	RW		
Flag1 Gen.overvolt.1	No	RW		Marked rows
Flag1 Gen.undervolt. 1	No	RW		mancarons
Flag1 Mains phase rot. misw.	No	RW		Doed ell
Flag1 Overspeed 1	No	RW		
Flag1 Underspeed 1	No	RW		
Flag1 Unintended stop	No	RW		Print
Flag1 Start fail	Yes	RW		
Flag1 Mainten. hours exceeded	No	RW		
Flag1 CAN-Fault J1939	No	RW		
Flag1 Charge AlternatorLow Volt.	No	RW		
▶ Flag1 Batt.undervolt.1	No	RW		
Flag1 DI 1	No	RW		
Flag1 DI 2	No	RW		-
Flag1 DI 3	No	RW		Save
> Flag1 DI 4	No	RW	_	
> Flag1 DI 5	No	RW	-	

Figure 9-2: Flag configuration default

You may assign as many alarms as required to one flag using LeoPC1. Just mark the respective entry and press Input to configure the alarm assignment or double-click the entry for configuration. The example in Figure 9-3 shows that the alarms "Unintended stop" and "Start fail" are assigned to flag 1, i.e. the flag is illuminated (flashing) if at least one of these alarms is present.

rlease select device:				Close
Generator 1 - 8440_1701_NEW_1			-	Help
Name	Value	Rights		Input
Level of display	00	RW		
> Flag1 Gen.overfreq. 1	No	RW		
> Flag1 Gen.underfreq. 1	No	RW		
> Flag1 Gen.overvolt. 1	No	RW		Marked rows
> Flag1 Gen.undervolt. 1	No	RW		
> Flag1 Mains phase rot. misw.	No	RW		Read all
> Flag1 Overspeed 1	No	RW		
> Flag1 Underspeed 1	No	RW		Drive
> Flag1 Unintended stop	Yes	RW		Print
> Flag1 Start fail	Yes	RW		
> Flag1 Mainten. hours exceeded	No	RW		
> Flag1 CAN-Fault J1939	No	RW		
> Flag1 Charge AlternatorLow Volt.	No	RW		
> Flag1 Batt.undervolt.1	No	RW		
> Flag1 DI 1	No	RW		
> Flag1 DI 2	No	RW		Course
> Flag1 DI 3	No	RW		Save
> Flag1 DI 4	No	RW		
> Flag1 DI 5	No	RW	-	

Figure 9-3: Flag configuration custom

# Chapter 10. Parameters

The following description of parameters is expanded to include all parameters that are accessible through LeoPC1. Not all parameters are accessible via the front panel. Most of the parameters, which are accessible via the front panel are password protected and are only accessible after entering a password.



# Measuring

### 

EN	R	ated syst	tem free	quency	Rated system frequency	50/60 Hz
80 10 3	Ne [320] ✓	ennfreque [320X] ✓	enz im \$ [350] ✔	System [350X] ✓	The rated frequency of the system has to be c The generator frequency monitoring as well a value configured in this parameter.	onfigured here. as the mains failure limits refer to the
EN	R	ated volt	age gel	nerator	Rated generator voltage	50 to 480 V
DE	Ner	nnspannı	ung Gel	nerator		
11 3	[320]	[320X]	[350] ✓	[350X]	The rated voltage of the generator has to be of The generator voltage monitoring refers to the	onfigured here. e value configured in this parameter.
EN		Rated	voltage	mains	Rated mains voltage	50 to 480 V
DE		Nenns	pannur	ng Netz		
12 3	[320] 	[320X]	[350] ✓	[350X]	The rated voltage of the mains has to be confi The mains failure limits refer to the value con	igured here. ffigured in this parameter.
EN	Genera	ator volta	ige mea	asuring	Generator voltage measurement	3Ph 4W / 3Ph 3W / 1Ph 2W / 1Ph 3W
E DE	Gei [320] ✓	n. Spann [320X] ✓	ungsme [350] ✓	essung [350X] ✓	The method of voltage measurement for the g 1Ph 2W and cannot be changed for the easYg A detailed description of the different measur Voltage Measuring on page 22.	generator. This parameter is set to gens [320] and [350].
EN	Ma	ains volta	ige mea	asuring	Mains voltage measurement	3Ph 4W / 3Ph 3W / 1Ph 2W / 1Ph 3W
EQ  L	Ne: [320]	tz Spann [320X] 	ungsme [350] ✔	essung [350X] ✓	The measurement principle for the mains. The cannot be changed for [350].	is parameter is set to 3Ph 4W and

A detailed description of the different measurement methods can be found in Voltage Measuring on page 22.



# NOTE

The correct configuration of these parameters is essential for a proper operation of the control unit.

# Application

### 

EN	Ignore CB reply			Ignore CB reply	YES/N
DE	Ignoriere	Rückmeld	lung LS		
 L	[320] [320X	[350]	[350X]	This parameter controls the function of the discrete inputs DI4 and DI5.	
-				YES The discrete inputs DI4 and DI5 are freely configurable. T rameters of the discrete inputs can be accessed and config via LeoPC1.	The pa- ured
				NO The discrete inputs DI4 and DI5 operate as reply inputs for mains (DI4) or generator (DI5) circuit breaker. The param of the discrete inputs can be accessed via LeoPC1 but can changed.	or the neters not be



# CAUTION

The customer must ensure that a mechanical interlock for the circuit breakers exists for the case that the parameter "Ignore CB reply" is configured to "YES".

E	2nd GCB close Delay time			2nd GCB close delay time	0.00 to 650.00
E L	Verz.Zeit zweiten GLS schließen [320] [320X] [350] [350X] ✓ ✓ ✓ ✓ ✓		hließen [350X] ✓	This parameter controls the delay for the $2^{nd}$ GCB close signal. The application and behavior of this signal is described under Functional Description of the 2nd CB Close Delay Time on page 63.	
EN	2nd MCB close Delay time			2nd MCB close delay time	0.00 to 650.00
DE	Ver. Zeit zweiten NLS schließen				
 L	[320] [320X]	[350] ✓	[350X]	This parameter controls the delay for the 2 <sup>nd</sup> MCB close tion and behavior of this signal is described under Fund the 2nd CB Close Delay Time on page 63.	se signal. The applica- ctional Description of
# Engine

#### 

### **Engine: Diesel**

EN	Fuel relay: close to stop			to stop	Fuel relay	close to stop / open to stop
20 3	Kraft [320] ✓	stoffmag [320X] ✓	net: Sto [350] ✓	opmag. [350X] ✓	<ul> <li>close to stop . To stop the engine the stop longer detected, the stop sfigured by parameter "Timopen to stop . Before the starting sequence energized. To stop the energized.</li> </ul>	op solenoid is energized. Once speed is no solenoid remains closed for the time con- me of motor stop". nce is initiated, the operating solenoid is gine the operating solenoid is de-
E			Preglo	w time	Preglow time	0 to 300 s
21       [320]       [350]       [350]       [350]         3       ✓       ✓       ✓       ✓		s preglowed for this time (if a "0" has been ed without preglow).				

### Engine: Pickup

EN			Speed	pickup	Speed pick-up	ON/OFF
DE				Pickup		
30	[320]	[320X]	[350]	[350X]	ONSpeed monitoring of the engine is performed using an MF	PU.
3				✓	OFFSpeed/frequency monitoring of the generator/engine is ca	rried out
					by measuring the frequency of the generator. There is no	MPU
					wired to this unit.	

EN		/	Iominal	speed	Nomina	l speed	500 to 4,000 RPM	
DE			Nenndı	rehzahl				
31	[320] [320X] [350] [350X]		[350X]	Revolu	olutions per minute of the engine at rated engine speed.			
3		1		1				
Zi	Number of gear teeth		ar teeth	Number	of gear teeth	5 to 260		
DE			Zähne	anzahl				
32	[320] [320X] [350] [350X]		Number of pulses per revolution.					
3	🗸 🗸							
-					Note:	If the number of gear teeth is not correct, the speed w	ill not be calculated	

: If the number of gear teeth is not correct, the speed will not be calculated correctly and this will lead to a speed/frequency mismatch alarm.

## Engine: Start/Stop Automatic

E _			Start	er time	Starter time	1 to 10 s
DE		Einrüc	kzeit Al	nlasser		
 L	[320]	[320X]	[350]	[350X]	The maximum time during which the crank relay remains enabled. The lay de-energizes when the engine reaches ignition speed or the configur expires.	starter re- ed time
E		Sta	art pau:	se time	Start pause time	10 to 99 s
DE		S	tartpau	senzeit		
 L	[320]	[320X]	[350] ✓	[350X]	Time between the individual starting attempts. (This time is used to pro starter relay.)	tect the
EN	Cool down time			vn time	Cool down time	0 to 999 s
DE		Moto	r Nach	laufzeit	·	
40 3	[320]	[320X]	[350]	[350X]	<b>Regular stop:</b> If the engine performs a normal stop or changed into the operation mode, a cool down with an opened GCB is carried out. This t justable.	STOP ime is ad-
					<b>Stop by an alarm of class F:</b> If a class F alarm is detected, the GCB we immediately and the engine will shutdown without a cool down.	ill open
E		Time	of mot	or stop	Time of motor stop	0 to 99 s
ם  L	[320] ✓	Zeit [320X] ✓	für Mo [350] ✓	torstop [350X] ✓	During this time a restart of the engine is blocked. This time should be configure the engine is totally shut down and protection of the engine start circuit is provid speed from the engine is no longer detected the time configured by this paramete itiated. If the fuel relay logic is configured to "close to stop", the "close to stop" be energized and stays energized until this timer has expired.	ed so that led. Once er is in- Relay will
۲ ۲	Cr	ank term	ination	by DI1	Crank termination by DI1	YES/NO
DB	Anlass	er aussp	ouren ül	ber DI1	XTEC The station of the line o	••
L	[320] ✓	[320X]	[350] ✓	[350X]	<ul> <li><b>NO</b></li></ul>	etected (re- ed is the dis-
E E	Er	ngine mo	nit. dela	ay time	Engine monitoring delay time	1 to 99 s
 L	[320]	Moto [320X] ✓	[350] √	gerung [350X] ✓	The engine monitoring is delayed to prevent initiating an alarm while the tor set is starting. The easYgen does not monitor under-voltage and –free and low oil pressure alarms until the delay time has expired.	ie genera- equency

\_\_\_\_\_

### **Breaker**

#### 

E	Tr	ansfer ti	ime GC	BMCB	Transfer time GCB/MCB	0.10 to 99.99 s
DE		Pasuer	nzeit Gl	LSNLS		
L	[320]	[320X] 	[350] ✓	[350X] ✓	Switching from generator supply to mains supply or from mains rator supply occurs automatically depending on the operating cor time between the reply "power circuit breaker is open" and a clos this parameter. This time applies for both directions. During this is dead.	supply to gene- nditions. The se-pulse is set by time the busbar

# **Emergency Power (AMF)**

#### 

EN				On/Off	Emergency power monitoring On/Off	<b>ON/OFF</b>
 L	[320]	[320X] 	[350] ✓	Ein/Aus [350X] ✓	<ul> <li>ONIf the unit is in operating mode AUTOMATIC and a raccording to the following parameters occurs, the engiand an automatic emergency operation is carried out.</li> <li>OFFNo emergency operation is carried out.</li> </ul>	nains fault ine is started
EN	Mains fail delay time			ay time	Mains fail delay time	0.20 to 99.99 s
DE		Sta	artverzö	gerung		
 L	[320]	[320X]	[350]	[350X]	The minimum period of time that the monitored mains must be dead terruption for the generator to start and carry out an emergency oper	without in- ation.
EN		Main	ns settlir	ng time	Mains settling time	0 to 9,999 s
DE		Netzbe	eruhigu	ngszeit		
80 3	$\begin{bmatrix} 320 \\ 3 \end{bmatrix} \begin{bmatrix} 320X \\ -1 \end{bmatrix} \begin{bmatrix} 350 \\ -1 \end{bmatrix} \begin{bmatrix} 350X \\ -1 \end{bmatrix} \begin{bmatrix} 3$				ble after they the time confi- onfigured lim- mains will	

### Password

#### 

EN	Password		ssword	HMI Password	0000 to 9999	
DE			Pa	asswort		
00 1	[320] ✓	[320X] ✓	[350] ✓	[350X]	The HMI password must be entered here to configure the control via panel. Once the password is entered, access to the configuration mem- lowed for two hours. A user may exit the configuration mode by allo- tered password to expire after two hours or by changing any one digi dom number generated on the password screen and entering it into the The default password is 0003. This parameter is only available from Software Version 2.0007 (refer Information on page 9 for more info).	the front us will be al- wing the en- t on the ran- le unit. r to Update

# NOTE The HMI password may be set with the parameter "Commissioning level code" (refer to Codes on page 96).

# Monitoring

#### 

E		Time u	ıntil hori	n reset	Time until horn reset	0 to 1,000 s
DE	Zeit bis Hupenreset					
01 1	Zeit bis Hupenreset [320] [320X] [350] [350X] $\checkmark$ $\checkmark$ $\checkmark$ $\checkmark$		The alarm LED flashes and the centralized alarm (horn) is issued when a new B to F class alarm is detected. After the delay time configured in "Time until horn reset" has expired, the flashing alarm LED changes to steady illumination and th centralized alarm (horn) is reset.		hen a new B he until horn nation and the	

If this parameter is configured to **0** the horn will never be set.

## Monitoring: Generator

Zi	Voltag	e monito	ring gel	nerator	Voltage monitoring generator	fixed to 4 phase
DE	Spg. Überwachung Generator					
	[320]	[320X]	[350]	[350X]	The line voltages are monitored for the setting 3Ph 3W. The star	voltages are
	1	~	1	✓	monitored for all other voltage systems.	

# Monitoring: Generator Overfrequency

EN			Mor	nitoring	Generator overfrequency monitoring	fixed to ON		
DE	[320] ✓	[320X]	Überwa [350] ✓	achung [350X] ✓	The generator overfrequency monitoring is always enabled and car abled.	nnot be dis-		
EN				Limit	Generator overfrequency limit	50.0 to 130.0 %		
8 50	[320]	[320X]	[350]	Limit [350X] ✓	① This value refers to the Rated system frequency (see page 71).			
U					The percentage threshold value that is to be monitored. If this value exceeded for at least the delay time, the action specified by the conclass is initiated.	e is reached or figured alarm		
E				Delay	Generator overfrequency delay	0.1 to 99.9 s		
51 3	[320] ✓	[320X]	Verzög [350] ✓	gerung [350X] ✓	If the monitored value exceeds the threshold value for the configur an alarm will be issued. If the monitored value falls below the three the hysteresis) before the delay expires, the delay will be reset.	ed delay time, shold (minus		
EN			Alarr	n class	Generator overfrequency alarm class	fixed to F		
DE	[320]	[320X]	Alarm [350] ✓	iklasse [350X] ✓	The generator overfrequency alarm class is set to "F" and cannot b	e changed.		
E		Self acknowledge		wledge	Generator overfrequency self acknowledgement	fixed to NO		
DE	[320]	Se [320X] ✓	lbstquit [350]	tierend [350X] ✓	The generator overfrequency self-acknowledgement is set to "NO" changed. The alarm will not automatically reset after the fault conc cleared.	and cannot be lition has		

# Monitoring: Generator Underfrequency

E			Мог	nitoring	<i>itoring</i> Generator underfrequency monitoring fixed to ON		
DE			Überwa	achung			
	[320] ✓	[320X]	[350] ✓	[350X]	The generator underfrequency monitoring is always enabled and c abled.	annot be dis-	
EN				Limit	Generator underfrequency limit	50.0 to 130.0 %	
DE				Limit			
52	[320]	[320X]	[350]	[350X]	(1) This value refers to the Rated system frequency (see page 71	).	
3	~	~	~	~	The percentage threshold value that is to be monitored. If this valu fallen below for at least the delay time, the action specified by the alarm class is initiated.	e is reached or configured	
EN				Delav	Generator underfrequency delay	0.1 to 99.9 s	
DE	Verzögerung						
53 3	[320]	[320X]	[350]	[350X]	If the monitored value exceeds the threshold value for the configu an alarm will be issued. If the monitored value falls below the thre the hysteresis) before the delay expires, the delay will be reset.	red delay time, eshold (minus	
R			Alarr	n class	Generator underfrequency alarm class	fixed to F	
DE			Alarm	nklasse			
	[320] ✓	[320X]	[350] ✓	[350X]	The generator underfrequency alarm class is set to "F" and cannot	be changed.	
EN		Seli	f ackno	wledae	Generator underfrequency self acknowledgement	fixed to NO	
DE		Se	Ibstquit	tierend			
	[320]	[320X]	[350]	[350X]	The generator underfrequency self-acknowledgement is set to "NO	O" and cannot	
	~	1	~	~	be changed. The alarm will not automatically reset after the fault c cleared.	condition has	
EN	De	laved bv	enaine	speed	Generator underfrequency delayed by engine speed	fixed to YES	
DE	Verzö	gert durc	h Moto	rdrehz.			
	[320]	[320X]	[350]	[350X]	The generator underfrequency delay by engine speed is set to "YE	S" and cannot	
	1	1	1	1	be changed. Monitoring is delayed by the time configured in Engi	ne monitoring	
					delay time on page /4 after starting the engine.		

# Monitoring: Generator Overvoltage

EN			Мо	nitoring	Generator overvoltage monitoring	fixed to ON	
DE	[320]	[320X]	Überwa [350] ✓	achung [350X] ✓	The generator overvoltage monitoring is always enabled and canno	ot be disabled.	
E				Limit	Generator overvoltage limit	50.0 to 125.0 %	
DE				Limit			
54	[320]	[320X]	[350]	[350X]	(1) This value refers to the Rated generator voltage (see page /1.)	)	
3	~	~	~	✓	The percentage threshold value that is to be monitored. If this value exceeded for at least the delay time, the action specified by the con class is initiated.	e is reached or figured alarm	
Z				Delay	Generator overvoltage delay	0.1 to 99.9 s	
DE	Verzögerung						
55 3	[320]	[320X]	[350]	[350X]	If the monitored value exceeds the threshold value for the configur an alarm will be issued. If the monitored value falls below the thres the hysteresis) before the delay expires, the delay will be reset.	ed delay time, shold (minus	
Zi			Alarr	n class	Generator overvoltage alarm class	fixed to F	
DE			Alarn	nklasse			
	[320]	[320X]	[350] ✓	[350X]	The generator overvoltage alarm class is set to "F" and cannot be c	hanged.	
EN		Sel	f ackno	wledge	Generator overvoltage self acknowledgement	fixed to NO	
DE		Se	lbstquit	tierend			
	[320]	[320X]	[350]	[350X]	The generator overvoltage self-acknowledgement is set to "NO" and changed. The alarm will not automatically reset after the fault cond cleared.	id cannot be lition has	
E	De	layed by	, engine	speed	Generator overvoltage delayed by engine speed	fixed to NO	
DE	Verzö	gert durc	ch Moto	rdrehz.			
	[320]	[320X]	[350] ✓	[350X]	The generator overvoltage delay by engine speed is set to "NO" and changed. The monitoring is not delayed by the time configured in H toring delay time on page 74 after starting the engine.	d cannot be Engine moni-	

# Monitoring: Generator Undervoltage

EN			Мог	nitoring	Generator undervoltage monitoring	fixed to ON
DE			Überwa	achung		
	[320] ✓	[320X]	[350] ✓	[350X]	The generator undervoltage monitoring is always enabled and car	nnot be disabled.
EN				Limit	Generator undervoltage limit	50.0 to 125.0 %
DE				Limit		. I
56	[320]	[320X]	[350]	[350X]	(1) This value refers to the Rated generator voltage (see page 7)	1.)
3	~	~	~	~	The percentage threshold value that is to be monitored. If this val fallen below for at least the delay time, the action specified by the alarm class is initiated.	ue is reached or e configured
EN				Delay	Generator undervoltage delay	0.1 to 99.9 s
DE			Verzö	gerung		
57 3	[320]	[320X]	[350]	[350X]	If the monitored value exceeds the threshold value for the configure an alarm will be issued. If the monitored value falls below the threshold the hysteresis before the delay expires, the delay will be reset.	red delay time, reshold (minus
Z			Alarr	n class	Generator undervoltage alarm class	fixed to F
DE			Alarm	nklasse		
	[320]	[320X]	[350] ✓	[350X]	The generator undervoltage alarm class is set to "F" and cannot be	e changed.
EN		Seli	f ackno	wledge	Generator undervoltage self acknowledgement	fixed to NO
DE		Se	lbstquit	tierend		
	[320]	[320X]	[350]	[350X]	The generator undervoltage self-acknowledgement is set to "NO"	and cannot be
	<b>V</b>		1	1	changed. The alarm will not automatically reset after the fault concleared.	ndition has
EN	De	layed by	engine	speed	Generator undervoltage delayed by engine speed	fixed to YES
DE	Verzö	gert durc	h Moto	rdrehz.		
	[320]	[320X]	[350]	[350X]	The generator undervoltage delay by engine speed is set to "YES	" and cannot be
	✓	~	1	~	changed. The monitoring is delayed by the time configured in En delay time on page 74 after starting the engine.	gine monitoring

EN			Мог	nitoring	Mains phase rotation monitoring	ON / OFF
е  L	[320]	[320X] 	Überwa [350] ✓	achung [350X] ✓	ON Phase rotation monitoring is carried out according to th parameters OFF Monitoring is disabled.	ne following
EN		Mains	phase r	rotation	Mains phase rotation direction	CW/CCW
DE			Netzd	lrehfeld		
 L	[320]	[320X] 	[350] ✓	[350X] ✓	<ul> <li>CW</li></ul>	V (clock- 2-Phase; de- CW (counter C-B-A-
EN				Delav	Mains phase rotation monitoring delay	fixed to 2 s
DE			Verzö	gerung	L 0 V	
	[320]	[320X]	[350]	[350X]	If a wrong phase rotation direction is detected for the configured dela alarm will be issued. This value is fixed to 2 seconds and cannot be changed.	ay time, an
EN			Alarr	n class	Mains phase rotation alarm class	fixed to B
DE			Alarm	nklasse		,
	[320]	[320X]	[350] ✓	[350X]	The mains phase rotation alarm class is set to "B" and cannot be char	nged.
Z		Sel	f ackno	wledge	Mains phase rotation self acknowledgement	YES / NO
DE		Se	lbstquit	tierend		. 1
87	[320]	[320X]	[350]	[350X]	YES The control will automatically clear the alarm if it is not	o longer va-
3			v	v	NO An automatic reset of the alarm does not occur. Reset of must be performed manually by pressing the appropria	of the alarm te buttons.
EN	De	layed by	engine	speed	Mains phase rotation delayed by engine speed	fixed to NO
DE	Verzö	gert durc	ch Moto	rdrehz.	The mains above actation delay her was in and it with "DAC" - 1	
	[320]	[320X]	[350] ✓	[350X]	changed. The monitoring is not delayed by the time configured in Entoring delay time on page 74 after starting the engine.	annot be gine moni-

### **Monitoring: Mains**

## Monitoring: Mains Failure Limits

E		High vol	tage thi	reshold	Emergency power: high voltage threshold	50.0 to 130.0 %
DE		Obere G	renzspa	annung		
81	[320]	[320X]	[350]	[350X]	① This value refers to the Rated mains voltage (see page 71).	
3			✓	✓		
					This value is referred to for mains failure recognition and mains e	estimation. If the

This value is referred to for mains failure recognition and mains estimation. If the monitored value exceeds the adjusted limit, this is recognized as a mains failure and an emergency power operation is initiated.

Z	Low voltage threshold	Emergency nower: low voltage threshold	50.0 to 130.0 %
		Emergency power, low voltage un eshold	2010 10 12010 70
82	[320] [320X] [350] [350X]	<ul><li>This value refers to the Rated mains voltage (see page 71).</li></ul>	1
3		This value is referred to for mains failure recognition and mains of monitored value exceeds the adjusted limit, this is recognized as and an emergency power operation is initiated.	estimation. If the a mains failure
A	Voltage hysteresis	Emergency power: voltage hysteresis	0.0 to 50.0 %
83	Spannungshysterese           [320]         [320X]         [350]         [350X]	(i) This value refers to the Rated mains voltage (see page 71).	
2		This value is referred to for mains failure recognition and mains of monitored value exceeds the adjusted limit, this is recognized as and an emergency power operation is initiated. If the monitored va- a configured limit and returns but remains close to the limit, the H be exceeded (on negative deviation monitoring) or fallen below (of monitoring) for the mains failure to be assessed as over. This mu- rupted for the mains settling time (see parameter on page 75). If to value returns to configured limits, the delay timer is reset to 0. Set	estimation. If the a mains failure value has passed hysteresis must on exceeding st occur uninter- the monitored ee Figure 10-1.
EN	High frequency threshold	Emergency power: high frequency threshold	70.0 to 160.0 %
四 84	Obere Grenzfrequenz           [320]         [320X]         [350]         [350X]	<ul><li>This value refers to the Rated system frequency (see page 7</li></ul>	1).
3		This value is referred to for mains failure recognition and mains of monitored value exceeds the adjusted limit, this is recognized as and an emergency power operation is initiated.	estimation. If the a mains failure
EN	Low frequency threshold	Emergency power: low frequency threshold	70.0 to 160.0 %
85 3	Untere Grenzfrequenz           [320]         [320X]         [350]         [350X]	<ul><li>This value refers to the Rated system frequency (see page 7</li></ul>	1).
5		This value is referred to for mains failure recognition and mains of monitored value exceeds the adjusted limit, this is recognized as	estimation. If the a mains failure

and an emergency power operation is initiated.

H		Freque	ncy hys	teresis	Emergency power: frequency hysteresis							0.0 to	50.0	%							
DE		Frequ	lenzhys	sterese																	-
86	[320]	[320X]	[350]	[350X]	1	This	s val	ue re	fers	to th	ne R	ate	d syst	tem frec	luency	(see p	bage '	71).			
3			~	1				c	1.	c			c ·1							TO	1

This value is referred to for mains failure recognition and mains estimation. If the monitored value exceeds the adjusted limit, this is recognized as a mains failure and an emergency power operation is initiated. If the monitored value has passed a configured limit and returns but remains close to the limit, the hysteresis must be exceeded (on negative deviation monitoring) or fallen below (on exceeding monitoring) for the mains failure to be assessed as over. This must occur uninterrupted for the mains settling time (see parameter on page 75). If the monitored value returns to configured limits, the delay timer is reset to 0. See Figure 10-1.



Figure 10-1: Voltage/frequency hysteresis

# Monitoring: Engine Overspeed

E			Mor	nitoring	Engine overspeed monitoring	ON / OFF
90 58 3	[320]	[320X]	Überwa [350] 	achung [350X] ✓	ONOverspeed monitoring of the engine speed is carried of to the following parameters. OFFNo monitoring is carried out.	out according
E				Limit	Engine overspeed limit 0	to 9,999 RPM
80 59 3	[320]	[320X]	[350]	Limit [350X] ✓	The threshold value is set by this parameter. If this value is reached for at least the delay time, the action specified by the configured ala itiated.	or exceeded rm class is in-
E				Delay	Engine overspeed delay	fixed to 0.1 s
DE	[320]	[320X]	Verzög [350]	gerung [350X] ✓	If the monitored value exceeds the threshold value for the configure an alarm will be issued. If the monitored value falls below the thresh the hysteresis) before the delay expires, the delay will be reset. This value is fixed to 0.1 seconds and cannot be changed.	ed delay time, hold (minus
EN			Alarn	n class	Engine overspeed alarm class	fixed to F
DE	[320] 	[320X]	Alarm [350] 	klasse [350X] ✓	The engine overspeed alarm class is set to "F" and cannot be change	ed.
E		Self	f acknow	vledge	Engine overspeed self acknowledgement	fixed to NO
DE	[320]	Se [320X] ✓	lbstquit [350] 	tierend [350X] ✓	The engine overspeed self-acknowledgement is set to "NO" and car changed. The alarm will not automatically reset after the fault condi- cleared.	nnot be ition has
E	De	layed by	engine	speed	Engine overspeed delayed by engine speed	fixed to NO
DE	Verzög [320]	gert durc [320X] ✓	h Motol [350]	rdrehz. [350X] ✓	The engine overspeed delay by engine speed is set to "NO" and can changed. The monitoring is not delayed by the time configured in E toring delay time on page 74 after starting the engine.	not be Ingine moni-

# Monitoring: Engine Underspeed

EN			Мог	nitoring	Engine underspeed monitoring fixed to (				
DE			Überwa	achung					
	[320] 	[320X]	[350] 	[350X]	The engine underspeed monitoring is always enabled and cann	ot be disabled.			
7									
台 				Limit	Engine underspeed limit	fixed to 1,000 RPM			
Ð				Limit	The threshold value is fixed in this peremeter. If this value is r	asshed or fallon be			
	[320]	[320X]	[350]	[350X]	low for at least the delay time, the action specified by the confi is initiated.	gured alarm class			
EN				Delay	Engine underspeed delay	fixed to 1.0 s			
DE			Verzö	gerung					
	[320]	[320X]	[350]	[350X]	If the monitored value falls below the threshold value for the c	onfigured delay			
		1		✓	time, an alarm will be issued				
					This value is fixed to 1.0 seconds and cannot be changed.				
EN			Alarr	n class	Engine underspeed alarm class	fixed to F			
DE EN			Alarr Alarr	n class Iklasse	Engine underspeed alarm class	fixed to F			
DE EN	[320]	[320X]	Alarr Alarr [350]	n class nklasse [350X]	Engine underspeed alarm class The engine underspeed alarm class is set to "F" and cannot be a	fixed to F			
DE EN	[320]	[320X]	Alarr Alarr [350]	n class nklasse [350X] ✓	Engine underspeed alarm class The engine underspeed alarm class is set to "F" and cannot be a	fixed to F			
DE EN	[320]	[320X]	Alarr Alarr [350]	n class oklasse [350X] ✓	Engine underspeed alarm class The engine underspeed alarm class is set to "F" and cannot be o	fixed to F			
EN DE EN	[320]	[320X] ✓	Alarr Alarr [350] 	n class hklasse [350X] ✓	Engine underspeed alarm class The engine underspeed alarm class is set to "F" and cannot be engine underspeed self acknowledgement	fixed to F changed. fixed to NO			
DE EN	[320]	[320X] ✓ Sel	Alarr Alarr [350]  f acknow	n class klasse [350X] ✓ wledge tierend	Engine underspeed alarm class The engine underspeed alarm class is set to "F" and cannot be a Engine underspeed self acknowledgement	fixed to F changed. fixed to NO			
DE EN	[320]	[320X] ✓ Sel Se [320X]	Alarr Alarr [350]  f acknoo lbstquit [350]	n class klasse [350X] $\checkmark$ wledge tierend [350X]	Engine underspeed alarm class         The engine underspeed alarm class is set to "F" and cannot be a         Engine underspeed self acknowledgement         The engine underspeed self-acknowledgement is set to "NO" a	fixed to F changed. fixed to NO nd cannot be			
DE EN	[320]  [320] 	[320X] ✓ Se/ Se [320X] ✓	Alarr Alarr [350]  f acknoo lbstquit [350]	n class oklasse [350X] ✓ wledge tierend [350X] ✓	Engine underspeed alarm class         The engine underspeed alarm class is set to "F" and cannot be a         Engine underspeed self acknowledgement         The engine underspeed self-acknowledgement is set to "NO" a changed. The alarm will not automatically reset after the fault of the set of the	fixed to F changed. fixed to NO nd cannot be condition has			
DE EN DE EN	[320]  [320] 	[320X] ✓ Sel Se [320X] ✓	Alarr Alarr [350]  f acknov Ibstquit [350] 	n class iklasse [350X] ✓ wledge tierend [350X] ✓	Engine underspeed alarm class         The engine underspeed alarm class is set to "F" and cannot be a         Engine underspeed self acknowledgement         The engine underspeed self-acknowledgement is set to "NO" a changed. The alarm will not automatically reset after the fault of cleared.	fixed to F changed. fixed to NO nd cannot be condition has			
N DE IN DE IN	[320]  [320] 	[320X] ✓ Se/ Se [320X] ✓	Alarr Alarr [350]  f acknoo lbstquit [350] 	n class aklasse [350X] ✓ wledge tierend [350X] ✓	Engine underspeed alarm class         The engine underspeed alarm class is set to "F" and cannot be a         Engine underspeed self acknowledgement         The engine underspeed self-acknowledgement is set to "NO" a changed. The alarm will not automatically reset after the fault of cleared.         Engine underspeed deleved by engine speed	fixed to F changed. fixed to NO nd cannot be condition has			
DE EN DE EN DE EN	[320]  [320]  Dee	[320X] ✓ Sel Se [320X] ✓	Alarr Alarr [350] f acknoo lbstquit [350]	n class aklasse [350X] ✓ wledge tierend [350X] ✓	Engine underspeed alarm class         The engine underspeed alarm class is set to "F" and cannot be a         Engine underspeed self acknowledgement         The engine underspeed self-acknowledgement is set to "NO" a         changed. The alarm will not automatically reset after the fault of cleared.         Engine underspeed delayed by engine speed	fixed to F changed. fixed to NO nd cannot be condition has fixed to YES			
DE EN DE EN DE EN	[320]  [320]  De Verzö,	[320X] ✓ Sel Se [320X] ✓	Alarr Alarr [350]  f acknov lbstquit [350]  engine ch Moto	n class aklasse [350X] ✓ wledge tierend [350X] ✓ speed rdrehz.	Engine underspeed alarm class         The engine underspeed alarm class is set to "F" and cannot be a         Engine underspeed self acknowledgement         The engine underspeed self-acknowledgement is set to "NO" a changed. The alarm will not automatically reset after the fault of cleared.         Engine underspeed delayed by engine speed         The engine underspeed delay by engine speed is set to "YES" a	fixed to F changed. fixed to NO nd cannot be condition has fixed to YES and cannot be			
DE EN DE EN DE EN	[320] [320]  De Verzö, [320]	[320X] ✓ Sel Se [320X] ✓	Alarr Alarr [350]  f acknoo lbstquit [350]  engine ch Moto [350]	n class aklasse [350X] ✓ wiedge tierend [350X] ✓ speed rdrehz. [350X] ✓	Engine underspeed alarm class         The engine underspeed alarm class is set to "F" and cannot be a         Engine underspeed self acknowledgement         The engine underspeed self-acknowledgement is set to "NO" a changed. The alarm will not automatically reset after the fault of cleared.         Engine underspeed delayed by engine speed         The engine underspeed delayed by engine speed is set to "YES" a changed. The monitoring is delayed by the time configured in labeled and the monitoring is delayed by the time configured in labeled.	fixed to F changed. fixed to NO nd cannot be condition has fixed to YES and cannot be Engine monitoring			
DE EN DE EN	[320]  [320]  De Verzö, [320] 	[320X] ✓ Sel Se [320X] ✓ elayed by gert durc [320X] ✓	Alarr Alarr [350]  f acknoo lbstquit [350]  ch Moto [350] 	n class aklasse [350X] ✓ wiledge tierend [350X] ✓ speed rdrehz. [350X] ✓	Engine underspeed alarm class The engine underspeed alarm class is set to "F" and cannot be a Engine underspeed self acknowledgement The engine underspeed self-acknowledgement is set to "NO" a changed. The alarm will not automatically reset after the fault o cleared. Engine underspeed delayed by engine speed The engine underspeed delay by engine speed is set to "YES" a changed. The monitoring is delayed by the time configured in I delay time on page 74 after starting the engine	fixed to F changed. fixed to NO fixed to NO fixed to YES fixed to YES and cannot be Engine monitoring			

### Monitoring: Engine Start Fail

EN			Mor	nitoring	Engine start fail monitoring	fixed to ON
DE			Überwa	achung		
	[320]	[320X]	[350]	[350X]	The engine start fail monitoring is always enabled and cannot be disa	bled.
	•	v	•	v		
EN	Nu	umber of	start at	tempts	Engine number of start attempts	fixed to 3
DE		Anzahl	Startve	rsuche		
	[320]	[320X]	[350]	[350X]	The control will attempt to start the engine with the configured numb	er of start at-
	1	~	✓	~	tempts. If the engine fails to start after the configured number of atten	npts an
					alarm will be initiated. An engine has been successfully started if the	ignition
					speed has been achieved within the start delay time.	
ä			Alarr	n class	Engine start fail alarm class	fixed to F
DE			Alarm	klasse		
	[320]	[320X]	[350]	[350X]	The engine start fail alarm class is set to "F" and cannot be changed.	
	1	1	✓	1		
EN		Sel	f ackno	wledge	Engine start fail self acknowledgement	fixed to NO
DE		Se	lbstquit	tierend		
	[320]	[320X]	[350]	[350X]	The engine start fail undervoltage self-acknowledgement is set to "Ne	O" and can-
	<ul><li>✓</li></ul>	< 1	<ul><li>✓</li></ul>	<ul> <li>Image: A main sector</li> </ul>	not be changed. The alarm will not automatically reset after the fault	condition
					has cleared.	

# Monitoring: Engine Unintended Stop

교 	Monitoring				Engine unintended stop monitoring	fixed to ON
DE	Überwachung					
	[320] [320X] [350] [350X]		[350X]	The engine unintended stop monitoring is always enabled and canno	t be disabled.	
	1	1	1	1		
E			Alarn	n class	Engine unintended stop alarm class	fixed to F
DE EN			Alarr Alarm	n class Iklasse	Engine unintended stop alarm class	fixed to F

# Monitoring: Battery Undervoltage

E			Мог	nitoring	Battery undervoltage monitoring	fixed to ON
DE			Überwa	achung		
	[320] ✓	[320X]	[350] ✓	[350X]	The battery undervoltage monitoring is always enabled and canno	t be disabled.
EN				Limit	Battery undervoltage limit	8.0 to 42.0 V
DE				Limit		
60 3	[320] ✓	[320X]	[350] ✓	[350X]	The threshold value is set by this parameter. If this value is reache low for at least the delay time, the action specified by the configur is initiated	d or fallen be- ed alarm class
3					is initiated.	
EN				Delay	Battery undervoltage delay	fixed to 10.0 s
DE			Verzö	gerung		
	[320]	[320X]	[350]	[350X]	If the monitored value falls below the threshold value for the delay	y time, an alarm
	1	✓	✓	✓	will be issued.	
					This value is fixed to 10.0 seconds and cannot be changed.	
EN			Alarr	n class	Battery undervoltage alarm class	fixed to B
DE EN			Alarr Alarr	n class nklasse	Battery undervoltage alarm class	fixed to B
DE EN	[320] ✓	[320X]	Alarr Alarr [350] ✓	n class nklasse [350X] ✓	Battery undervoltage alarm class The battery undervoltage alarm class is set to "B" and cannot be cl	fixed to B
EN DE EN	[320] ✓	[320X]	Alarr Alarr [350] ✓	n class klasse [350X] ✓	Battery undervoltage alarm class         The battery undervoltage alarm class is set to "B" and cannot be class         Battery undervoltage self acknowledgement	fixed to B hanged.
DE EN DE EN	[320] ✓	[320X] ✓ Sel	Alarr Alarr [350] ✓	n class nklasse [350X] ✓ wledge tierend	Battery undervoltage alarm class         The battery undervoltage alarm class is set to "B" and cannot be class         Battery undervoltage self acknowledgement	fixed to B hanged. fixed to NO
DE EN DE EN	[320] ✓	[320X] Sel Se [320X]	Alarr Alarr [350] ✓ f acknow Ibstquit	n class aklasse [350X] ✓ wledge tierend	Battery undervoltage alarm class         The battery undervoltage alarm class is set to "B" and cannot be class         Battery undervoltage self acknowledgement         The battery undervoltage self-acknowledgement is set to "NO" and	fixed to B hanged. fixed to NO d cannot be
DE EN DE EN	[320] ✓ [320] ✓	[320X] ✓ Sel [320X] ✓	Alarr Alarr [350] ✓ f acknoo elbstquit [350] ✓	n class aklasse [350X] ✓ wledge tierend [350X] ✓	Battery undervoltage alarm class         The battery undervoltage alarm class is set to "B" and cannot be class         Battery undervoltage self acknowledgement         The battery undervoltage self-acknowledgement is set to "NO" and changed. The alarm will not automatically reset after the fault com-	fixed to B hanged. fixed to NO d cannot be dition has
DE EN DE EN	[320] ✓ [320] ✓	[320X] ✓ Se/ Se [320X] ✓	Alarr Alarr [350] ✓ f acknoo lbstquit [350] ✓	n class iklasse [350X] ✓ wledge tierend [350X] ✓	Battery undervoltage alarm class         The battery undervoltage alarm class is set to "B" and cannot be class         Battery undervoltage self acknowledgement         The battery undervoltage self-acknowledgement is set to "NO" and changed. The alarm will not automatically reset after the fault concleared.	fixed to B hanged. fixed to NO d cannot be dition has
DE EN	[320] ✓ [320] ✓	[320X] ✓ Se/ Se [320X] ✓	Alarr Alarr [350] ✓ f acknoo elbstquit [350] ✓	n class iklasse [350X] ✓ wledge tierend [350X] ✓	Battery undervoltage alarm class         The battery undervoltage alarm class is set to "B" and cannot be class         Battery undervoltage self acknowledgement         The battery undervoltage self-acknowledgement is set to "NO" and changed. The alarm will not automatically reset after the fault concleared.         Battery undervoltage deleved by anging model.	fixed to B hanged. fixed to NO d cannot be dition has
E EN DE EN	[320] ✓ [320] ✓	[320X] ✓ Sel Se [320X] ✓	Alarr Alarr [350] ✓ f acknov Ibstquit [350] ✓	n class iklasse [350X] ✓ wiledge tierend [350X] ✓	Battery undervoltage alarm class         The battery undervoltage alarm class is set to "B" and cannot be class         Battery undervoltage self acknowledgement         The battery undervoltage self-acknowledgement is set to "NO" and changed. The alarm will not automatically reset after the fault concleared.         Battery undervoltage delayed by engine speed	fixed to B hanged. fixed to NO d cannot be dition has fixed to NO
DE EN DE EN	[320] ✓ [320] ✓ Dee Verzö	[320X] ✓ Sel Se [320X] ✓ elayed by gert durc	Alarr Alarr [350] ✓ f acknoo lbstquit [350] ✓ eengine ch Moto	n class klasse [350X] ✓ wledge tierend [350X] ✓ speed rdrehz.	Battery undervoltage alarm class         The battery undervoltage alarm class is set to "B" and cannot be class         Battery undervoltage self acknowledgement         The battery undervoltage self-acknowledgement is set to "NO" and changed. The alarm will not automatically reset after the fault concleared.         Battery undervoltage delayed by engine speed         The battery undervoltage delayed by engine speed is set to "NO" and cleared.	fixed to B hanged. fixed to NO d cannot be dition has fixed to NO d cannot be
DE EN DE EN	[320] ✓ [320] ✓ Dee Verzö [320]	[320X] ✓ Sel Se [320X] ✓	Alarr Alarr [350] ✓ f ackno ilbstquit [350] ✓ eengine ch Moto [350]	n class klasse [350X] ✓ wledge tierend [350X] ✓ speed rdrehz. [350X] ✓	Battery undervoltage alarm class         The battery undervoltage alarm class is set to "B" and cannot be class         Battery undervoltage self acknowledgement         The battery undervoltage self-acknowledgement is set to "NO" and changed. The alarm will not automatically reset after the fault concleared.         Battery undervoltage delayed by engine speed         The battery undervoltage delayed by engine speed is set to "NO" and changed. The monitoring is not delayed by the time configured in	fixed to B hanged. fixed to NO d cannot be dition has fixed to NO d cannot be Fingine moni

# Monitoring: Battery Charge Voltage

EN			Mor	nitoring	Battery charge voltage monitoring	ON / OFF
80 61 3	[320] ✓	[320X]	Überwa [350] ✓	achung [350X] √	<ul> <li>ONBattery charge voltage monitoring is carried out accorfollowing parameters.</li> <li>OFFNo monitoring is carried out.</li> </ul>	rding to the
EN				Limit	Battery charge voltage limit	00.0 to 32.0 V
62 3	[320] ✓	[320X]	[350] ✓	Limit [350X] ✓	The threshold value is set by this parameter. If this value is reached low for at least the delay time, the action specified by the configure is initiated.	or fallen be- d alarm class
EN				Delay	Battery charge voltage delay	fixed to 60.0 s
DE	[320] ✓	[320X]	Verzög [350] ✓	gerung [350X] ✓	If the monitored value falls below the threshold value for the delay will be issued. This value is fixed to 60.0 seconds and cannot be changed.	time, an alarm
EN			Alarn	n class	Battery charge voltage alarm class	fixed to B
DE	[320] ✓	[320X]	Alarm [350] ✓	klasse [350X] ✓	The battery undervoltage alarm class is set to "B" and cannot be cha	anged.
EN		Self	ackno	vledge	Battery charge voltage self acknowledgement	fixed to NO
DE	[320]	Se. [320X] ✓	lbstquit [350] ✓	tierend [350X] ✓	The battery undervoltage self-acknowledgement is set to "NO" and changed. The alarm will not automatically reset after the fault cond cleared.	cannot be ition has
EN	De	layed by	engine	speed	Battery charge voltage delayed by engine speed	fixed to YES
DE	Verzög [320] ✓	gert durc [320X] ✓	h Moto. [350] ✓	rdrehz. [350X] ✓	The battery undervoltage delay by engine speed is set to "YES" and changed. The monitoring is delayed by the time configured in Engi	l cannot be ne monitoring

# Monitoring: Interface

E			Мо	nitoring	J1939 interface monitoring	ON / OFF
DE			Überwa	achung		
93	[320]	[320X]	[350]	[350X]	<b>ON</b> J1939 interface monitoring is carried out according to	the following
3		1		✓	parameters.	
					<b>OFF</b> No monitoring is carried out.	
EN				Delay	J1939 interface monitoring delay	0.1 to 650.0 s
DE			Verzö	gerung		
	[320]	[320X]	[350]	[350X]	If a J1939 alarm is present for at least the delay time, an alarm will b	be issued.
L		1		✓		
E			Aları	n class	J1939 interface monitoring alarm class	<b>B</b> / <b>F</b>
DE			Alarn	nklasse		1 1
	[320]	[320X]	[350]	[350X]	An alarm class can be assigned to the J1939 monitoring. If fault con	dition is de-
L		~		~	tected, the action specified by the alarm class is initiated. It may be p	possible to
					configure all classes of alarms in this parameter but only alarm class	es B and F
					are implemented in the easYgen-300 series. Ensure that only class B	or F is con-
					figured here.	
H		Sel	f ackno	wledge	J1939 interface monitoring self acknowledgement	YES / NO
DE		Se	lbstquit	tierend		
	[320]	[320X]	[350]	[350X]	<b>YES</b> The control will automatically clear the alarm if it is n	o longer va-
L		1		✓	lid.	
					NO An automatic reset of the alarm does not occur. Reset	of the alarm
					must be performed manually by pressing the appropria	ate buttons.
ä	De	layed by	engine	speed	J1939 interface monitoring delayed by engine speed	YES / NO
DE	Verzö	gert duro	ch Moto	rdrehz.		C
	[320]	[320X]	[350]	[350X]	<b>YES</b> The J1939 monitoring is delayed by the engine. There	Tore the con-
L		✓		~	ditions of the parameter "Engine monitoring delay tim	e on page 74
					must be fulfilled.	
					<b>NO</b> The J1939 monitoring is not delayed by the engine.	

### Monitoring: Interface: J1939 Amber Warning Lamp DM1



### NOTE

This monitoring function is only available if parameter 90 "Device type" is configured "1" or "Standard" (refer to page 95.)

B			Мог	nitoring	J1939 interface: amber warning alarm monitoring	ON / OFF
94 3	[320]	[320X]	Überwa [350] 	achung [350X] ✓	<ul> <li>ONJ1939 amber warning alarm monitoring is carried out a the following parameters.</li> <li>OFFNo monitoring is carried out.</li> </ul>	according to
EN				Delay	J1939 interface: amber warning alarm monitoring delay	0.1 to 999.0 s
DE			Verzö	gerung		1
 L	[320]	[320X]	[350] 	[350X]	will be issued.	an alarm
EN			Alarr	n class	J1939 interface: amber warning alarm monitoring alarm class	<b>B</b> / <b>F</b>
DE			Alarn	nklasse		
 L	[320]	[320X]	[350]	[350X]	An alarm class can be assigned to the J1939 amber warning alarm me fault condition is detected, the action specified by the alarm class is in may be possible to configure all classes of alarms in this parameter b classes B and F are implemented in the easYgen-300 series. Ensure the class B or F is configured here.	onitoring. If nitiated. It ut only alarm hat only
EN		Sel	f ackno	wledge	J1939 interface: amber warning alarm monitoring self acknowledgemen	nt YES / NO
DE		Se	lbstquit	tierend		
 L	[320]	[320X]	[350]	[350X] ✓	<ul> <li>YES The control will automatically clear the alarm if it is not lid.</li> <li>NO An automatic reset of the alarm does not occur. Reset of must be performed manually by pressing the appropriate</li> </ul>	o longer va- of the alarm ate buttons.
E	De	layed by	engine	speed	J1939 interface: amber warning alarm monitoring delayed by engine sp	eedYES / NO
id  L	Verzö [320]	igert durc [320X] ✓	ch Moto [350] 	rdrehz. [350X] ✓	<ul> <li>YES</li></ul>	by the en- e monitoring
					engine.	ijed by the

### Monitoring: Interface: J1939 Red Stop Lamp DM1

# NOTE

ĺ

# This monitoring function is only available if parameter 90 "Device type" is configured "1" or "Standard" (refer to page 95.)

EN			Мо	nitoring	J1939 interface: red stop alarm monitoring	ON / OFF
95 3	[320]	[320X]	Überwa [350] 	achung [350X] ✓	<ul> <li>ON J1939 red stop alarm monitoring is carried out accordin lowing parameters.</li> <li>OFF No monitoring is carried out.</li> </ul>	ig to the fol-
E				Delay	J1939 interface: red stop alarm monitoring delay	0.1 to 999.0 s
DE			Verzö	gerung		
 L	[320]	[320X]	[350] 	[350X] ✓	If a J1939 red stop alarm is present for at least the delay time, an alari sued.	n will be is-
E			Alarr	n class	J1939 interface: red stop alarm monitoring alarm class	<b>B</b> / <b>F</b>
DE			Alarn	nklasse		
 L	[320]	[320X]	[350]	[350X]	An alarm class can be assigned to the J1939 red stop alarm monitorin condition is detected, the action specified by the alarm class is initiate possible to configure all classes of alarms in this parameter but only a B and F are implemented in the easYgen-300 series. Ensure that only is configured here.	g. If fault ed. It may be larm classes class B or F
EN		Seli	<sup>f</sup> ackno	wledge	J1939 interface: red stop alarm monitoring self acknowledgement	YES / NO
DE		Se	lbstquit	ttierend		1
	[320]	[320X]	[350]	[350X]	YES The control will automatically clear the alarm if it is no	longer va-
L		v		v	NO An automatic reset of the alarm does not occur. Reset o must be performed manually by pressing the appropriat	f the alarm te buttons.
EN	De	layed by	engine	speed	J1939 interface: red stop alarm monitoring delayed by engine speed	YES / NO
DE	Verzö	gert durc	h Moto	rdrehz.		
 L	[320]	[320X]	[350] 	[350X]	YES The J1939 red stop alarm monitoring is delayed by the Therefore the conditions of the parameter "Engine mon lay time" on page 74 must be fulfilled.	engine. itoring de-

**NO** ...... The J1939 red stop alarm monitoring is not delayed by the engine.

# **Discrete Inputs**

#### 

The easYgen-300 series has 5 discrete inputs (DI1 to DI5). The discrete inputs 1 & 2 are pre-defined as alarm inputs for oil pressure (DI1) and coolant temperature (DI2). The discrete input 3 is a control input for remote start. The functions of the discrete inputs 4 and 5 are dependent on the parameter Ignore CB reply (see page 72). If this parameter is set to NO, these discrete inputs are configured as reply inputs for MCB (DI4) and GCB (DI5). Any changes made to the settings of the discrete inputs DI4 and DI5 have no effect. If this parameter is set to YES, these inputs can be configured freely with the following parameters using LeoPC1.

Z	DI {x} operation	Discrete Input DI {x} operation	N.O. / N.C.
DE	DI {x} Funktiont [320] [320X] [350] [350X] ✓ ✓ ✓ ✓ ✓	The discrete input can be operated by a Normally Oper Closed contact. The Normally Closed contact input can broken wire. A positive or negative voltage potential c <b>N.O.</b>	n contact or a Normally n be use to monitor for a an be applied. t" by energizing a voltage t" by de-energizing a vol-
E	DI {x} delay	Discrete Input DI {x} delay	0.02 to 650.00 s
E L	DI {x} Verzögerungt [320] [320X] [350] [350X] ✓ ✓ ✓ ✓ ✓	A delay time in seconds may be assigned to each alarm must be continuously present for the delay time at the i curs.	n input. The fault condition nput before tripping oc-
EN	DI {x} alarm class	Discrete Input DI {x} alarm class	A / B / C / D / E / F / Control
Ш Ц	Dl {x} Alarmklasset	<ul> <li>see chapter Alarm Classes on page 104.</li> <li>An alarm class can be assigned to a discrete input. The when the discrete input receives a triggering signal. Or are implemented in the easYgen.</li> <li>If "control" has been configured as the alarm class, the luated by the relay outputs if configured accordingly (spage 92 for more information).</li> </ul>	alarm class is initiated ly alarm classes B and F discrete input can be eva- ee Relay Outputs on
E E	DI {x} delayed by eng. speed	Discrete Input DI {x} delayed by engine speed	YES / NO
 L	Di {x} verzog. a. iviotordrehz.         [320]       [320X]         ↓       ↓         ↓       ↓         ↓       ↓         ↓       ↓	<ul><li>YES The input monitoring is delayed by the e tions of the parameter Engine monitoring must be fulfilled.</li><li>NO The input monitoring is not delayed by t analyzed immediately.</li></ul>	ngine. Therefore the condi- g delay time on page 74 he engine. The input is
EN	DI {x} self acknowledge	Discrete Input DI {x} self acknowledge	YES / NO
а L	DI {x} Selbstquittierend [320] [320X] [350] [350X] ✓ ✓ ✓ ✓	<ul><li>YES The control will automatically clear the a longer present.</li><li>NO An automatic reset of the alarm does not must be performed manually by pressing</li></ul>	alarm if the fault is no occur. Reset of the alarm the appropriate buttons,

by enabling the appropriate discrete input, or via an interface.

# **Relay Outputs**

#### 

The easYgen-300 series has 6 (or 4 for [320] & [320X]) relay outputs. The relay outputs 3 and 4 can be freely configured with one signal output from the list of configurable parameters in Table 10-1 (only [350] & [350X]). If this signal is triggered, the relay will be operated.

EN			F	Relay 1	Relay output 1 [350] & [350X]	fixed to open MCB
DE	[320]	[320X] 	[350] ✓	Relais 1 [350X] ✓	The relay output is preset to the command open MCB and cann	ot be changed.
EN			F	Relay 2	Relay output 2	fixed to close GCB
DE			F	Relais 2		
	[320]	[320X]	[350] ✓	[350X]	The relay output is preset to the command open GCB and cann	ot be changed.
H			F	Relay 3	Relay output 3 [350] & [350X] one from configur	able parameter list
DE			F	elais 3		
 L	[320]	[320X]	[350]	[350X]	The relay output can be configured to one signal out of the con ter list. The available signals are listed below.	figurable parame-
EN			F	Relay 4	Relay output 4 one from configur	able parameter list
DE			F	elais 4		
 L	[320]	[320X]	[350]	[350X]	The relay output can be configured to one signal out of the con ter list. The available signals are listed below.	figurable parame-
EN			F	Relay 5	Relay output 5	fixed to fuel relay
DE			F	elais 5		1
	[320]	[320X]	[350]	[350X]	The relay output is preset to the fuel relay and cannot be chang	ed.
				•		
Ä			F	Relay 6	Relay output 6	fixed to starter
DE EN			F	Relay 6 Relais 6	Relay output 6	fixed to starter

The following output signals may be selected from the list of configurable parameters for the relay outputs 3 and 4. If a signal is selected for an easYgen version without this feature, the relay will not be triggered.

Configurable Parameter	Description	Applie	s to		
-	The assigned relay will energize if	[320]	[320X]	[350]	[350X]
Generator overfrequency 1	the generator frequency is exceeded (refer to Monitoring: Generator Overfrequency on page 76 for details)	~	~	~	~
Generator underfrequency 1	the generator frequency is fallen below (refer to Monitoring: Generator Underfrequency on page 77 for details)	~	~	~	~
Generator overvoltage 1	the generator voltage is exceeded (refer to Monitoring: Generator Overvoltage on page 78 for details)	~	~	~	~
Generator undervoltage 1	the generator voltage is fallen below (refer to Monitoring: Generator Undervoltage on page 79 for details)	~	~	~	~
Mains phase rotation mis- match	the mains phase rotation is wrong (refer to Monitoring: Mains on page 80 for details)			~	~
Overspeed 1	the engine speed is exceeded (refer to Monitoring: Engine Over- speed on page 83 for details)		~		~
Underspeed 1	the engine speed is fallen below (refer to Monitoring: Engine Un- derspeed on page 84 for details)		~		<ul> <li>✓</li> </ul>
Start fail	the engine failed to start within 3 attempts (refer to Monitoring: En- gine Start Fail on page 85 for details)	~	~	~	~
Unintended stop	the engine has stopped unintentionally (refer to Monitoring: Engine Unintended Stop on page 85 for details)	~	~	~	~
Maintenance hours exceeded	the maintenance hours are exceeded (refer to Counter on page 94 for details)	~	~	~	~
Battery undervoltage 1	the battery voltage is fallen below (refer to Monitoring: Battery Un- dervoltage on page 86 for details)	~	~	~	~
Charge alternator low voltage	the battery charge voltage is fallen below (refer to Monitoring: Bat- tery Charge Voltage on page 87 for details)	~	~	~	~
Discrete Input DI 1	discrete input DI 1 is energized	✓	✓	$\checkmark$	✓
Discrete Input DI 2	discrete input DI 2 is energized	✓	$\checkmark$	✓	<ul> <li>✓</li> </ul>
Discrete Input DI 3	discrete input DI 3 is energized	✓	$\checkmark$	✓	✓
Discrete Input DI 4	discrete input DI 4 is energized	✓	$\checkmark$	✓	✓
Discrete Input DI 5	discrete input DI 5 is energized	$\checkmark$	$\checkmark$	$\checkmark$	✓
Preglow	the preglow time is active (refer to Engine: Diesel on page 73 for details)	~	~	~	~
Automatic operation mode	the unit is in Automatic operation mode	$\checkmark$	$\checkmark$	$\checkmark$	<ul> <li>✓</li> </ul>
All alarm classes	an alarm of any class is issued	$\checkmark$	$\checkmark$	$\checkmark$	✓
Stopping alarm	an alarm of a class higher than B is issued	$\checkmark$	$\checkmark$	$\checkmark$	✓
Engine released	as soon as an engine start is initiated	✓	$\checkmark$	$\checkmark$	<ul> <li>✓</li> </ul>
Horn	an alarm of class B or higher is issued	✓	✓	$\checkmark$	<ul> <li>✓</li> </ul>
Delayed close GCB	a GCB close command has been issued and the configured 2nd GCB close delay time has expired (refer to Application on page 72 for details)	~	~	~	~
Delayed close MCB	an MCB close command has been issued and the configured 2nd MCB close delay time has expired (refer to Application on page 72 for details)			~	~
Amber warning lamp	the ECU has issued an amber warning alarm (refer to Monitoring: Interface: J1939 Amber Warning Lamp DM1 on page 89 for details)		~		~
Red stop lamp	the ECU has issued an red stop alarm (refer to Monitoring: Inter- face: J1939 Red Stop Lamp DM1 on page 90 for details)		~		~
Mains failure	the mains values are not within the mains failure limits (refer to Monitoring: Mains Failure Limits on page 80 for details)			~	~

Table 10-1: Relay outputs - list of configurable parameters

# Counter

#### 

EN		Maini	tenance	hours	Maintenance hours	0 to 9,999 h
80 70	Wai [320] ✓	rtungsinte [320X] ✓	ervall S [350] ✔	tunden [350X] ✓	① To disable the maintenance counter "hours" configure "0".	I
1					This parameter defines the remaining hours until the next maintenan curs. Once the configured total time (calculated from days and hours exceeded, a message is displayed.	ice call oc- s) has been
					If the parameter "Reset maintenance call" is configured to "YES" (semaintenance counter is reset to the configured value.	ee below) the
EN	Rese	t mainten	ance p	eriod h	Reset maintenance period hours	YES / NO
DE	Wartur	ngsstund	en rück	setzen	If this perpendicular is configured to "VES" the maintenance counter "IL	
71 1	[320]	[320X]	[350]	[350X]	set/reset to the configured value. Once the counter has been set/reset, ter automatically changes back to "NO".	, this parame-
EN		Counte	er value	preset	Counter value preset	0 to 99,999.9
DE		Zá	ähler-S	etzwert		
 L	[320]	[320X]	[350] ✓	[350X]	The operation hour counter is set to this value (the current value is of This counter may be used to count the operation hours.	overwritten).
EN		Set of	peratior	hours	Set operation hours	YES / NO
DE						
	E	Betriebss	tunden	setzen		
 L	[320] ✓	Betriebss [320X] ✓	tunden [350] ✓	setzen [350X] ✓	If this parameter is configured to "YES" the operation hour counter the configured value. Once the counter has been set/reset, this paran ically changes back to "NO".	is set/reset to neter automat-
L	[320] ✓	Betriebss [320X] ✓	tunden [350] ✓	setzen [350X] ✓	If this parameter is configured to "YES" the operation hour counter the configured value. Once the counter has been set/reset, this paramically changes back to "NO". Number of starts	is set/reset to neter automat- 0 to 65,535
L	[320] ✓	Betriebss [320X] ✓ Nu	tunden [350] ✓ mber o Anzah	setzen [350X] ✓ f starts I Starts	If this parameter is configured to "YES" the operation hour counter the configured value. Once the counter has been set/reset, this paramically changes back to "NO". Number of starts	is set/reset to neter automat- 0 to 65,535
L DE EN	[320] ✓ [320]	3etriebss [320X] ✓ Nu [320X]	tunden [350] wher o Anzah [350]	setzen [350X] f starts [350X]	If this parameter is configured to "YES" the operation hour counter the configured value. Once the counter has been set/reset, this paramically changes back to "NO". Number of starts The start counter is set to this value (the current value is overwritten ter more be used to count the number of starts	is set/reset to neter automat- 0 to 65,535

## Interfaces

#### 

### **CAN Interface**

EN			Ba	udrate	CAN baudrate	20/50/100/125/250/500/800/1000 kBd
DE			Ba	nudrate		
	[320]	[320X]	[350]	[350X]	The CAN bus baudrate is configured here.	
L		1		✓		



# NOTE

The baud rate is the same for all devices connected to the CAN bus regardless of the selected protocol.

J1939

EN		Device type	J1939 device type	Off/Standard/S6 Scania/EMR
90 3	Be [320] [320X] [ ✓	triebsmodus [350] [350X] ✓	<ul> <li>Off The J1939 visualization is disabled.</li> <li>Standard The standard J1939 messages are di LeoPC1.</li> <li>S6 Scania The standard J1939 messages are di LeoPC1, and the Scania S6 message addition. The Scania S6 messages are di LeoPC1, and the Deutz EMR2 messi in addition. The Deutz EMR2 messi</li> </ul>	No values are displayed. isplayed on the unit and in isplayed on the unit and in es are displayed in LeoPC1 in lo not appear on the unit. isplayed on the unit and in sages are displayed in LeoPC1 ages do not appear on the unit.
E	Request s	end address	J1939 request send address	0 to 255
DE EN	Request se Request Se	end address endeadresse	J1939 request send address	0 to 255
на На 91	Request se Request Se [320] [320X] [	end address endeadresse [350] [350X]	<b>J1939 request send address</b> The J1939 protocol device number: This is necess rameter groups	0 to 255 sary for requesting particular pa-
80 91 3	Request s Request Se [320] [320X] [ ✓	end address endeadresse [350] [350X] ✓	J1939 request send address The J1939 protocol device number: This is necess rameter groups. The acknowledgement command for passive alarn participant address (Diagnostic Data Clear/Reset of DM3).	0 to 255 sary for requesting particular pa- ms will also be sent with this of Previously Active DTCs -
91 3	Request so Request So [320] [320X]   ✓ Receive de	end address andeadresse [350] [350X] ✓ vice number	J1939 request send address The J1939 protocol device number: This is necess rameter groups. The acknowledgement command for passive alarn participant address (Diagnostic Data Clear/Reset of DM3). J1939 receive device number	0 to 255 sary for requesting particular pa- ms will also be sent with this of Previously Active DTCs - 0 to 255
91 3	Request so Request So [320] [320X] [ 	end address andeadresse [350] [350X] ✓ vice number äte Nummer	J1939 request send address         The J1939 protocol device number: This is necess         rameter groups.         The acknowledgement command for passive alarn         participant address (Diagnostic Data Clear/Reset of DM3).         J1939 receive device number	0 to 255 sary for requesting particular pa- ms will also be sent with this of Previously Active DTCs - 0 to 255
91 3 92	Request so Request So [320] [320X] [  Receive de Empf. Gen [320] [320X] [	end address andeadresse [350] [350X] $\checkmark$ vice number äte Nummer [350] [350X]	J1939 request send address         The J1939 protocol device number: This is necess         rameter groups.         The acknowledgement command for passive alarn         participant address (Diagnostic Data Clear/Reset of DM3).         J1939 receive device number         Indicates the number of the J1939 device, whose of the J1939 device, whose of the J1939 device of the J1939	0 to 255 sary for requesting particular pa- ms will also be sent with this of Previously Active DTCs - 0 to 255 data shall be visualized.

You find detailed information about the J1939 protocol under J1939 Protocol Descriptions starting on page 106.

# System

#### 

### Codes

E	Comissioning level code		el code	Set commissioning level code	0000 to 9999
DE	Code Inebtrieb	nahme	Ebene		
 L	[320] [320X]	[350]	[350X]	The user may configure the HMI password (Parameter <b>00</b> ) here. The word protects the configuration of the unit via the front panel. The mis valid immediately after changing and confirming it within LeoPC This parameter is only available from Software Version 2.0007 (reference).	e HMI pass- new password 1. er to Update

NOTE The commissioning level coder (HMI password) will not be reset when restoring the default values.

# **Factory Settings**

EN	Fa	actory settings	Enable to reset to factory settings	ON / OFF
DE	Werkseinstellung		OFF The parameters "Clear event log" and "Set defa	ult values" are dis-
L	1 1	1 1	abled.	
			ON The parameters "Clear event log" and "Set defa enabled. The event log may be cleared and the o be restored.	ult values" are default values may
교 -	C	Clear event log	Clear event log	ON / OFF
DE	Ereignisspe	eicher löschen		
	[320] [320X]	[350] [350X]	<b>OFF</b> The event log will not be cleared.	
L	✓ ✓	✓ ✓	ON All entries in the event logger will be cleared ar will be reset to "OFF" automatically. The paran tings" must be configured "ON" to clear the even	nd this parameter neter "Factory set- ent log.

		001	aoraan	Valueoo		~
DE	Standardwerte			dwerte		
	[320]	[320X]	[350]	[350X]	<b>OFF</b> The default values will not be restored.	
L	✓	✓	✓	✓	ON All parameters will be reset to their default values and this par	ame-
					ter will be reset to "OFF" automatically. The parameter "Facto	ory
					settings" must be configured "ON" to restore the default value	s.

#### **Parameter Access Level**

EN			Displa	y level	Display level 1 to 3
DE			Anzeige	ebene	
72	[320]	[320X]	[350]	[350X]	The user may alter the number of configurable parameters that are displayed on
1	1	1	1	<ul> <li>Image: A second s</li></ul>	the control unit front panel when the unit is in configuration mode. By selecting
•					the highest level of access (level 3), all parameters will be displayed. The lower
					the access level selected, the fewer parameters are displayed.

### Flags

The easYgen-300 series provides four configurable LED flags in the alphanumerical display to indicate alarms. One or more alarm messages can be assigned to each one of these flags (i.e. the respective flag will be illuminated if the configured alarm state(s) occur(s) in addition to the regular alarm indication). A detailed description of these flags can be found in the chapter Alarm Messages on page 41 and a configuration example can be found under Configuring the Flags on page 68.

a Flag {x} {alarm y}				larm y}	Flag {x} {alarm y}YI	ES / NO
DE		Fla	g {x} {A	larm y}		
	[320]	[320X]	[350]	[350X]	<b>YES</b> If the alarm $\{y\}$ is present, the display flag $\{x\}$ will be illum	ninated.
L	1	<ul> <li>Image: A second s</li></ul>	1	1	<b>NO</b> The display flag $\{x\}$ ignores the alarm $\{y\}$ .	
				{ <b>x</b> }Display flags 1 to 4		
				{y} The following alarms may be indicated with the flags:		
				gen. overfrequency, gen. underfrequency, gen. overvoltage,	gen.	
				undervoltage, mains phase rotation mismatch, overspeed, un	nders-	
				peed, unintended stop, start fail, maintenance hours expired	, CAN	
				failure J1939, undervoltage auxiliary alternator, undervoltag	ge bat-	
					tery, discrete input 1, discrete input 2, discrete input 3, discr	rete in-



put 4, and/or discrete input 5, amber warning lamp, red stop lamp

Figure 10-2: Configurable display flags

### Versions

### NOTE

i

The following parameters are not configurable. They may be viewed using LeoPC1 for information purposes only.

E			Serial n	number	Serial number (S/N)	display only
DE		S	Serienni	ummer		
 L	[320]	[320X]	[350] ✓	[350X]	This is the serial number of the easYgen and identifies the control cl	early.
E		Boo	t item n	umber	Boot item number (P/N)	display only
DE		Boot /	Artikelni	ummer		
 L	[320]	[320X]	[350] ✓	[350X]	This is the item number of the firmware, which is stored on the easY	gen.
EN			Boot re	evision	Boot revision (REV)	display only
DE			Boot Re	evision		
 L	[320]	[320X]	[350]	[350X]	This is the revision of the firmware, which is stored on the easYgen.	
EN			Boot v	version	Boot version	display only
DE	Boot Version		/ersion			
 L	[320]	[320X]	[350] ✓	[350X]	This is the version (Vx.xxxx) of the firmware, which is stored on the	e easYgen.
EN		Program	n item n	number	Program item number	display only
DE	Pro	ogramm /	Artikelni	ummer		
 L	[320] ✓	[320X]	[350]	[350X]	This is the item number of the application software of the easYgen.	
EN		Pro	ogram re	evision	Program revision	display only
DE	Programm Revision		evision			
 L	[320]	[320X]	[350]	[350X]	This is the revision of the application software of the easYgen.	
E		Pr	ogram \	version	Program version	display only
DE		Prog	ramm V	/ersion		
 L	[320]	[320X]	[350]	[350X]	This is the version (Vx.xxxx) of the application software of the easY	gen.

# Chapter 11. Event Logger

The event logger is a FIFO (First In/First Out) memory for logging alarm events and operation states of the unit. The capacity of the event logger is 15 entries. Additional event messages overwrite the oldest messages. Since the easYgen-300 units do not include a clock module, the operating hours are stored with each event logger entry as the timestamp.

The individual alarm messages, which are stored in the event history, are described in detail under Alarm Messages on page 41. The operation states, which are stored in the event history, are listed in Table 11-1 on page 100.



# NOTE

The event logger cannot be read out directly from the front of the unit. It can only be read out using the program GetEventLog, which can either be used as a stand alone or within LeoPC1.

# GetEventLog Software

### Installing GetEventLog

GetEventLog can either be used as a stand alone or within LeoPC1. In order to call it up from LeoPC1, it must be installed into the LeoPC1 installation path.

To install GetEventLog, start GetEventLog\_vxxxx.exe from the GetEventLog directory on the CD delivered with the unit.

If you want to use GetEventLog from inside LeoPC1, it must be installed into the LeoPC1 installation directory.

### Starting GetEventLog

Connect the easYgen to a free COM port on your computer using the DPC as described under Configuration Using the PC on page 67.

Start GetEventLog directly or call it up by selecting GetEventLog from the menu Tools in LeoPC1.

After starting GetEventLog for the first time, you must configure the communication settings. To do this, select the Interface tab, configure the COM port according to the port, to which you have connected the DPC, and enter the other settings as represented in figure Figure 11-1 since these are the default settings of the easYgen-300.

🖹, Eventlog 1.0001	<u>×</u>
Eventing Interface	Command etE ventLog
<u>-</u>	

Figure 11-1: GetEventLog - interface configuration

#### Reading Out GetEventLog

On the Eventlog tab of GetEventLog, click the Request Eventlog button to read out the content of the event logger memory. The content of the event logger is displayed as shown in Figure 11-2.

, Eventlog 1.0001							
Eventiog Interface							
"-"; "00008.4h"; "00064A" "+"; "00008.4h"; "00063A" "+"; "00008.4h"; "00064A" "-"; "00008.4h"; "00064A" "-"; "00008.4h"; "00070A" "-"; "00008.4h"; "00070A" "+"; "00008.4h"; "00070A" "+"; "00008.4h"; "00031A" (end> ▼	[Request Eventlog]						

Figure 11-2: GetEventLog - event logger content

The 15 latest events are displayed in chronological order and each entry is composed like this:

#### "sign";"operating hour";"alarm/state"

whereas "sign"+" indicates the occurrence and "-" indicates the disappearance or acknowledgement of the alarm or state

"operating hour" serves as a timestamp and indicates the operating hour of the event occurred "alarm/state" indicates the type of alarm or change of state that occurred

The alarm codes are the same as displayed on the unit and described under Alarm Messages on page 41. The codes for the operation states are indicated in Table 11-1 below.

Example: The entry **"+"; "00008.4h"; "00031A"** means that alarm 31A unintended stop **"00031A"** occurred **"+"** at operating hour 8.4 **"00008.4h"**. The operating hours are indicated in decimals, i.e. 8.4 hours are 8 hours and 24 minutes.

Number	Operation state	[320]	[320X]	[350]	[350X]
70	Mode: Automatic	✓	<ul> <li>✓</li> </ul>	✓	✓
71	Mode: Stop	✓	✓	✓	✓
72	Mode: Manual	✓	✓	✓	✓
73	GCB closed	✓	✓	✓	✓
74	GCB opened	✓	✓	✓	✓
75	MCB closed			✓	✓
76	MCB opened			✓	✓
77	Mains not in range			✓	✓
78	Emergency mode active			✓	<ul> <li>✓</li> </ul>
79	Engine run	✓	<ul> <li>✓</li> </ul>	✓	✓

Table 11-1: Event logger - operation states

#### Storing Event Logger Data

Using the Save Eventlog button on the Eventlog tab, you are able to save the content of the event logger in CSV format (comma separated values).

#### **Resetting the Event Logger**

The event logger can only be reset using LeoPC1. To do this, perform the following steps:

Connect the easYgen with your PC and start LeoPC1 as described in Configuration Using the PC on page 67. Set the parameter Factory settings to YES. Set the parameter Clear Even Log to YES. The event logger should be cleared.

# Chapter 12. Technical Data

Name plate			
1       2       3         Image: Construction of the sector of the	1 2 3 4 5 6 7 8 9	S/N S/N S/N P/N REV Details Type UL	Serial number (numerical) Serial number (Barcode) Date of production (YYMM) Item number Item revision number Technical data Unit name Extended description UL sign
Measuring values			
Measuring voltages	<b>480 Vac</b> Rated val Maximur Rated vol Rated sur	lue (Vn) n value (Vm ltage phase - rge voltage	
- Linear measuring range			
- Measuring frequency	Generato Mains	r	
- Accuracy			Class 1
- Input resistance per path			
- Maximum power consumption	per path		
Ambient veriebles			
- Power supply			12/24 Vdc (6.5 to 32.0 Vdc)
B	attery grou	nd (terminal	1) must be grounded to the chassis
- Intrinsic consumption			
- Degree of pollution			
- Ambient temperature	Storage .		20 to +85 $^{\circ}$ C / -4 to +185 $^{\circ}$ F
	Operation	n	20 to +70 °C / -4 to +158 °F
- Ambient humidity			95 %, non condensing
Discrete inputs			isolated
- Input range (V <sub>Cont. digital input</sub> )	••••••••••••••	Rated v	oltage 12/24 Vdc (6.5 to 32.0 Vdc)
- Input resistance			approx. 6.7 kΩ
Polov outputs			notantial from
Contact material			A gCdO
- General purpose (GP) (V <sub>Centeral</sub>	······	•••••	
Content par pose (Sr ) ( Cont, rela	AC		2.00 Aac@250 Vac
	DC		2.00 Adc@24 Vdc
			0.36 Adc@125 Vdc
			0.18 Adc@250 Vdc
- Pilot duty (PD) (V <sub>Cont, relay output</sub> )			
	AC		B300
	DC		1.00 Adc@24 Vdc
			0.22 Adc@125 Vdc
			0.10 Adc@250 Vdc

MPU Input	capacitive isolated
- Input impedance	min. approx. 17 kΩ
- Input voltage	
Pre-exciter current output D+	
- Max. exciter current	
	12 Vdc (terminal 4) 0.11 Adc
	24 Vdc (terminal 3) 0.11 Adc
<i>Note:</i> The charging alternator	D+ acts as an output for pre-exciting the charging alternator
during engine start-up of	nly. During regular operation, it acts as an input for monitor-
ing the charging voltage	h.
Interface	
Service interface	non isolated
- Version	
- Signal level	
Le	evel conversion and insulation by using DPC (P/N 5417-557)
CAN hus interface	batelozi
- Insulation voltage	1 500 Vdc
- Version	CAN bus
- Internal line termination	Not available
Housing	
- Type	
- Dimensions ( $W \times H \times D$ )	$158 \times 158 \times 40 \text{ mm}$
- Front cutout ( $W \times H$ )	
- Connection	screw and plug terminals 2.5 mm <sup>2</sup>
- Recommended tightening tor	que
	Connectors0.5 Nm
	Housing clamps0.1 Nm
	use only 60/75 °C copper leads
	use only class 1 cables (or similar)
- Weight	approx. 450 g
Vibration	
- Sinusoidal	
- Endurance	
- Random	
Shock	
- Shock	
Protection	
- Protection system	IP54 from front for proper installation with gasket pending
- Front folio	insulating surface
- EMC test (CE)	
- Listings	CE marking; UL listing for ordinary locations pending
- Type approval	UL/cUL, Ordinary Locations, File No.: 231544
Standards	
- Shock	
- Vibration	EN 60255-21-1; EN 60255-21-3
- Temperature	IEC 60068-2-30; IEC 60068-2-2; IEC 60068-2-1

# Chapter 13. Accuracy

Measuring value		Display	Accuracy	Notes	
Frequency					
Generator	$f_{L1N}, f_{L2N}, f_{L3N}$	15.0 to 85.0 Hz	0.1 %	-	
Mains	$f_{L1N},f_{L2N},f_{L3N}$	40.0 to 85.0 Hz	0.1 %	-	
Voltage					
Generator	V <sub>L1N</sub> , V <sub>L2N</sub> , V <sub>L3N</sub> ,	0 to 600 V	1 %	Transformer ratio selectable	
Mains	$\mathbf{V}_{\text{L1N}}, \mathbf{V}_{\text{L2N}}, \mathbf{V}_{\text{L3N}},$	0 to 600 V	1 %	Transformer ratio selectable	
Miscellaneous					
Operating hours		0 to 99,999.9 h		-	
Maintenance call		0 to 9,999 h		-	
Start counter		0 to 65,535		-	
Battery voltage		6.5 to 32 V	1 %	-	
MPU speed		$f_n \pm 40~\%$		-	

#### **Reference conditions (to measure the accuracy):**

- Input voltage.....sinusoidal rated voltage
- Frequency .....rated frequency ± 2 %
- Power supply .....rated voltage  $\pm 2 \%$
- Warm-up period ......20 minutes

# Appendix A. Common

# **Alarm Classes**

#### 

The easYgen-300 series provides only the alarm classes B & F:

Alarm class	Visible in the display	LED "Alarm" & horn	Relay "Close GCB" is de-energized	Shut-down engine	Engine blocked until ack. sequence has been passed			
В	yes	yes						
	Warning Alarm This alarm does not interrupt the operation. An output of the centralized alarm occurs: ⇒ Alarm text + flashing LED "Alarm" + Relay centralized alarm (horn).							
F	yes	yes	yes	immediately	yes			
	Responding Alarm With this alarm the GCE ⇒ Alarm text + flashing	3 is opened immediately a LED "Alarm" + Relay c	and the engine is stopped. entralized alarm (horn)+ (	GCB open + Engine stop.				

The alarm classes A, C, D, & E can be configured, but are intended for future software revisions **and should not be used**. The behavior of the unit is the following if configured for these alarm classes:

Alarm class	Visible in the display	LED "Alarm" & horn	Relay "Close GCB"	Shut-down engine	Engine blocked until			
		a norm	is at theighted		been passed			
				-	-			
Α	yes	no	no	no	no			
	Warning Alarm This alarm does not interrupt the unit operation. A message output without a centralized alarm occurs at the unit: $\Rightarrow$ Alarm text.							
С	yes	yes	yes	after cool down	yes			
	<b>Responding Alarm</b> With this alarm the GCB is opened and the engine is stopped. Coasting occurs. $\Rightarrow$ Alarm text + flashing LED "Alarm" + Relay centralized alarm (horn) + Coasting + GCB open + Engine stop.							
D	yes yes yes after cool down			yes				
	Responding Alarm With this alarm the GCB is opened and the engine is stopped. Coasting occurs. ⇒ Alarm text + flashing LED "Alarm" + Relay centralized alarm (horn) + Coasting + GCB open + Engine stop.							
Е	yes	yes	yes	immediately	yes			
	Responding Alarm With this alarm the GCB is opened immediately and the engine is stopped. ⇒ Alarm text + flashing LED "Alarm" + Relay centralized alarm (horn)+ GCB open + Engine stop.							

### NOTE

If the control unit is in MANUAL operation mode, a cool down phase is <u>not</u> performed regardless of the alarm class!

# **Conversion Factors and Charts**

#### 

### **Conversion Factors: Temperature**

°C ⇔ °F	°F⇔°C
$1 \text{ °F} = (\text{[Value °C \times 1.8 °F/°C}) + 32 °F$	$1 \ ^{\circ}C = \frac{([Value] \ ^{\circ}F - 32 \ ^{\circ}F)}{1.8 \ ^{\circ}F/^{\circ}C}$

Table 13-1: Conversion factor: temperature

### **Conversion Factors: Pressure**

bar ⇒ psi	psi ⇔ bar
1 psi = [Value] bar $\times$ 14.501	1 bar = $\frac{[Value] psi}{14.501}$

Table 13-2: Conversion factor: pressure

### **Conversion Chart: Wire Size**

AWG	mm <sup>2</sup>	AWG	mm <sup>2</sup>	AWG	mm <sup>2</sup>						
30	0.05	21	0.38	14	2.5	4	25	3/0	95	600MCM	300
28	0.08	20	0.5	12	4	2	35	4/0	120	750MCM	400
26	0.14	18	0.75	10	6	1	50	300MCM	150	1000MCM	500
24	0.25	17	1.0	8	10	1/0	55	350MCM	185		
22	0.34	16	1.5	6	16	2/0	70	500MCM	240		

Table 13-3: Conversion chart: wire size

# Appendix B. J1939 Protocol Descriptions

# Visualizing J1939 Measuring Values with LeoPC1

These J1939 measuring values are received by the easYgen via CAN bus from the ECU and visualized in LeoPC1 using direct configuration. The PC/laptop running LeoPC1 must be connected to the easYgen via the DPC interface (refer to page 32).

# NOTE

The values are displayed on the unit with less accuracy. Refer to J1939 Visualization [320X], [350X] on page 40 for more information.

### J1939 Standard Measuring Values

Name			Unit	Value in LeoPC1 with defective sensor	Value in LeoPC1 with missing sensor value
SPN	PGN	Description in J1939 protocol			
190	61444	Engine speed	0.1 rpm	214748364.6rpm	214748364.7rpm
247	65253	Total engine hours	1 h	2147483646h	2147483647h
110	65262	Engine coolant temperature	°C	32766°C	32767°C
174	65262	Fuel temperature	1°C	32766°C	32767°C
175	65262	Engine oil temperature	0.01°C	21474836.46°C	21474836.47°C
100	65263	Engine oil pressure	1kPa	65534kPa	65535kPa
111	65263	Coolant level	0.1%	6553,4%	6553.5%
91	61443	Throttle position	0.1%	6553.4%	6553.5%
92	61443	Load at current speed	1%	65534%	65535%
513	61444	Actual engine torque	1%	32766%	32767%
98	65263	Engine oil level	0.1%	6553.4%	6553.5%
183	65266	Fuel rate	0.01 l/h	21474836.46 L/h	21474836.47 L/h
108	65269	Barometric pressure	0.1kPa	65534kPa	65535kPa
172	65269	Air inlet temperature	1°C	32766°C	32767°C
102	65270	Boost pressure	1kPa	65534kPa	65535kPa
105	65270	Intake manifold temp.	1°C	32766°C	32767°C
173	65270	Exhaust gas temperature	0.001°C	21474836.46°C	21474836.47°C

SPN = Suspect Parameter Number; PGN = Parameter Group Number

### **Special EMR Messages**

Туре	Message acc. to EMR manual	Display in LeoPC1		
0	Engine stop information	no stop		
1	Engine safety	Type 1. Engine safety		
2	CAN message engine stop request	Type 2: CAN message engine stop request		
3	Low oil pressure	Type 3: low oil pressure		
4	Low oil level	Type 4: low oil level		
5	High coolant temp	Type 5: high coolant temp		
6	Low coolant level	Type 6: low coolant level		
7	Intake manifold temp	Type 7: intake manifold temp		
8	Reserved (Stop via SAE-J1587)	Type 8: reserved (Stop via SAE-J1587)		
9	Reserved (Stop via VP2)	Type 9: reserved (Stop via VP2)		



### NOTE

These parameters are only visible in LeoPC1 and are not displayed on the unit.

### **Special S6 Messages**

Suspect Parameter Number	Parameter Group Number	Description	Display in LeoPC1
DLN2-Proprietary	65409 (FF81h)	Assessed messages: Low engine oil level High engine oil level Low oil pressure High coolant temperature	NO Sensor defect YES

If DLN2 does not transmit, "missing" is displayed in LeoPC1



### NOTE

These parameters are only visible in LeoPC1 and are not displayed on the unit.

# Appendix C. Front Customization

The easYgen-300 series is designed language-independent, but can be customized to your demands using paper strips. The left paper strip is intended for customization and may contain more detailed information about the display.

The right paper strip is divided in three parts. The lowest part serves for labeling the unit indicators (refer to Display of the Operating Values on page 36). You can customize the paper strip to reflect the unit of measure in your preferred language. The middle section serves for labeling the four configurable alarm flags (refer to Alarm Messages on page 41). You can customize the paper strip to reflect the alarm message assigned to the respective flag in your preferred language. The upper field is intended for customization and may contain more detailed information about the display.



Figure 13-4: Paper strips

The unit is delivered with English paper strips, where the left paper strip contains the alarm messages and the right paper strip contains the units of measure in English, the default alarm messages for the alarm flags, and information about the configuration parameters in the upper section.

Templates for paper strips in different languages can be found in the "Paper Strips" directory on the CD delivered with the unit. The templates are in Microsoft Word format and can be customized to your demands. Please note that the paper strip geometry must not be modified in the templates. Just edit the text in the paper strips, print them out, cut out the paper strips where indicated, and insert them into the openings at the side of the unit.
# Appendix D. Troubleshooting

If problems are encountered while commissioning or operating the easYgen-300, please refer to the troubleshooting table below and LeoPC1 prior to contacting Woodward for technical assistance. The most common problems and their solutions are described in the troubleshooting table. If problems are encountered between the easYgen-300 and its wiring and the engine or other devices, refer to the respective manuals for solving the problem.

Symptom	Possible cause	Possible solution	Verify
Unit does not power up.	Power supply outside operating range.	With power supply voltage con- nected to terminals 1(-) and 2(+) of	Voltage must be no less than 6.5 Volts and no greater than
		the easYgen-300, measure the vol-	32 Volts.
	Power supply polarity reversed.	With power supply voltage con-	Voltage measurement reads
		the easYgen-300, measure the vol-	(+) polarity when meter is connected to terminal 1(-), and
A1		tage at these terminals.	2(+).
occurs, after engine has fired.	Engine produces no oil pressure.	Check engine oil pressure.	Functional Description of the Oil Pressure Input DI1" for more information.
	Oil pressure sensor is miswired.	Check wiring of the oil pressure sensor.	A "Normally Closed" contact from the oil pressure sensor
	Incorrect oil pressure sensor is being used.	Verify the correct sensor is being used.	16/15 on the eas Ygen-300. Refer to chapter "Chapter 8 - Functional Description of the Oil Pressure Input D11" for
	Oil pressure sensor is defective.	Check the oil pressure sensor.	Check oil pressure sensor for proper functionality and ob- structions.
Alarm "61A – Coolant tem- perature" occurs after engine	Engine temperature is too high.	Check engine temperature.	Engine temperature must be within its specified range.
has fired.	Coolant temperature sensor is miswired.	Check wiring of the temperature sensor.	A "Normally Open" contact must be wired from the sensor to the easYgen-300 (terminals 17/15).
	Coolant temperature sensor is de- fective.	Check coolant temperature sensor.	Check coolant temperature sensor for proper functionali- ty.
Engine does not start by pressing the "Start" button.	Unit is in operating mode "Stop" and the "Stop" LED is lit.	Unit must be in operating mode "Manual".	Press the "Operating Mode" button twice for selecting ma- nual mode.
Engine does not start by set- ting the "Remote-Start" signal (discrete input 3).	Unit is in operating mode "Stop".	Unit must be in operating mode "Auto" to be started via "Remote- Start" signal.	Press the "Operating Mode" button for selecting "Auto" mode.
	Unit is in operating mode "Ma- nual".	Unit must be in operating mode "Auto" to be started via "Remote- Start" signal.	Press the "Operating Mode" button for selecting "Auto" mode.
	"Remote-Start" signal is mis- wired to the easYgen-300.	Measure the voltage between ter- minals 18/15.	If you set the "Remote Start" signal, you should measure a voltage between terminals 18/15. If a voltage is present at these terminals, everything is wired correctly.

"Generator Circuit Breaker Closed" LED is not lit, al- though the Circuit Breaker is closed. "Generator Circuit Breaker Closed" signal is miswired. Measure the voltage between ter- minals 20 and 15 on the easYgen- 300. If the circuit breaker is closed you should measure around 0 Volts between terminals 20 and 15. If around 0 Volts are measured, the "Generator Cir- cuit Breaker Closed" LED should be lit.   If the circuit breaker is closed. Wrong setting of Parameter "Ig- nore Breaker Replies". Use the Woodward "LeoPC1" con- figuration software to check for correct setting of the Parameter "Ignore Breaker Replies". Use the Woodward "LeoPC1" con- figuration software to check for correct setting of the Parameter "Ignore Breaker Replies".	Symptom	Possible cause	Possible solution	Verify
Closed" LED is not lit, al- though the Circuit Breaker is closed. Closed" signal is miswired. minals 20 and 15 on the easYgen- 300. you should measure around 0 Volts between terminals 20 and 15. If around 0 Volts are measured, the "Generator Cir- cuit Breaker Closed" LED should be lit.   If the circuit breaker is open, you should measure a voltage similar to the battery voltage in your system between ter- minals 20 and 15. In this case the "Generator Circuit Breaker Closed" LED must not be lit. Check whether you are using an N.C. contact as breaker aux. contact.   Wrong setting of Parameter "Ig- nore Breaker Replies". Use the Woodward "LeoPC1" con- figuration software to check for correct setting of the Parameter "Ignore Breaker Replies". Within the LeoPC1 configura- tion software, the parameter "Ignore Breaker Replies".	"Generator Circuit Breaker	"Generator Circuit Breaker	Measure the voltage between ter-	If the circuit breaker is closed,
though the Circuit Breaker is closed. 300. Yolts between terminals 20 and 15. If around 0 Volts are measured, the "Generator Cir- cuit Breaker Closed" LED should be lit.   If the circuit breaker is open, you should be lit. If the circuit breaker is open, you should be lit.   If the circuit Breaker Replies". Use the Woodward "LeoPC1" con- figuration software to check for correct setting of the Parameter "Ignore Breaker Replies". Within the LeoPC1 configura ton software, the parameter "Ignore Breaker Replies".	Closed" LED is not lit, al-	Closed" signal is miswired.	minals 20 and 15 on the easYgen-	you should measure around 0
closed. and 15. If around 0 Volts are measured, the "Generator Cir- cuit Breaker Closed" LED should be lit. If the circuit breaker is open, you should measure a voltage similar to the battery voltage in your system between ter- minals 20 and 15. In this case the "Generator Circuit Breaker Closed" LED must not be lit. Check whether you are using an N.C. contact as breaker aux. contact. Wrong setting of Parameter "Ig- nore Breaker Replies". Wrong setting of Parameter "Ig- nore Breaker Replies". Use the Woodward "LeoPC1" con- figuration software to check for correct setting of the Parameter "Ignore Breaker Replies". Within the LeoPC1 configura tion software, the parameter "Ignore Breaker Replies". Were the Woodward "LeoPC1" con- figuration software to check for correct setting of the Parameter "Ignore Breaker Replies". How to enable the MCB reply state to be visua- lized on the "Generator Circuit Breaker Closed" LED.	though the Circuit Breaker is	6	300.	Volts between terminals 20
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Wrong setting of Parameter "Ig- nore Breaker Replies".Use the Woodward "LeoPC1" con- figuration software to check for correct setting of the Parameter "Ignore Breaker Replies".Use the Woodward "LeoPC1" con- figuration software to check for correct setting of the Parameter "Ignore Breaker Replies".Within the LeoPC1 con- figuration software to check for correct setting of the Parameter "Ignore Breaker Replies".Within the LeoPC1 con- figuration software to check for correct setting of the Parameter "Ignore Breaker Replies".Within the LeoPC1 con- figuration software to check for correct setting of the Parameter "Ignore Breaker Replies".Within the LeoPC1 con- figuration software to check for correct setting of the Parameter "Ignore Breaker Replies".Within the LeoPC1 con- figuration software to check for correct setting of the Parameter "Ignore Breaker Replies".Within the LeoPC1 con- figuration software to check for correct setting of the Parameter "Ignore Breaker Replies".Within the LeoPC1 configuration software to check for correct setting of the Parameter "Ignore Breaker Replies".Within the LeoPC1 configuration software to check for to software, the parameter "Ignore Breaker Replies".				cuit Breaker Closed" LED
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Im your system between terminals 20 and 15. In this case minals 20 and 15. In this case the "Generator Circuit Breake Closed" LED must not be lit. Check whether you are using an N.C. contact as breaker aux. contact.Wrong setting of Parameter "Ig- nore Breaker Replies".Use the Woodward "LeoPC1" con- figuration software to check for correct setting of the Parameter "Ignore Breaker Replies".Within the LeoPC1 configura tion software, the parameter "Ignore Breaker Replies".Wrong setting of Parameter nore Breaker Replies".Use the Woodward "LeoPC1" con- figuration software to check for correct setting of the Parameter "Ignore Breaker Replies".Within the LeoPC1 configura tion software, the parameter "Ignore Breaker Replies".Wrong setting of Parameter tion software to check for correct setting of the Parameter "Ignore Breaker Replies".Within the LeoPC1 configura 				in your system between ter-
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MCB reply state to be visua- lized on the "Generator Circui Breaker Closed" LED.			"Ignore Breaker Replies"	be set to "No" to enable the
lized on the "Generator Circui Breaker Closed" LED.			ignore breaker kepnes .	MCB reply state to be visua-
Breaker Closed" LED.				lized on the "Generator Circuit
Breaker Closed EED.				Breaker Closed" I ED
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Breaker Bendies" is set to				Breaker Replies" is set to
"Vas" the state of the CB re-				"Ves" the state of the CB re-
by will not be reconnected				ply will not be recognized!
"Mains Circuit Breaker	"Maine Circuit Breaker	"Mains Circuit Breaker Closed"	Massura the voltage between ter	If the circuit breaker is closed
Mains Closed" I ED is not lit al. signal is missioned minals to sold the asymptotic for t	Closed" I ED is not lit al-	signal is miswired	minals 19 and 15 on the easy gen-	you should measure around 0
though the Circuit Product is signal is miswired.	though the Circuit Breaker is	signal is miswired.	300	Volts between terminals 10
aloga in closed and the second of the second	closed		500.	and 15. If around 0 Volts are
manual in a found of voits are manual in a found of voits are	ciosed.			measured the "Mains Circuit
Brassfred, the Mains Credit				Breaker Closed" I ED should
bit				be lit
If the circuit breaker is open				If the circuit breaker is open
you should measure a voltage				you should measure a voltage
you should inclusive voltage				similar to the battery voltage
in your system between ter-				in your system between ter-
m your system ot wear the case				minals 19 and 15. In this case
the "Mains Circuit Breaker				the "Mains Circuit Breaker
Closed" LED mist not be lit				Closed" LED must not be lit
Check whether you are using				Check whether you are using
an N C contact as breaker				an N C contact as breaker
aux contact a branch				aux contact
Wrong setting of Parameter "Ig. Use the Woodward "LeoPC1" con- Within the LeoPC1 configura		Wrong setting of Parameter "Ig-	Use the Woodward "LeoPC1" con-	Within the LeoPC1 configura-
nore Breaker Replies" figuration software to check for		nore Breaker Replies"	figuration software to check for	tion software, the parameter
correct setting of the Parameter "Tonore Breaker Realies" mus		note Breaker Replies .	correct setting of the Parameter	"Ignore Breaker Replies" must
"Ignore Breaker Renlies" be set to "No" to enable the			"Ignore Breaker Replies"	be set to "No" to enable the
MCB really state to be visua-			-Grote Breaker Replies .	MCB reply state to be visua-
lized on the "Mains Circuit				lized on the "Mains Circuit
Breaker Closed" I ED				Breaker Closed" LED
If the parameter "Ignore				If the parameter "Ignore
Breaker Renlies" is set to				Breaker Replies" is set to
"Yes", the state of the CR re-				"Yes", the state of the CB re-
ply will not be recognized!				ply will not be recognized!

#### easYgen-300 Series - Genset Control

Symptom	Possible cause	Possible solution	Verify
Alarm "30A - Start fail" oc-	Low fuel situation.	Check, if enough Fuel is present to	Fuel level is above fuel pick-
curs.		run the engine.	up and fuel system is properly
		C C	primed
	Fuel line connection to the en-	Check whether the fuel line to en-	No leaks in fuel system and
	gine is not present.	gine is installed properly.	system is primed
	Generator produces no voltage	Check if the generator is excited	While the crank is engaged the
	Scherutor produces no vorage.	properly	generator shall produce vol-
		property.	tage
	Fuel relay output of the easygen	Massura the resistance between	Case 1 Darameter "Fuel Delay
	300 is defective or miswired	terminals 13 and 11 on the easy	Logic" is set to "Open to
	500 is delective of miswired.	con 200	Logic is set to Open to
		gen-300.	Stop :
			If an aim a is made stands dother as
			If engine is not started, the re-
			sistance between terminals 13
			and 11 must be around infini-
			tive Ohms.
			If the easYgen-300 performs
			an start, the resistance between
			terminals 13 and 11 must be
			around 0 Ohms.
			Case 2, Parameter "Fuel Relay
			Logic" is set to "Close to
			Stop":
			If engine is not started, the re-
			sistance between terminals 13
			and 11 must be around 0
			Ohms.
			If the easYgen-300 performs
			an start, the resistance between
			terminals 13 and 11 must be
			around infinitive Ohms.
	Crank Relay output of the easY-	Measure the resistance between	If engine is not started, the re-
	gen-300 is defective or miswired.	terminals 14 and 11 on the easY-	sistance between terminals 14
	5	gen-300.	and 11 must be around infini-
		8	tive Ohms.
			If the easygen-300 performs
			an start, the resistance between
			terminals 14 and 11 must be
			around 0 Ohms
	Pickup Sensor is miswired to the	Check whether the Pickup sensor	The easygen-300 requires 2
	easYgen_300	is properly wired to terminals	Vac for the MPU during
	cus i gell-500.	$37(GND)$ and $38(\pm)$ on the easy	cranking cycle. If this voltage
		37(010) and $38(+)$ on the east -	is not achieved perhaps the
		gen-500.	is not achieved perhaps the
			the gear is too much
	Demonstern en als entent en 11	The events extend on a dama (1, 1)	Magazza angla angla 1
	Parameter crank cutout speed is	The crank cutout speed must be be-	Measure engine speed when
	set too low	tween the cranking speed and the	cranking engines, before igni-
		normal operating speed of the en-	tion.
		gine	
Starter is not engaged.	Starting relay output of the ea-	Measure the resistance between	It engine is not running, the
	sYgen-300 is defective or mis-	terminals 14 and 11 on the easY-	resistance between terminals
	wired.	gen-300.	14 and 11 should read infinite
			Ohms.
			If the easYgen-300 performs a
			start, the resistance between
			terminals 14 and 11 must be
			around 0 Ohms.

Symptom	Possible cause	Possible solution	Verify
Alarm "21A - Underspeed" occurs, after engine has fired.	Pickup Sensor is miswired to the easYgen-300.	Check whether the pickup sensor is properly wired to terminals 37 (GND) and 38(+) on the easYgen- 300.	The easYgen-300 requires 2 Vac for the MPU during cranking cycle. If this voltage is not achieved perhaps the gap between the pickup and the gear is too much.
	Pickup Sensor is defective.	Check the pickup sensor for proper functionality.	The easYgen-300 requires 2 Vac for the MPU during cranking cycle. If this voltage is not achieved perhaps the gap between the pickup and the gear is too much.
	Engine has stalled.	Check to see if engine fuel level is too low or fuel line is blocked or lost prime. Possible problem with engine air flow.	Troubleshoot engine fuel and air supply. Check air and fuel filters.
Alarm "13A - Generator un- dervoltage" occurs, after the engine has fired.	Generator voltages are not prop- erly connected to the easYgen- 300.	Check generator voltages if engine is started up.	Measure the generator voltag- es on the terminals 29 / 31 / 33 / 35 while the engine is run- ning. (Please refer to the wir- ing diagram for your easYgen- 300 derivate, because the ter- minal assignment is different from derivate to derivate.)
	Wrong wiring selected for the generator voltage measurement.	Use the LeoPC1 configuration software to check for settings of parameter "Generator voltage mea- suring"	Check, which wiring you have to use, and then set the para- meter "Generator voltage mea- suring" via LeoPC1 to one of the following selections : - 1Ph2W - 1Ph3W - 3Ph3W - 3Ph3W - 3Ph4W Note: These wirings are only selectable in the easYgen- 300/X units! See "Chapter 6 - Connections - Voltage measurement Gene- rator" for further details.
	Voltage regulator is not set cor- rectly	Adjust voltage regulator rated vol- tage or remote voltage setting.	

Symptom	Possible cause	Possible solution	Verify
CAN / J1939 Communication does not work.	The parameter for enabling the J1939 Communication is confi- gured "Off" in the easYgen-300.	Check for setting of Parameter 90 "J1939 Device Type" in the confi- guration menu of the easYgen-300.	Parameter 90 "J1939 Device Type" must be set to a value greater than "1" to enable a J1939 / CAN communication. Refer to "Chapter 7 - Opera- tion and Navigation - Configu- ration Displays" and "Parame- ters – Interfaces" for further information.
	Baud rate for CAN communica- tion is set to a incorrect value.	Check that the correct baud rate is entered	The baud rate has to be the same for all devices connected to the CAN bus.
	Termination resistors are not cor- rect.	Check whether the termination re- sistors are of the correct resistive value.	Refer to chapter "Connections - Interfaces" for further infor- mation on termination resis- tors.
	CAN connection is miswired.	Check whether the correct CAN lines are connected to terminals 39 (CAN-L) and 40 (CAN-H).	Refer to chapter "Connections - Interfaces" for further infor- mation on termination resis- tors.
	Wrong setting of parameter "Re- quest send address".	Check whether you have selected the correct request send address.	Refer to chapter "Configura- tion Displays" and "Parame- ters – Interfaces" for further information.
	Wrong setting of parameter "Re- ceive Device Number".	Check whether you have selected the correct receive device number.	Refer to chapter "Configura- tion Displays" and "Parame- ters – Interfaces" for further information.
Engine overspeeds on startup.	Engine governor is not set cor- rectly.	Adjust governor settings for proper response.	Refer to governor manual.
	The Parameter for overspeed level is not set correctly.	Set the correct speed for over- speed.	
	The Parameter for Number of Pickup Teeth is not correct.	Check that this setting is correct for the engine.	Refer to engine specification.
Alarm 12 "Overvoltage" oc- curs on startup.	Voltage regulator is not set cor- rectly	Adjust voltage regulator settings for proper response.	Refer to AVR manual.
Alarm "51A - Charge failure" occurs after the engine has fired, and the "Engine moni- toring delay time" has ex- pired.	Charge alternator is miswired to the easYgen-300.	If charge alternator with 24 Volts Volts are used, connect it to ter- minals 1 (-) and 3 (+). If charge alternator with 12 Volts are used, connect it to terminals 1 (-) and 4 (+).	Please Refer to "Chapter 8 - Functional Description of the Charging Alternator In- put/Output" for further infor- mation.
	Charge alternator polarity re- versed.	With charge alternator connected to terminals 1 (-) and 3 (+) [for 24 Volt charge alternators] or 1 (-) and 4 (+) [for 12 Volt charge alter- nators] of the easYgen-300, meas- ure the voltage at these terminals.	Voltage measurement reads (+) polarity when meter is connected to terminal 1 (-), and 3 (+) or 1 (-) and 4 (+). Please Refer to "Chapter 8 - Functional Description of the Charging Alternator In-
	Charge alternator defective.	Check charge alternator output.	put/Output for further infor- mation. Ensure charge alternator out- put is within specifications

# Appendix E. List of Parameters

Unit nu	umber	P/N	R(	ev		
Versio	n	easYgen-				
During		eus i gen				
Project						
Serial 1	number	S/N	Date			
	Pa	rameter	Setting range	Default value	Custome	er setting
PASS	WORD					
	HMI Password		0000 to 9999	random		
MEAS	SURING					
	Rated system	frequency	50/60 Hz	50 Hz		
	Rated voltage	generator	50 to 480 V	400 V		
[350] [350X]	Rated voltage	mains	50 to 480 V	400 V		
[3x0X]	Generator vol	tage measuring	3Ph 4W 3Ph 3W 1Ph 2W 1Ph 3W	3Ph 4W	□ 3Ph 4W □ 3Ph 3W □ 1Ph 2W □ 1Ph 3W	□ 3Ph 4W □ 3Ph 3W □ 1Ph 2W □ 1Ph 3W
[320]	Generator vol	tage measuring	1Ph 2W	1Ph 2W	n/a	n/a
[350X]	Mains voltage Mains voltage	measuring	3Ph 4W 3Ph 3W 1Ph 2W 1Ph 3W 3Ph 4W	3Ph 4W	$\square 3Ph 4W$ $\square 3Ph 3W$ $\square 1Ph 2W$ $\square 1Ph 3W$	□ 3Ph 4W □ 3Ph 3W □ 1Ph 2W □ 1Ph 3W n/a
APPL	ICATION					
	Ignore CB rep	Ly Dolou Timo	YES/NO	NO		
[350]	2nd MCB Close	Delay Time	0.00 to 650.00 s	0.20 s		
[350X]			0.00 10 020.00 5	0.20 5		
ENGI	NE					
	Engine type:	Diesel				
	Fuel relay		open to stop / close to stop	open to stop	□ open □ close	□ open □ close
[320] [320X]	Preglow time		0 to 300 s	0 s		
[350] [350X]	Preglow time		0 to 300 s	3 s		
	MPU (pickup)					
[3x0X]	Speed Pickup		ON/OFF	ON	$\Box 1 \Box 0$	
[3x0X]	Nominal speed		500 to 4,000 RPM	1,500 RPM		
[3x0X]	Number of gea	r teeth	5 to 260	118		
	Start/stop au	tomatic	1	0		1
	Starter time	ima	1 to 10 s	8 8	_	
	Cool down tim	۲ <sup>111</sup>	10 to 99 s	10.8		
	Time of motor	ston	0 to 999 s	30 s		
	Crank termina	tion by DI1	YES/NO	NO	ΠΥΠΝ	ΠΥΠΝ
	Engine Monit.	delay time	0 to 99 s	8 s		
r				* *		L
BREA	KER					1
[350] [350X]	Transfer time	GCBMCB	0.10 to 99.99 s	0.10 s		

	Parameter	Setting range	Default value	Custome	er setting
EMER	RGENCY POWER (AMF)				
[350] [350X]	On/Off	ON/OFF	ON		
[350] [350X]	Mains fail delay time	0.20 to 99.99 s	3.00 s		
[350] [350X]	Mains settling time	0 to 9,999 s	20 s		
MONI	TORING				
	Time until horn reset	0 to 1,000 s	180 s		
	Generator protection				
	Voltage monitoring generator	4 phase	4 phase	n/a	n/a
	Generator: Over frequency	ON	ON		
	Limit	50.0 to 130.0 %	110.0 %	n/a	n/a
	Delay	0.1 to 99.9 s	10.0 %		
	Alarm class	F	F	n/a	n/a
	Self acknowledge	NO	NO	n/a	n/a
	Generator: Under frequency				
	Monitoring	ON	ON	n/a	n/a
	Limit	50.0 to 130.0 %	90.0 %		
	Delay	0.1 to 99.9 s	5.0 s		
	Self acknowledge	F NO	F	n/a n/a	n/a n/a
	Delayed by engine speed	YES	YES	n/a	n/a
	Generator: Over voltage	125	125	ii/u	ii/u
	Monitoring	ON	ON	n/a	n/a
	Limit	50.0 to 125.0 %	110.0 %		
	Delay	0.1 to 99.9 s	2.0 s		
	Alarm class	F	F	n/a	n/a
	Self acknowledge	NO	NO	n/a	n/a
	Delayed by engine speed	NO	NO	n/a	n/a
	Generator: Under voltage	ON	01	,	,
	Monitoring	50.0 to 125.0 %	02.0.%	n/a	n/a
	Delay	0.1 to 99.9 s	92.0 %		
	Alarm class	F	F	n/a	n/a
	Self acknowledge	NO	NO	n/a	n/a
	Delayed by engine speed	YES	YES	n/a	n/a
	Mains protection			-	
[350] [350X]	Monitoring	ON / OFF	ON		
[350] [350X]	Mains phase rotation	CW (+)/CCW (-)	CW	□ + □ -	□ + □ -
[350] [350X]	Delay	2 s	2 s	n/a	n/a
[350] [350X]	Alarm class	В	В	n/a	n/a
[350] [350X]	Self acknowledge	YES / NO	NO		
[350] [350X]	Delayed by engine speed	NO	NO	n/a	n/a
[250]	Emergency power: Limits				1
[350] [350X]	High voltage threshold	50.0 to 130.0 %	130.0 %		
[350] [350X]	Low voltage threshold	50.0 to 130.0 %	90.0 %		
[350] [350X]	Voltage hysteresis	0.0 to 50.0 %	2.0 %		
[350] [350X]	High frequency threshold	70.0 to 160.0 %	110.0 %		
[350] [350X]	Low frequency threshold	70.0 to 160.0 %	90.0 %		
[350]	Frequency hysteresis	0.0 to 50.0 %	2.0 %		

	Parameter	Setting range	Default value	Custome	er setting
MON	TORING				
	Engine: Overspeed				
[3x0X]	Monitoring	ON/OFF	ON	$\Box 1 \Box 0$	$\Box 1 \Box 0$
[3x0X]	Limit	0 to 9 999 RPM	1 850 RPM		0100
[3x0X]	Delay	0.1 s	0.1 s	n/a	n/a
[3x0X]	Alarm class	F	F	n/a	n/a
[3x0X]	Self acknowledge	NO	NO	n/a	n/a
[3x0X]	Delayed by engine speed	NO	NO	n/a	n/a
	Engine: Underspeed		110		1.7 tt
[3x0X]	Monitoring	ON	ON	n/a	n/a
[3x0X]	Limit	1 000 RPM	1.000 RPM	n/a	n/a
[3x0X]	Delay	1.0 s	1.0.5	n/a	n/a
[3x0X]	Alarm class	F	F	n/a	n/a
[3x0X]	Self acknowledge	NO	NO	n/a	n/a
[3x0X]	Delayed by engine speed	YES	YES	n/a	n/a
	Engine: Start fail				
	Monitoring	ON	ON	p/a	n/a
	Number of start attempts	3	3	n/a	n/a
	Alarm class	F	F	n/a	n/a
	Self acknowledge	NO	NO	n/a	n/a
	Engine: Unintended stop	_			
	Monitoring	ON	ON	n/a	n/a
	Alarm class	F	F	n/a	n/a
	Battery: Undervoltage	-	*	in a	ii) u
	Monitoring	ON	ON	n/a	n/a
	Limit	8 0 to 42 0 V	10.0 V	11/ a	11/ a
	Delay	60.0 s	60.0 s	n/a	n/a
	Alarm class	B	B	n/a	n/a
	Self acknowledge	NO	NO	n/a	n/a
	Delayed by engine speed	NO	NO	n/a	n/a
	Battery: charge voltage			1	1
	Monitoring	ON/OFF	ON		
	Limit	0.0 to 32.0 V	16.0 V		
	Delay	10.0 s	10.0 s	n/a	n/a
	Alarm class	В	В	n/a	n/a
	Self acknowledge	NO	NO	n/a	n/a
	Delayed by engine speed	YES	YES	n/a	n/a
	Interface: J1939				
[3x0X]	Monitoring	ON/OFF	OFF		
[3x0X]	Delay	0.1 to 650.0 s	20.0 s		
[3x0X]	Alarm class	B/F	В		
[3x0X]	Self acknowledge	YES/NO	NO		$\Box Y \Box N$
[3x0X]	Delayed by engine speed	YES/NO	NO		$\Box Y \Box N$
	Interface: J1939: amber warning	g lamp DM1			
[3x0X]	Monitoring	ON/OFF	OFF		
[3x0X]	Delay	0.1 to 999.0 s	2.0 s		
[3x0X]	Alarm class	B/F	В		
[3x0X]	Self acknowledge	YES/NO	YES	<b>ΔΥΝ</b>	
[3x0X]	Delayed by engine speed	YES/NO	NO	$\Box Y \Box N$	$\Box Y \Box N$
	Interface: J1939: red stop lam	p DM1			
[3x0X]	Monitoring	ON/OFF	OFF		
[3x0X]	Delay	0.1 to 999.0 s	2.0 s		
[3x0X]	Alarm class	B/F	В		
[3x0X]	Self acknowledge	YES/NO	YES	<b>Δ</b> Υ <b>Δ</b> Ν	<b>ΠΥΠΝ</b>
[3x0X]	Delayed by engine speed	YES/NO	NO	$\Box Y \Box N$	

	Parameter	Setting range	Default value	Custome	er setting	
DIGGI						
DISCH	RETE INPUTS					
	Discrete input [DI1] oil press	ure				
	DI 1 operation	N.O.	N.O.	n/a	n/a	
	DI 1 delay	0.5 s	0.5 s	n/a	n/a	
	DI 1 alarm class	F	F	n/a	n/a	
	DI 1 delayed by eng. speed	YES	YES	n/a	n/a	
	DI 1 self acknowledge	NO	NO	n/a	n/a	
	Discrete input [DI2] coolant t	emperature	-	-	-	
	DI 2 operation	N.O.	N.O.	n/a	n/a	
	DI 2 delay	1.0 s	1.0 s	n/a	n/a	
	DI 2 alarm class	F	F	n/a	n/a	
	DI 2 delayed by eng. speed	YES	YES	n/a	n/a	
	DI 2 self acknowledge	NO	NO	n/a	n/a	
	Discrete input [DI3] remote start					
	DI 3 operation	N.O.	N.O.	n/a	n/a	
	DI 3 delay	0.02 s	0.02 s	n/a	n/a	
	DI 3 alarm class	Control	Control	n/a	n/a	
	DI 3 delayed by eng. speed	NO	NO	n/a	n/a	
	DI 3 self acknowledge	NO	NO	n/a	n/a	
	Discrete input [DI4] reply MCB	or freely configurable				
	If parameter "Ignore CB reply"	is set to "YES", this i	nput is freely	configural	ble	
	DI 4 operation	N.O. / N.C.	N.C.	□ N.O. □ N.C.	$\square$ N.O. $\square$ N.C.	
	DI 4 delay	0.02 to 650.00 s	0.00 s			
	DI 4 alarm class	A/B/C/D/E/F/Control	Control			
	DI 4 delayed by eng. speed	YES/NO	NO			
	DI 4 self acknowledge	YES/NO	YES			
	Discrete input [DI5] reply GCB	or freely configurable	1	1		
	If parameter "Ignore CB reply"	is set to "YES", this i	nput is freely	configural	ble	
	DI 5 operation		NC	□ N.O.	□ N.O.	
		N.O. / N.C.	N.C.	□ N.C.	□ N.C.	
	DI 5 delay	0.02 to 650.00 s	0.00 s			
	DI 5 alarm class	A/B/C/D/E/F/Control	Control			
	DI 5 delayed by eng. speed	YES/NO	NO	<b>ΔΥ</b> ΔΝ	<b>Δ</b> Υ <b>Δ</b> Ν	
	DI 5 self acknowledge	YES/NO	YES	<b>ΔΥ</b> ΔΝ	<b>Δ</b> Υ <b>Δ</b> Ν	
DIGIT	DIGITAL OUTPUTS					

[350] [350X]	Relay 1	Command: open MCB	open MCB	n/a	n/a
	Relay 2	Command: close GCB	close GCB	n/a	n/a
[350] [350X]	Relay 3	one from configurable parameter list (see end of table)	Preglow		
	Relay 4	one from configurable parameter list (see end of table)	stopping alarm		
	Relay 5	Fuel relay	Fuel relay	n/a	n/a
	Relay 6	Starter	Starter	n/a	n/a
	Relay 7	internal relay			

#### COUNTER

001	UTTER					
	Maintenance hours	0 to 9,999 h	300 h			
	Reset maintenance period h	YES/NO	NO	$\Box Y \Box N$	$\Box Y \Box N$	
	Counter value preset	0 to 99,999.9 h	-			
	Set operation hours	YES/NO	NO	$\Box Y \Box N$	$\Box Y \Box N$	
	Number of starts	0 to 65,535	-			

### COMM. INTERFACES

[3x0X]	CAN Interfaces					
	Baudrate	20/50/100/125/250/ 500/800/1000 kBd	125 kBd			
	J1939					
[3x0X]	Device type	Off/Standard/S6 Scania/EMR	Standard			
[3x0X]	Request send address	0 to 255	3			
[3x0X]	Receive device number	0 to 255	0			

	Parameter	Setting range	Default value	Custome	er setting
SYSTE	М				
	Codes				
Ċ	Comissioning level code	0000 to 9999	0003		
E	Factory settings	ON / OFF	OFF		
C	Clear event log	ON / OFF	OFF		
S	Set default values	ON / OFF	OFF		
I	Display level	1 to 3	1		
		1000	•		
E	Flag 1 gen. overfreg. 1	YES/NO	NO	ΠΥΠΝ	ΠΥΠΝ
E	Flag 1 gen. underfreg. 1	YES/NO	NO		
I	Flag 1 gen. overvolt. 1	YES/NO	NO		
E	Flag 1 gen. undervolt. 1	YES/NO	NO	ΠΥΠΝ	ΠΥΠΝ
I	Flag 1 mains rot. field alarm	YES/NO	NO		
E	Flag 1 overspeed 1	YES/NO	NO	ΠΥΠΝ	ΠΥΠΝ
E	Flag 1 underspeed 1	YES/NO	NO		
E	Flag 1 unintended stop	YES/NO	NO		
E	Flag 1 start fail	YES/NO	YES	ΠΥΠΝ	ΠΥΠΝ
E	Flag 1 maintenance hours exc.	YES/NO	NO	ΠΥΠΝ	
E	Flag 1 J1939 CAN Error	YES/NO	NO	ΠΥΠΝ	ΠΥΠΝ
E	Flag 1 Red stop lamp	YES/NO	NO		
I	Flag 1 Amber warning lamp	YES/NO	NO		
E	Flag 1 undervolt. aux. alt.	YES/NO	NO		
E	Flag 1 undervolt. batt. 1	YES/NO	NO	ΠΥΠΝ	
E	Flag 1 DI 1	YES/NO	NO	ΠΥΠΝ	ΠΥΠΝ
E	Flag 1 DI 2	YES/NO	NO	ΠΥΠΝ	
I	Flag 1 DI 3	YES/NO	NO		
E	Flag 1 DI 4	YES/NO	NO		
I	Flag 1 DI 5	YES/NO	NO		
	-				
E	Flag 2 gen. overfreg. 1	YES/NO	NO	<b>ΠΥΠΝ</b>	<b>ΠΥΠΝ</b>
F	Flag 2 gen. underfreq. 1	YES/NO	NO		
E	Flag 2 gen. overvolt. 1	YES/NO	YES	<b>ΠΥΠΝ</b>	<b>ΠΥΠΝ</b>
F	Flag 2 gen. undervolt. 1	YES/NO	YES		
F	Flag 2 mains rot. field alarm	YES/NO	NO		
E	Flag 2 overspeed 1	YES/NO	NO		
E	Flag 2 underspeed 1	YES/NO	NO		<b>ΔΥΔ</b> Ν
E	Flag 2 unintended stop	YES/NO	NO	<b>Δ</b> Υ <b>Δ</b> Ν	<b>ΠΥΠΝ</b>
E	Flag 2 start fail	YES/NO	NO		$\Box Y \Box N$
E	Flag 2 maintenance hours exc.	YES/NO	NO		
E	Flag 2 J1939 CAN Error	YES/NO	NO		$\Box Y \Box N$
E	Flag 2 Red stop lamp	YES/NO	NO		
E	Flag 2 Amber warning lamp	YES/NO	NO	<b>Δ</b> Υ <b>Δ</b> Ν	$\Box Y \Box N$
E	Flag 2 undervolt. aux. alt.	YES/NO	NO		$\Box Y \Box N$
E	Flag 2 undervolt. batt. 1	YES/NO	NO	<b>Δ</b> Υ <b>Δ</b> Ν	<b>ΔΥ</b> ΔΝ
E	Flag 2 DI 1	YES/NO	NO		
E	Flag 2 DI 2	YES/NO	NO		
E	Flag 2 DI 3	YES/NO	NO	<b>Δ</b> Υ <b>Δ</b> Ν	<b>ΔΥ</b> ΔΝ
E	Flag 2 DI 4	YES/NO	NO		
E	Flag 2 DI 5	YES/NO	NO	ΠΥΠΝ	ΠΥΠΝ

	Parameter	Setting range	Default value	Customer	setting
SVSTI	ZM .				
51511	Flag 3 gen overfreg 1	VES/NO	VES	ΠΥΠΝ	
	Flag 3 gen underfreg 1	VES/NO	VES		
	Flag 3 gen overvolt 1	VES/NO	NO		
	Flag 3 gen, underwolt 1	VES/NO	NO		
	Flag 3 maing rot field alarm	I ES/NO VES/NO	NO		
	Flag 2 overgreed 1	I ES/NO VES/NO	NO		
	Flag 3 overspeed 1	YES/NO	NO		
	Flag 3 underspeed 1	YES/NO	NO		
	Flag 3 unintended stop	YES/NO	NO		
	Flag 3 start fail	YES/NO	NO		
	Flag 3 maintenance hours exc.	YES/NO	NO		
	Flag 3 J1939 CAN Error	YES/NO	NO	$\Box Y \Box N$	$\Box Y \Box N$
	Flag 3 Red stop lamp	YES/NO	NO	$\Box Y \Box N$	$\Box Y \Box N$
	Flag 3 Amber warning lamp	YES/NO	NO	$\Box Y \Box N$	$\Box Y \Box N$
	Flag 3 undervolt. aux. alt.	YES/NO	NO	$\Box Y \Box N$	$\Box Y \Box N$
	Flag 3 undervolt. batt. 1	YES/NO	NO	$\Box Y \Box N$	<b>Δ</b> Υ <b>Δ</b> Ν
	Flag 3 DI 1	YES/NO	NO	$\Box Y \Box N$	<b>Δ</b> Υ <b>Δ</b> Ν
	Flag 3 DI 2	YES/NO	NO	$\Box Y \Box N$	<b>Δ</b> Υ <b>Δ</b> Ν
	Flag 3 DI 3	YES/NO	NO	$\Box Y \Box N$	<b>Δ</b> Υ <b>Δ</b> Ν
	Flag 3 DI 4	YES/NO	NO	$\Box Y \Box N$	<b>ΔΥ</b> ΔΝ
	Flag 3 DI 5	YES/NO	NO		<b>ΔΥ</b> ΔΝ
	Flag 4 gen. overfreg. 1	YES/NO	NO	<b>ΠΥΠΝ</b>	<b>ΠΥΠΝ</b>
	Flag 4 gen. underfreg. 1	YES/NO	NO	<b>ΠΥΠΝ</b>	
	Flag 4 gen. overvolt. 1	YES/NO	NO	ΠΥΠΝ	
	Flag 4 gen. undervolt. 1	YES/NO	NO		
	Flag 4 mains rot, field alarm	YES/NO	NO		
	Flag 4 overspeed 1	VFS/NO	NO		
	Flag 4 underspeed 1	VFS/NO	NO		
	Flag 4 unintended stop	VES/NO	NO		
	Flag 4 start fail	VES/NO	NO		
	Flag 4 maintenance hours eva	VES/NO	VES		
	Flag 4 Haincenance nours exc.	IES/NO VES/NO	I ES		
	Flag 4 Dod stop lown	I ES/NO	NO		
	Flag 4 Amban warning lamp	I ES/NO	NO		
	Flag 4 Amber warning lamp	I ES/NO	NO		
	Flag 4 undervolt. aux. alt.	YES/NO	NO		
	Flag 4 undervolt. batt. 1	YES/NO	NO		
		YES/NO	NO		
	Flag 4 DI 2	YES/NO	NO		
	Flag 4 DI 3	YES/NO	NO		
	Flag 4 DI 4	YES/NO	NO		
	Flag 4 DI 5	YES/NO	NO	$\Box Y \Box N$	$\Box Y \Box N$
	Versions				
	Serial number	Info			
	Boot item number	Info			
	Boot revision	Info			
	Boot version	Info			
	Program item number	Info			
	Program revision	Info			
	Program version	Info			

[3x0X] applies only to easYgen-320X and 350X

[350] applies only to easYgen-350

[350X] applies only to easYgen-350X

The output signals, which may be selected from the list of configurable parameters for the discrete outputs 3 and 4, are listed in Table 10-1 on page 93.



### NOTE

All parameters shaded in gray color are fixed parameters and cannot be configured by the operator. The "light gray" parameters for DI4 and DI 5 can be configured if the parameter "Ignore CB reply" is set to "YES".

## Appendix F. Service Options

### **Product Service Options**

The following factory options are available for servicing Woodward equipment, based on the standard Woodward Product and Service Warranty (5-01-1205) that is in effect at the time the product is purchased from Woodward or the service is performed. If you are experiencing problems with installation or unsatisfactory performance of an installed system, the following options are available:

- Consult the troubleshooting guide in the manual.
- Contact Woodward technical assistance (see "How to Contact Woodward" later in this chapter) and discuss your problem. In most cases, your problem can be resolved over the phone. If not, you can select which course of action you wish to pursue based on the available services listed in this section.

## **Returning Equipment For Repair**

If a control (or any part of an electronic control) is to be returned to Woodward for repair, please contact Woodward in advance to obtain a Return Authorization Number. When shipping the unit(s), attach a tag with the following information:

- name and location where the control is installed;
- name and phone number of contact person;
- complete Woodward part numbers (P/N) and serial number (S/N);
- description of the problem;
- instructions describing the desired repair.



### CAUTION

To prevent damage to electronic components caused by improper handling, read and observe the precautions in Woodward manual 82715, *Guide for Handling and Protection of Electronic Controls, Printed Circuit Boards, and Modules.* 

### **Packing a Control**

Use the following materials when returning a complete control:

- protective caps on any connectors
- antistatic protective bags on all electronic modules
- packing materials that will not damage the surface of the unit
- at least 100 mm (4 inches) of tightly packed, industry-approved packing material
- a packing carton with double walls
- a strong tape around the outside of the carton for increased strength

### **Return Authorization Number RAN**

When returning equipment to Woodward, please telephone and ask for the Customer Service Department in Stuttgart [+49 (0) 711 789 54-0]. They will help expedite the processing of your order through our distributors or local service facility. To expedite the repair process, contact Woodward in advance to obtain a Return Authorization Number, and arrange for issue of a purchase order for the unit(s) to be repaired. No work can be started until a purchase order is received.

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### NOTE

We highly recommend that you make arrangement in advance for return shipments. Contact a Woodward customer service representative at +49 (0) 711 789 54-0 for instructions and for a Return Authorization Number.

## **Replacement Parts**

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When ordering replacement parts for controls, include the following information:

- the part numbers P/N (XXXX-XXX) that is on the enclosure nameplate
- the unit serial number S/N, which is also on the nameplate

### How To Contact Woodward

#### 

Please contact following address if you have questions or if you want to send a product for repair:

Woodward GmbH Handwerkstrasse 29 70565 Stuttgart - Germany

Phone:	+49 (0) 711 789 54-0	(8:00 - 16:30 German time)
Fax:	+49 (0) 711 789 54-100	
email:	stgt-info@woodward.com	

For assistance outside Germany, call one of the following international Woodward facilities to obtain the address and phone number of the facility nearest your location where you will be able to get information and service.

Facility	Phone number
USĂ	+1 (970) 482 5811
India	+91 (129) 409 7100
Brazil	+55 (19) 3708 4800
Japan	+81 (476) 93 4661
The Netherlands	+31 (23) 566 1111

You can also contact the Woodward Customer Service Department or consult our worldwide directory on Woodward's website (**www.woodward.com**) for the name of your nearest Woodward distributor or service facility. [For worldwide directory information, go to **www.woodward.com/ic/locations**.]

## **Engineering Services**

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Woodward Industrial Controls Engineering Services offers the following after-sales support for Woodward products. For these services, you can contact us by telephone, by e-mail, or through the Woodward website.

- Technical support
- Product training
- Field service during commissioning

**Technical Support** is available through our many worldwide locations, through our authorized distributors, or through GE Global Controls Services, depending on the product. This service can assist you with technical questions or problem solving during normal business hours. Emergency assistance is also available during non-business hours by phoning our toll-free number and stating the urgency of your problem. For technical engineering support, please contact us via our toll-free or local phone numbers, e-mail us, or use our website and reference technical support.

**Product Training** is available on-site from several of our worldwide facilities, at your location, or from GE Global Controls Services, depending on the product. This training, conducted by experienced personnel, will assure that you will be able to maintain system reliability and availability. For information concerning training, please contact us via our toll-free or local phone numbers, e-mail us, or use our website and reference *customer training*.

**Field Service** engineering on-site support is available, depending on the product and location, from our facility in Colorado, or from one of many worldwide Woodward offices or authorized distributors. Field engineers are experienced on both Woodward products as well as on much of the non-Woodward equipment with which our products interface. For field service engineering assistance, please contact us via our toll-free or local phone numbers, e-mail us, or use our website and reference *field service*.

## **Technical Assistance**

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If you need to telephone for technical assistance, you will need to provide the following information. Please write it down here before phoning:

Contact		
Your company		
Your name		
Phone number		
Fax number		
Control (see name plat	e)	
Unit no. and revision:	P/N:	REV:
Unit type	easYgen	
Serial number	S/N	
Description of your pro	oblem	

Please be sure you have a list of all parameters available. You can print this using LeoPC1. Additionally you can save the complete set of parameters (standard values) and send them to our Service department via e-mail.

We appreciate your comments about the content of our publications. Please send comments to: <u>stgt-documentation@woodward.com</u> Please include the manual number from the front cover of this publication.



#### Woodward GmbH

Handwerkstrasse 29 - 70565 Stuttgart - Germany Phone +49 (0) 711 789 54-0 • Fax +49 (0) 711 789 54-100 stgt-info@woodward.com

#### Homepage

http://www.woodward.com/power

Woodward has company-owned plants, subsidiaries, and branches, as well as authorized distributors and other authorized service and sales facilities throughout the world.

Complete address/phone/fax/e-mail information for all locations is available on our website (www.woodward.com).

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